# Sesquilinear Functional and Jordan Derivation in Involutive Banach Algebras with Application to Tensor Product and Hyers-Ulam Stability 

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#### Abstract

In this paper, we extend Vukman's generalization of Kurepa's theorem on sesquilinear functional to the projective tensor product of two hermitian Banach *-algebras via sesquilinear functional. For a complex unital ${ }^{*}$-algebra $\mathbb{A}$ and two additive self mappings $\theta$ and $\phi$ as antihomomorphism and homomorphism respectively on $\mathbb{A}$, we define a generalized class of quadratic functional, viz., $(\theta, \phi)$ - $\mathbb{A}$-quadratic functional. Using this, we give a characterization of sesquilinear functional on the projective tensor product in terms of Jordan $(\theta, \phi)$ derivation. The Hyers-Ulam stability of Jordan $(\theta, \phi)$-derivation is also discussed.


Index Terms-Projective tensor product, quadratic functional, sesquilinear functional, Jordan derivation.

## I. Introduction

THE study of sesquilinear functionals has attained significant interest from numerous researchers due to its broad applicability across various domains. For a complex vector space $X$ and a complex ${ }^{*}$-algebra $\mathbb{A}$ with $X$ as a left $\mathbb{A}$-module, it is well known that each $\mathbb{A}$-sesquilinear functional

$$
B: X \times X \rightarrow \mathbb{A}
$$

gives rise to an $\mathbb{A}$-quadratic functional

$$
Q: X \rightarrow \mathbb{A}
$$

by the relation $Q(x)=B(x, x)$ for all $x \in X$. Kurepa [15] provided a positive response to the converse of this statement when examining the case of $\mathbb{A}$ being the field of complex numbers. In [28], Vroba obtained a simpler proof of Kurepa's result. In 1984, Vukman in [26] achieved a broader formulation of Kupera's theorem by replacing the complex field $\mathbb{C}$ with commutative hermitian Banach *-algebra. The generalization for noncommutative case was also done by Vukman in another paper [27] using a simpler approach.

Building upon the influence of these studies, in this paper we establish some results on sesquilinear functionals in Banach *-algebras. The novelty of our work lies in the fact that some existing works have been extended in the setting of projective tensor product of two hermitian Banach *algebras. Furthermore, we have generalized the investigation conducted by Semrl [24] concerning Jordan *-derivation on the Banach ${ }^{*}$-algebra $\mathbb{A}$ to Jordan $(\theta, \phi)$-derivation. Jordan derivation was introduced by Herstein [13] in 1957, and he

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proved some results of Jordan derivation on prime rings. Subsequently, Semrl [24] demonstrated a series of findings pertaining to Jordan ${ }^{*}$-derivations, as well as exploring sesquilinear and quadratic functionals. In [1], Ashraf et al. discussed about Lie ideals and generalized Jordan $(\theta, \phi)$ derivations in prime rings. Different researchers (refer to [2], [8], [16], [19]) have established several interesting results considering different types of Jordan derivations which is the motivation to work in this topic.

## II. Preliminaries

In this section, we present some basic definitions necessary for the main results of the paper.

Definition 2.1 [5] In an algebra $\mathbb{A}$, for $x, x^{*} \in \mathbb{A}$, an involution is a self mapping on $\mathbb{A}$ with $x \rightarrow x^{*}$ such that
(i) $(x+y)^{*}=x^{*}+y^{*}$,
(ii) $\left(x^{*}\right)^{*}=x$,
(iii) $(x y)^{*}=y^{*} x^{*}$,
(iv) $\left(\alpha x^{*}\right)=\bar{\alpha} x^{*}$
for all $x, y \in \mathbb{A}$ and for all scalar $\alpha$, where $x^{*}$ is called the adjoint of $x$.

An algebra $\mathbb{A}$ with an involution is called a $*$-algebra. A Banach *-algebra is a Banach algebra $\mathbb{A}$ with an involution '*' defined on it. Let $\mathbb{A}$ be the algebra $M_{n}(\mathbb{C})$ of all $n \times n$ complex matrices and let $a=\left(a_{i j}\right) \in \mathbb{A}$. Then $\mathbb{A}$ is a Banach *-algebra, where $a^{*}=\left(\overline{a_{j i}}\right)$.

If each hermitian element in a Banach $*$-algebra $\mathbb{A}$ has a real spectrum, then $\mathbb{A}$ is called a hermitian algebra. $\mathbb{B}^{*}$ algebras are the most important hermitian Banach *-algebras. In a Banach *-algebra $\mathbb{A}$, for any hermitian element $h \in \mathbb{A}$, $h>0(h \geq 0)$, if the spectrum of $h$ is positive (nonnegative).

Definition 2.2 [24] Let $X$ be a complex vector space and $\mathbb{A}$ be a complex ${ }^{*}$-algebra such that $X$ is a left A-module.
A mapping

$$
B: X \times X \rightarrow \mathbb{A}
$$

is an $\mathbb{A}$-sesquilinear functional if
(i) $B\left(a_{1} x_{1}+a_{2} x_{2}, y\right)=a_{1} B\left(x_{1}, y\right)+a_{2} B\left(x_{2}, y\right)$ for all $x_{1}, x_{2}, y \in X ; a_{1}, a_{2} \in \mathbb{A}$,
(ii) $B\left(x, a_{1} y_{1}+a_{2} y_{2}\right)=B\left(x, y_{1}\right) a_{1}^{*}+B\left(x, y_{2}\right) a_{2}^{*}$ for all $x, y_{1}, y_{2} \in X ; a_{1}, a_{2} \in \mathbb{A}$.
For example, let $H$ be a Hilbert space and $\beta(H)$ be the algebra of all bounded linear operators on $H$. Let the involution on $\beta(H)$ be the adjoint operation. The mapping

$$
\phi: H \times H \rightarrow \beta(H)
$$

defined by

$$
(\phi(x, y))(z)=<z, y>x
$$

where $x, y, z \in H$ is a $\beta(H)$-sesquilinear functional.
A mapping $Q: X \rightarrow \mathbb{A}$ is said to be an $\mathbb{A}$-quadratic functional if the following conditions are satisfied:
(i) $Q(x+y)+Q(x-y)=2 Q(x)+2 Q(y)$ for all $x, y \in X$,
(ii) $Q(a x)=a Q(x) a^{*}$ for all $x \in X$ and $a \in \mathbb{A}$.

In [27], Vukman proved the following result regarding sesquilinear functional in hermitian Banach *-algebras.

Lemma 2.3 [27] For a vector space $X$ and a hermitian Banach *-algebra $\mathbb{A}$, let $X$ be a unitary left $\mathbb{A}$-module. Suppose there exists an $\mathbb{A}$-quadratic functional $Q: X \rightarrow \mathbb{A}$. Then the mapping $B: X \times X \rightarrow \mathbb{A}$ defined by
$B(x, y)=\frac{1}{4}(Q(x+y)-Q(x-y))+\frac{i}{4}(Q(x+i y)-Q(x-i y))$ is an $\mathbb{A}$-sesquilinear functional. Moreover, for all $x \in X$ the relation $Q(x)=B(x, x)$ holds.

In the theory of Banach spaces, the tensor product serves as a tool to transform multilinear phenomena into linear ones, simplifying their analysis. In 1953, Grothendiek [10] developed the modern tensor product theory of Banach spaces. Various concepts linked to the tensor product have been explored in [7], [21], [23].

Definition 2.4 [5] Let $\mathbb{A}$ and $\mathbb{B}$ be two normed spaces over the field $\mathbb{F}$ with dual spaces $\mathbb{A}^{*}$ and $\mathbb{B}^{*}$. For $a \in \mathbb{A}$ and $b \in \mathbb{B}$, let $a \otimes b$ be the element of $B L\left(\mathbb{A}^{*}, \mathbb{B}^{*} ; \mathbb{F}\right)$ defined by

$$
a \otimes b(f, g)=f(a) g(b),\left(f \in \mathbb{A}^{*}, g \in \mathbb{B}^{*}\right)
$$

The algebraic tensor product of $\mathbb{A}$ and $\mathbb{B}, \mathbb{A} \otimes \mathbb{B}$ is defined as the linear span of $\{a \otimes b: a \in \mathbb{A}, b \in \mathbb{B}\}$ in $B L\left(\mathbb{A}^{*}, \mathbb{B}^{*} ; \mathbb{F}\right)$, where $B L\left(\mathbb{A}^{*}, \mathbb{B}^{*} ; \mathbb{F}\right)$ is the set of all bounded bilinear mappings from $\mathbb{A}^{*} \times \mathbb{B}^{*}$ to $\mathbb{F}$.
For example, if $\mathbb{A}$ is a Banach $*$-algebra, then $M_{n}(\mathbb{C}) \otimes \mathbb{A}$ is isomorphic to $M_{n}(\mathbb{A})$, which is the set of all $n \times n$ matrices over $\mathbb{A}$ (refer to [5]).

Definition 2.5 [6] For any two normed spaces $\mathbb{A}$ and $\mathbb{B}$, the projective tensor norm $\gamma$ on $\mathbb{A} \otimes \mathbb{B}$ is defined by

$$
\gamma(u)=\inf \left\{\sum_{i=1}^{n}\left\|a_{i}\right\| \cdot\left\|b_{i}\right\|: u=\sum_{i=1}^{n} a_{i} \otimes b_{i}\right\},
$$

where the infimum is taken over all finite representations of $u$. The completion of $\mathbb{A} \otimes \mathbb{B}$ with respect to $\gamma$ is called the projective tensor product of $\mathbb{A}$ and $\mathbb{B}$ and it is denoted by $\mathbb{A} \otimes_{\gamma} \mathbb{B}$.

For example, for the sequence space $l^{1}$ over $\mathbb{R}$, there exists an isometric linear isomorphism of $l^{1} \otimes_{\gamma} \mathbb{R}$ to $l^{1}(\mathbb{R})$.

Lemma 2.6 [5] Let $\mathbb{A}$ and $\mathbb{B}$ be two normed algebras over $\mathbb{F}$. There exists a unique product on $\mathbb{A} \otimes \mathbb{B}$ with respect to which $\mathbb{A} \otimes \mathbb{B}$ is an algebra and

$$
(a \otimes b)(c \otimes d)=a c \otimes b d, \quad(a, c \in \mathbb{A} \text { and } b, d \in \mathbb{B})
$$

If $\mathbb{A}$ and $\mathbb{B}$ are two hermitian Banach $*$-algebras, then $\mathbb{A} \otimes_{\gamma} \mathbb{B}$ is also a hermitian Banach *-algebra.

Definition 2.7 [24] For a *-algebra $\mathbb{A}$, a mapping $D: \mathbb{A} \rightarrow \mathbb{A}$ is a Jordan *-derivation if for all $u, v \in \mathbb{A}$,
(i) $D(u+v)=D(u)+D(v)$,
(ii) $D\left(u^{2}\right)=u D(u)+D(u) u^{*}$.

Definition 2.8 [1] Let $\mathbb{A}$ be a complex unital Banach *-algebra with unit element $e$. For two endomorphisms $\theta$ and $\phi$ on $\mathbb{A}$, a mapping $\Delta: \mathbb{A} \rightarrow \mathbb{A}$ is said to be a Jordan $(\theta, \phi)$-derivation if for all $u, v \in \mathbb{A}$,
(i) $\Delta(u+v)=\Delta(u)+\Delta(v)$,
(ii) $\Delta\left(u^{2}\right)=\Delta(u) \theta(u)+\phi(u) \Delta(u)$.

Example 2.9 For the $C^{*}$-algebra $\mathbb{A}=\left\{\left[\begin{array}{cc}u & v \\ 0 & u\end{array}\right]: u, v \in \mathbb{R}\right\}$ with usual matrix operations and the norm, let $\Delta: \mathbb{A} \rightarrow \mathbb{A}$ be defined by $\Delta\left(\left[\begin{array}{ll}u & v \\ 0 & u\end{array}\right]\right)=\left[\begin{array}{ll}0 & v \\ 0 & 0\end{array}\right]$. Let $\theta: \mathbb{A} \rightarrow \mathbb{A}$ and $\phi: \mathbb{A} \rightarrow \mathbb{A}$ be such that $\theta\left(\left[\begin{array}{ll}u & v \\ 0 & u\end{array}\right]\right)=\left[\begin{array}{ll}u & 0 \\ 0 & u\end{array}\right]=\phi\left(\left[\begin{array}{ll}u & v \\ 0 & u\end{array}\right]\right)$. Then $\Delta$ is a Jordan $(\vec{\theta}, \phi)$-derivation.

Definition 2.10 [12] A Banach $*$-algebra $\mathbb{A}$ is called a zero product determined Banach *-algebra if for every vector space $X$ and every bilinear mapping

$$
\Psi: \mathbb{A} \times \mathbb{A} \rightarrow X
$$

the following condition holds:
if $\Psi(u, v)=0$ whenever $u v=0$, then there exists a linear mapping

$$
T: \mathbb{A}^{2} \rightarrow X
$$

such that $\Psi(u, v)=T(u v)$ for all $u, v \in \mathbb{A}$. [Here $\mathbb{A}^{2}$ denotes the complex linear span of all elements of the form $x y$ where $x, y \in \mathbb{A}]$.

If $\mathbb{A}$ has unit element $e$, and $\mathbb{A}$ is zero product determined Banach *-algebra then $\Psi(u, v)=\Psi(u v, e)$ for all $u, v \in \mathbb{A}$ and also $\Psi(u, e)=\Psi(e, u)$ for all $u \in \mathbb{A}$.

## III. Main Results

We introduce the subsequent expansion of Vukman's findings to projective tensor product of two hermitian Banach *-algebras, $\mathbb{A}$ and $\mathbb{B}$. Starting with two quadratic functionals, $Q_{1}$ and $Q_{2}$ defined on the vector spaces $X$ and $Y$, where $X$ is a left $\mathbb{A}$-module, and $Y$ is a left $\mathbb{B}$-module, we formulate an $\mathbb{A} \otimes_{\gamma} \mathbb{B}$-sesquilinear functional on $X \otimes Y$. Significantly, our work also finds a relationship between the norms of elements in $X \otimes Y$ via quadratic functionals and sesquilinear functionals in case of $C^{*}$-algebras.

Theorem 3.1 Let $X, Y$ be two vector spaces and $\mathbb{A}$, $\mathbb{B}$ be two hermitian Banach ${ }^{*}$-algebras with unit elements $e_{1}$ and $e_{2}$ respectively. Let $X$ be a unitary left $\mathbb{A}$ - module and $Y$ be a unitary left $\mathbb{B}$-module. Let $Q_{1}: X \rightarrow \mathbb{A}$ be an $\mathbb{A}$-quadratic functional on $X$ and $Q_{2}: Y \rightarrow \mathbb{B}$ be a $\mathbb{B}$-quadratic functional on $Y$. Then corresponding to $Q_{1}$ and $Q_{2}$, there exists an $\mathbb{A} \otimes_{\gamma} \mathbb{B}$-sesquilinear functional

$$
B:(X \otimes Y) \times(X \otimes Y) \rightarrow \mathbb{A} \otimes_{\gamma} \mathbb{B}
$$

such that

$$
B(x \otimes y, x \otimes y)=Q_{1}(x) \otimes Q_{2}(y)
$$

for each $x \in X$ and $y \in Y$. Moreover, if $X$ and $Y$ are $C^{*}$ algebras and $Q_{1}$ and $Q_{2}$ are bounded, then for $u=x \otimes y \in$ $X \otimes Y$,

$$
\left\|B\left(u u^{*}, u u^{*}\right)\right\| \leq 4\left\|Q_{1}\right\| \cdot\left\|Q_{2}\right\| \cdot\|u\|^{2}
$$

Proof: For the unitary left $\mathbb{A}$-module $X$, from the given $\mathbb{A}$-quadratic form $Q_{1}: X \rightarrow \mathbb{A}$, by Lemma 2.3 we construct an $\mathbb{A}$-sesquilinear functional

$$
B_{1}: X \times X \rightarrow \mathbb{A}
$$

For fixed vectors $u_{1}, v_{1} \in X$, we consider $f_{1}: \mathbb{A} \rightarrow \mathbb{A}$ and $g_{1}: \mathbb{A} \rightarrow \mathbb{A}$ defined by

$$
\begin{equation*}
f_{1}\left(w_{1}\right)=B_{1}\left(w_{1} u_{1}, v_{1}\right) \tag{1}
\end{equation*}
$$

and

$$
\begin{equation*}
g_{1}\left(w_{1}\right)=B_{1}\left(u_{1}, w_{1}^{*} v_{1}\right), w_{1} \in \mathbb{A} \tag{2}
\end{equation*}
$$

Again, for the unitary left $\mathbb{B}$-module $Y$, in a similar way we can construct the $\mathbb{B}$-sesquilinear functional

$$
B_{2}: Y \times Y \rightarrow \mathbb{B}
$$

For fixed vectors $u_{2}, v_{2} \in Y$, we define $f_{2}: \mathbb{B} \rightarrow \mathbb{B}$ and $g_{2}: \mathbb{B} \rightarrow \mathbb{B}$ by the relation

$$
\begin{equation*}
f_{2}\left(w_{2}\right)=B_{2}\left(w_{2} u_{2}, v_{2}\right) \tag{3}
\end{equation*}
$$

and

$$
\begin{equation*}
g_{2}\left(w_{2}\right)=B_{2}\left(u_{2}, w_{2}^{*} v_{2}\right), \text { for } w_{2} \in \mathbb{B} \tag{4}
\end{equation*}
$$

Let $B:(X \otimes Y) \times(X \otimes Y) \rightarrow \mathbb{A} \otimes_{\gamma} \mathbb{B}$ be defined by

$$
\begin{aligned}
& B\left(\sum_{i=1}^{n} u_{1_{i}} \otimes u_{2_{i}}, \sum_{j=1}^{m} v_{1_{j}} \otimes v_{2_{j}}\right) \\
& =\sum_{i=1}^{n} \sum_{j=1}^{m} B_{1}\left(u_{1_{i}}, v_{1_{j}}\right) \otimes B_{2}\left(u_{2_{i}}, v_{2_{j}}\right)
\end{aligned}
$$

where $\sum_{i=1}^{n} u_{1_{i}} \otimes u_{2_{i}}, \sum_{j=1}^{m} v_{1_{j}} \otimes v_{2_{j}} \in X \otimes Y$. Now,

$$
\begin{align*}
B\left(i u_{1} \otimes u_{2}, v_{1} \otimes v_{2}\right) & =B_{1}\left(i u_{1}, v_{1}\right) \otimes B_{2}\left(u_{2}, v_{2}\right) \\
& =i B_{1}\left(u_{1}, v_{1}\right) \otimes B_{2}\left(u_{2}, v_{2}\right) \\
& =i B\left(u_{1} \otimes u_{2}, v_{1} \otimes v_{2}\right) \tag{5}
\end{align*}
$$

Similarly,

$$
\begin{equation*}
B\left(u_{1} \otimes u_{2}, i v_{1} \otimes v_{2}\right)=-i B\left(u_{1} \otimes u_{2}, v_{1} \otimes v_{2}\right) \tag{6}
\end{equation*}
$$

On the projective tensor product $\mathbb{A} \otimes_{\gamma} \mathbb{B}$, we consider the function $f: \mathbb{A} \otimes_{\gamma} \mathbb{B} \rightarrow \mathbb{A} \otimes_{\gamma} \mathbb{B}$ such that

$$
\begin{align*}
f\left(\sum_{k} w_{1_{k}} \otimes w_{2_{k}}\right) & =\frac{1}{2} \sum_{k}\left\{f_{1}\left(w_{1_{k}}\right) \otimes f_{2}\left(w_{2_{k}}\right)\right. \\
& \left.+g_{1}\left(w_{1_{k}}^{*}\right) \otimes g_{2}\left(w_{2_{k}}^{*}\right)\right\}, \tag{7}
\end{align*}
$$

where $\sum_{i} w_{1_{k}} \otimes w_{2_{k}} \in \mathbb{A} \otimes_{\gamma} \mathbb{B}$.
Now using (1), (2), (3) and (4), from (7) we have,

$$
\begin{aligned}
& f\left(\sum_{k} w_{1_{k}} \otimes w_{2_{k}}\right) \\
& =\frac{1}{2} \sum_{k}\left\{B_{1}\left(w_{1_{k}} u_{1}, v_{1}\right) \otimes B_{2}\left(w_{2_{k}} u_{2}, v_{2}\right)\right. \\
& \left.+B_{1}\left(u_{1}, w_{1_{k}} v_{1}\right) \otimes B_{2}\left(u_{2}, w_{2_{k}} v_{2}\right)\right\}
\end{aligned}
$$

$$
\begin{align*}
& =\frac{1}{2} \sum_{k}\left\{B\left(\left(w_{1_{k}} \otimes w_{2_{k}}\right)\left(u_{1} \otimes u_{2}\right), v_{1} \otimes v_{2}\right)\right. \\
& \left.+B\left(u_{1} \otimes u_{2},\left(w_{1_{k}} \otimes w_{2_{k}}\right)\left(v_{1} \otimes v_{2}\right)\right)\right\} \\
& =\frac{1}{2}\left\{B\left(\left(\sum_{k} w_{1_{k}} \otimes w_{2_{k}}\right)\left(u_{1} \otimes u_{2}\right), v_{1} \otimes v_{2}\right)\right. \\
& \left.+B\left(u_{1} \otimes u_{2},\left(\sum_{k} w_{1_{k}} \otimes w_{2_{k}}\right)\left(v_{1} \otimes v_{2}\right)\right)\right\} \tag{8}
\end{align*}
$$

Since $B_{1}$ is $\mathbb{A}$-sesquilinear functional, so from (1) and (2) we obtain,

$$
\begin{equation*}
f_{1}\left(e_{1}\right)=B_{1}\left(u_{1}, v_{1}\right)=g_{1}\left(e_{1}\right) \tag{9}
\end{equation*}
$$

and

$$
\begin{align*}
f_{1}\left(w_{1}\right) & =B_{1}\left(w_{1} u_{1}, v_{1}\right) \\
& =w_{1} B_{1}\left(u_{1}, v_{1}\right)=w_{1} f_{1}\left(e_{1}\right)(u \operatorname{sing}(9)) . \tag{10}
\end{align*}
$$

Similarly, we can show that

$$
\begin{gather*}
f_{2}\left(e_{2}\right)=B_{2}\left(u_{2}, v_{2}\right)=g_{2}\left(e_{2}\right), \\
f_{2}\left(w_{2}\right)=w_{2} f_{2}\left(e_{2}\right),  \tag{11}\\
g_{1}\left(w_{1}^{*}\right)=g_{1}\left(e_{1}\right) w_{1}^{*} \tag{12}
\end{gather*}
$$

and

$$
\begin{equation*}
g_{2}\left(w_{2}^{*}\right)=g_{2}\left(e_{2}\right) w_{2}^{*} . \tag{13}
\end{equation*}
$$

Now using (10), (11), (12) and (13), from (7), we get,

$$
\begin{align*}
& f\left(\sum_{k} w_{1_{k}} \otimes w_{2_{k}}\right) \\
& =\frac{1}{2} \sum_{i}\left\{f_{1}\left(w_{1_{k}}\right) \otimes f_{2}\left(w_{2_{k}}\right)+g_{1}\left(w_{1_{k}}^{*}\right) \otimes g_{2}\left(w_{2_{k}}^{*}\right)\right\} \\
& =\frac{1}{2} \sum_{k}\left\{w_{1_{k}} f_{1}\left(e_{1}\right) \otimes w_{2_{k}} f_{2}\left(e_{2}\right)+g_{1}\left(e_{1}\right) w_{1_{k}}^{*} \otimes g_{2}\left(e_{2}\right) w_{2_{k}}^{*}\right\} \\
& =\frac{1}{2} \sum_{k}\left\{\left(w_{1_{k}} \otimes w_{2_{k}}\right)\left(B_{1}\left(u_{1}, v_{1}\right) \otimes B_{2}\left(u_{2}, v_{2}\right)\right)\right. \\
& \left.+\left(B_{1}\left(u_{1}, v_{2}\right) \otimes B_{2}\left(u_{2}, v_{2}\right)\right)\left(w_{1_{k}}^{*} \otimes w_{2_{k}}^{*}\right)\right\} \\
& =\frac{1}{2} \sum_{k}\left\{\left(w_{1_{k}} \otimes w_{2_{k}}\right) B\left(u_{1} \otimes u_{2}, v_{1} \otimes v_{2}\right)\right. \\
& \left.+B\left(u_{1} \otimes u_{2}, v_{1} \otimes v_{2}\right)\left(w_{1_{k}}^{*} \otimes w_{2_{k}}^{*}\right)\right\} \\
& =\frac{1}{2}\left\{\sum_{k}\left(w_{1_{k}} \otimes w_{2_{k}}\right) B\left(u_{1} \otimes u_{2}, v_{1} \otimes v_{2}\right)\right. \\
& \left.+B\left(u_{1} \otimes u_{2}, v_{1} \otimes v_{2}\right) \sum_{k}\left(w_{1_{k}}^{*} \otimes w_{2_{k}}^{*}\right)\right\} \tag{14}
\end{align*}
$$

Now comparing (8) and (14) we obtain,

$$
\begin{align*}
& B\left(\left(\sum_{k} w_{1_{k}} \otimes w_{2_{k}}\right)\left(u_{1} \otimes u_{2}\right), v_{1} \otimes v_{2}\right) \\
& +B\left(u_{1} \otimes u_{2},\left(\sum_{k} w_{1_{k}} \otimes w_{2_{k}}\right)\left(v_{1} \otimes v_{2}\right)\right) \\
& =\left(\sum_{k} w_{1_{k}} \otimes w_{2_{k}}\right) B\left(u_{1} \otimes u_{2}, v_{1} \otimes v_{2}\right) \\
& +B\left(u_{1} \otimes u_{2}, v_{1} \otimes v_{2}\right)\left(\sum_{k} w_{1_{k}}^{*} \otimes w_{2_{k}}^{*}\right) \tag{15}
\end{align*}
$$

Replacing $\sum_{k} w_{1_{k}} \otimes w_{2_{k}}$ by $\sum_{k} i w_{1_{k}} \otimes w_{2_{k}}$ and using (5) and (6), we get,

$$
B\left(\left(\sum_{k} w_{1_{k}} \otimes w_{2_{k}}\right)\left(u_{1} \otimes u_{2}\right), v_{1} \otimes v_{2}\right)
$$

$$
\begin{align*}
& -B\left(u_{1} \otimes u_{2},\left(\sum_{k} w_{1_{k}} \otimes w_{2_{k}}\right)\left(v_{1} \otimes v_{2}\right)\right) \\
& =\left(\sum_{k} w_{1_{k}} \otimes w_{2_{k}}\right) B\left(u_{1} \otimes u_{2}, v_{1} \otimes v_{2}\right) \\
& -B\left(u_{1} \otimes u_{2}, v_{1} \otimes v_{2}\right)\left(\sum_{k} w_{1_{k}}^{*} \otimes w_{2_{k}}^{*}\right) \tag{16}
\end{align*}
$$

Thus for $u=\sum_{i=1}^{n} u_{1_{i}} \otimes u_{2_{i}}, v=\sum_{j=1}^{m} v_{1_{j}} \otimes v_{2_{j}} \in X \otimes Y$ and $w=\sum_{k} w_{1_{k}} \otimes w_{2_{k}} \in \mathbb{A} \otimes_{\gamma} \mathbb{B}$, comparing (15) and (16) we get,

$$
B(w u, v)=w B(u, v)
$$

and

$$
B(u, w v)=B(u, v) w^{*}
$$

Thus $B$ is an $\mathbb{A} \otimes_{\gamma} \mathbb{B}$-sesquilinear functional.
For $x \in X, y \in Y$,

$$
B(x \otimes y, x \otimes y)=B_{1}(x, x) \otimes B_{2}(y, y)=Q_{1}(x) \otimes Q_{2}(y)
$$

Now, we consider $X$ and $Y$ as $C^{*}$-algebras and let $Q_{1}$ and $Q_{2}$ be bounded. Then for $u_{1}, v_{1} \in X$,

$$
\begin{aligned}
\left\|B_{1}\left(u_{1}, v_{1}\right)\right\| & =\| \frac{1}{4}\left(Q_{1}\left(u_{1}+v_{1}\right)-Q_{1}\left(u_{1}-v_{1}\right)\right) \\
& +\frac{i}{4}\left(Q_{1}\left(u_{1}+i v_{1}\right)-Q_{1}\left(u_{1}-i v_{1}\right)\right) \| \\
& \leq \frac{1}{4}\left(\left\|Q_{1}\right\| \cdot\left\|u_{1}+v_{1}\right\|+\left\|Q_{1}\right\| \cdot\left\|u_{1}-v_{1}\right\|\right) \\
& +\frac{1}{4}\left(\left\|Q_{1}\right\| \cdot\left\|u_{1}+i v_{1}\right\|+\left\|Q_{1}\right\| \cdot\left\|u_{1}-i v_{1}\right\|\right) \\
& \leq\left\|Q_{1}\right\|\left(\left\|u_{1}\right\|+\left\|v_{1}\right\|\right) .
\end{aligned}
$$

Similarly, $\left\|B_{2}\left(u_{2}, v_{2}\right)\right\| \leq\left\|Q_{2}\right\|\left(\left\|u_{2}\right\|+\left\|v_{2}\right\|\right)$ for all $u_{2}, v_{2} \in Y$.
Now, for $u=x \otimes y \in X \otimes Y$,

$$
\begin{aligned}
& \left\|B\left(u u^{*}, u u^{*}\right)\right\| \\
& =\left\|B_{1}\left(x x^{*}, x x^{*}\right)\right\| \cdot\left\|B_{2}\left(y y^{*}, y y^{*}\right)\right\| \\
& \leq\left\|Q_{1}\right\|\left(\left\|x x^{*}\right\|+\left\|x x^{*}\right\|\right) \cdot\left\|Q_{2}\right\|\left(\left\|y y^{*}\right\|+\left\|y y^{*}\right\|\right) \\
& =4\left\|Q_{1}\right\| \cdot\left\|Q_{2}\right\| \cdot\left\|x x^{*}\right\| \cdot\left\|y y^{*}\right\| \\
& =4\left\|Q_{1}\right\| \cdot\left\|Q_{2}\right\| \cdot\|x\|^{2} \cdot\|y\|^{2} \\
& =4\left\|Q_{1}\right\| \cdot\left\|Q_{2}\right\| \cdot\|x \otimes y\|^{2} \\
& =4\left\|Q_{1}\right\| \cdot\left\|Q_{2}\right\| \cdot\|u\|^{2} .
\end{aligned}
$$

Example 3.2: Let $X=\mathbb{A}=l^{1}$ and $Y=\mathbb{B}=\mathbb{R}$. Let the mappings $Q_{1}: l^{1} \rightarrow l^{1}$ be defined by

$$
Q_{1}\left(\left\{x_{1}, x_{2}, x_{3}, \ldots . .\right\}\right)=\left\{x_{1}^{2}, x_{2}^{2}, 0,0, \ldots .\right\} \text { for }\left\{x_{n}\right\} \in l^{1}
$$

and $Q_{2}: \mathbb{R} \rightarrow \mathbb{R}$ by $Q_{2}(u)=u^{2}$, for $u \in \mathbb{R}$. Clearly, $Q_{1}$ and $Q_{2}$ are $\mathbb{A}$-quadratic functionals. Now, by Lemma 2.3, we can construct two $\mathbb{A}$-sesquilinear functionals $B_{1}: l^{1} \times l^{1} \rightarrow l^{1}$ and $B_{2}: \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ defined by

$$
B_{1}\left(\left\{x_{1}, x_{2}, x_{3}, \ldots\right\},\left\{y_{1}, y_{2}, y_{3}, \ldots\right\}\right)=\left\{x_{1} y_{1}, x_{2} y_{2}, 0,0, \ldots\right\}
$$

and $B_{2}(u, v)=u v$ where $\left\{x_{n}\right\},\left\{y_{n}\right\} \in l^{1}$ and $u, v \in \mathbb{R}$. Since, $l^{1} \otimes_{\gamma} \mathbb{R} \cong l^{1}(\mathbb{R})$ so, by Theorem 3.1, there exists

$$
B:\left(l^{1} \otimes \mathbb{R}\right) \times\left(l^{1} \otimes \mathbb{R}\right) \rightarrow l^{1}(\mathbb{R})
$$

such that

$$
B\left(\sum_{i=1}^{n} u_{i} \otimes v_{i}, \sum_{j=1}^{m} r_{j} \otimes s_{j}\right)
$$

$$
=\sum_{i=1}^{n} \sum_{j=1}^{m}\left\{p_{i_{1}} q_{j_{1}} v_{i} s_{j}, p_{i_{2}} q_{j_{2}} v_{i} s_{j}, 0,0, \ldots .\right\}
$$

where $u_{i}=\left\{p_{i_{k}}\right\}_{k}, r_{j}=\left\{q_{j_{k}}\right\}_{k} \in l^{1}$ and $v_{i}, s_{j} \in \mathbb{R}$.
Now,

$$
\begin{aligned}
& \sum_{i=1}^{n} \sum_{j=1}^{m} B_{1}\left(u_{i}, r_{j}\right) \otimes B_{2}\left(v_{i}, s_{j}\right) \\
& =\sum_{i=1}^{n} \sum_{j=1}^{m}\left\{p_{i_{1}} q_{j_{1}}, p_{i_{2}} q_{j_{2}}, 0,0, \ldots\right\} \otimes v_{i} s_{j} \\
& =\sum_{i=1}^{n} \sum_{j=1}^{m}\left\{p_{i_{1}} q_{j_{1}} v_{i} s_{j}, p_{i_{2}} q_{j_{2}} v_{i} s_{j}, 0,0, \ldots .\right\} \\
& =B\left(\sum_{i=1}^{n} u_{i} \otimes v_{i}, \sum_{j=1}^{m} r_{j} \otimes s_{j}\right),
\end{aligned}
$$

which exhibits the content of the Theorem 3.1.
The following result deals with zero product determined Banach *-algebras.

Theorem 3.3 Let $X, Y$ be two unital zero product determined Banach *-algebras with unit elements $e_{1}^{\prime}, e_{2}^{\prime}$ respectively and $\mathbb{A}, \mathbb{B}$ be two hermitian Banach ${ }^{*}$-algebras with unit elements $e_{1}, e_{2}$ respectively. Let $X$ be a unitary left $\mathbb{A}$-module and $Y$ be a unitary left $\mathbb{B}$-module. Let $Q_{1}: X \rightarrow \mathbb{A}$ be a bounded $\mathbb{A}$-quadratic functional on $X$ and $Q_{2}: Y \rightarrow \mathbb{B}$ be a bounded $\mathbb{B}$-quadratic functional on $Y$ satisfying $x_{i} y_{i}=0$ implies $Q_{i}\left(x_{i}+y_{i}\right)=0$ (for $i=1,2$ ), $x_{1}, y_{1} \in X$ and $x_{2}, y_{2} \in Y$. Then there exists a bounded linear mapping

$$
L: X \otimes Y \rightarrow \mathbb{A} \otimes_{\gamma} \mathbb{B}
$$

such that

$$
L\left(\sum_{i=1}^{n} x_{i} \otimes y_{i}\right)=B\left(\sum_{i=1}^{n} x_{i} \otimes y_{i}, e_{1}^{\prime} \otimes e_{2}^{\prime}\right)
$$

and $\|L\| \leq\|B\|$, where $B$ is the $\mathbb{A} \otimes_{\gamma} \mathbb{B}$-sesquilinear functional as defined in Theorem 3.1.

Proof: Let $B_{1}, B_{2}$ be the sesquilinear functionals determined by $Q_{1}$ and $Q_{2}$ respectively. Let $x_{1}, y_{1} \in X$ with $x_{1} y_{1}=0$. Now,

$$
\begin{aligned}
B_{1}\left(x_{1}, y_{1}\right) & =\frac{1}{4}\left(Q_{1}\left(x_{1}+y_{1}\right)-Q_{1}\left(x_{1}-y_{1}\right)\right) \\
& +\frac{i}{4}\left(Q_{1}\left(x_{1}+i y_{1}\right)-Q_{2}\left(x_{1}-i y_{1}\right)\right) \\
& =0
\end{aligned}
$$

Thus, $x_{1} y_{1}=0$ implies $B_{1}\left(x_{1}, y_{1}\right)=0$. So, there exists a linear mapping $L_{1}: X^{2} \rightarrow \mathbb{A}$ such that

$$
B_{1}\left(u_{1}, v_{1}\right)=L_{1}\left(u_{1} v_{1}\right), u_{1}, v_{1} \in X
$$

Similarly, we have a linear mapping $L_{2}: Y^{2} \rightarrow \mathbb{B}$ with

$$
B_{2}\left(u_{2}, v_{2}\right)=L_{2}\left(u_{2} v_{2}\right), u_{2}, v_{2} \in Y .
$$

Now, we define $L: X \otimes Y \rightarrow \mathbb{A} \otimes_{\gamma} \mathbb{B}$ such that

$$
L\left(\sum_{i=1}^{n} x_{i} \otimes y_{i}\right)=\sum_{i=1}^{n} L_{1}\left(x_{i} e_{1}^{\prime}\right) \otimes L_{2}\left(y_{i} e_{2}^{\prime}\right)
$$

$$
\begin{aligned}
& =\sum_{i=1}^{n} B_{1}\left(x_{i}, e_{1}^{\prime}\right) \otimes B_{2}\left(y_{i}, e_{2}^{\prime}\right) \\
& =B\left(\sum_{i=1}^{n} x_{i} \otimes y_{i}, e_{1}^{\prime} \otimes e_{2}^{\prime}\right)
\end{aligned}
$$

Also it is easy to see that $\|L\| \leq\|B\|$.
Now we establish a relation between the $\mathbb{A} \otimes_{\gamma} \mathbb{B}$ sesquilinear functional and Jordan $(\theta, \phi)$-derivation. For this, we introduce a new class of $\mathbb{A}$-quadratic functionals with respect to the mappings $\theta$ and $\phi$, denoted as $(\theta, \phi)$ - $\mathbb{A}$ quadratic functional, and represent such quadratic functional using a given Jordan $(\theta, \phi)$-derivation.

Definition 3.4: $((\theta, \phi)$-A -quadratic functional) Let $X$ be a vector space and $\mathbb{A}$ be a unital $*$-algebra with unit element $e$ such that $X$ is a left $\mathbb{A}$-module. For two additive self mappings $\theta$ and $\phi$ as antihomomorphism and homomorphism respectively on $\mathbb{A}$ and $\theta(e)=\phi(e)=e$, a mapping $Q: X \rightarrow \mathbb{A}$ is said to be a $(\theta, \phi)$ - $\mathbb{A}$-quadratic functional if the following conditions hold:
(i) $Q(x+y)+Q(x-y)=2 Q(x)+2 Q(y)$,
(ii) $Q(a x)=\phi(a) Q(x) \theta(a)$ for all $x, y \in X, a \in \mathbb{A}$.

Example 3.5: Let $X=\mathbb{A}=M_{n}(\mathbb{R})$ with usual matrix operations. We define $Q: M_{n}(\mathbb{R}) \rightarrow M_{n}(\mathbb{R})$ by

$$
Q(M)=M M^{T}
$$

for all $M \in M_{n}(\mathbb{R})$, where $M^{T}$ denotes the transpose of $M$. Let the self mappings $\theta$ and $\phi$ on $M_{n}(\mathbb{R})$ be defined by $\theta(M)=M^{T}$ and $\phi(M)=M$ for all $M \in M_{n}(\mathbb{R})$. Then $Q$ is a $(\theta, \phi)$ - $\mathbb{A}$-quadratic functional.

Example 3.6 Let $X=\mathbb{A}=l^{1}$. Let the mapping $Q: l^{1} \rightarrow l^{1}$ be defined by

$$
Q\left(\left\{x_{1}, x_{2}, x_{3}, \ldots .\right\}\right)=\left\{x_{1} x_{2}, x_{1} x_{2}, 0,0, \ldots .\right\} \text { for }\left\{x_{n}\right\} \in l^{1}
$$

Let $\theta$ and $\phi$ be two self mappings on $l^{1}$ such that

$$
\begin{gathered}
\theta\left(\left\{x_{1}, x_{2}, x_{3}, \ldots\right\}\right)=\left\{x_{2}, x_{1}, 0,0, \ldots\right\} \\
\text { and } \phi\left(\left\{x_{1}, x_{2}, x_{3}, \ldots\right\}\right)=\left\{x_{1}, x_{2}, 0,0, \ldots\right\} .
\end{gathered}
$$

Then $Q$ is a $(\theta, \phi)$ - $\mathbb{A}$-quadratic functional.
Remark 3.7 It becomes evident that when $\phi$ is the indentity mapping on a Banach *-algebra $\mathbb{A}$ and $\theta$ is an involution on $\mathbb{A}$, the class of all $(\theta, \phi)$ - $\mathbb{A}$-quadratic functionals contains the class of $\mathbb{A}$-quadratic functionals.
Following the Theorem 2.1 of [24], some equivalent characterization for Jordan $(\theta, \phi)$-derivation can be obtained as follows:

Lemma 3.8 Let $\mathbb{A}$ be a unital Banach *-algebra with unit element $e$, and $\Delta: \mathbb{A} \rightarrow \mathbb{A}$ be an additive mapping. Let $\theta$ and $\phi$ be two additive self mappings on $\mathbb{A}$ with $\theta(u v)=\theta(v) \theta(u), \phi(u v)=\phi(u) \phi(v)$ and $\theta(e)=\phi(e)=e$. Then the following conditions are equivalent:
(i) $\Delta$ is a Jordan $(\theta, \phi)$-derivation,
(ii) $\Delta(u)=-\phi(u) \Delta\left(u^{-1}\right) \theta(u)$ for all invertible $u \in \mathbb{A}$,
(iii) $\Delta(u v u)=\phi(u v) \Delta(u)+\phi(u) \Delta(v) \theta(u)+\Delta(u) \theta(u v)$ for all $u, v \in \mathbb{A}$.

Proof: (ii) $\Longrightarrow$ (i):
For invertible $u \in \mathbb{A}, \Delta(u)=-\phi(u) \Delta\left(u^{-1}\right) \theta(u)$. So $\Delta(e)=0$.
Let $u$ be invertible and $\|u\|<1$. Then $e+u, e-u, e-u^{2}$ are also invertible, and $(u-e)^{-1}-\left(u^{2}-e\right)^{-1}=\left(u^{2}-e\right)^{-1} u$. We have to show that $\Delta\left(u^{2}\right)=\phi(u) \Delta(u)+\Delta(u) \theta(u)$. Now,

$$
\begin{aligned}
& \Delta(u)+\phi\left(u^{-1}\right) \Delta(u) \theta\left(u^{-1}\right) \\
& =\Delta(u)-\Delta\left(u^{-1}\right)=\Delta\left(u-u^{-1}\right)=\Delta\left(u^{-1}\left(u^{2}-e\right)\right) \\
& =-\phi\left(u^{-1}\left(u^{2}-e\right)\right) \Delta\left(\left(u^{2}-e\right)^{-1} u\right) \theta\left(u^{-1}\left(u^{2}-e\right)\right) \\
& =-\phi\left(u^{-1}\right) \phi\left(u^{2}-e\right) \Delta\left((u-e)^{-1}\right) \theta\left(u^{2}-e\right) \theta\left(u^{-1}\right) \\
& +\phi\left(u^{-1}\right) \phi\left(u^{2}-e\right) \Delta\left(\left(u^{2}-e\right)^{-1}\right) \theta\left(u^{2}-e\right) \theta\left(u^{-1}\right) \\
& =-\phi\left(u^{-1}\right) \phi(u+e) \phi(u-e) \Delta\left((u-e)^{-1}\right) \\
& \theta(u-e) \theta(u+e) \theta\left(u^{-1}\right)-\phi\left(u^{-1}\right) \Delta\left(u^{2}-e\right) \theta\left(u^{-1}\right) \\
& =\phi\left(u^{-1}\right) \phi(u+e) \Delta(u-e) \theta(u+e) \theta\left(u^{-1}\right) \\
& -\theta\left(u^{-1}\right) \Delta\left(u^{2}\right) \theta\left(u^{-1}\right) \\
& =\phi\left(e+u^{-1}\right) \Delta(u) \theta\left(e+u^{-1}\right)-\phi\left(u^{-1}\right) \Delta\left(u^{2}\right) \theta\left(u^{-1}\right) \\
& =\left(\phi(e)+\phi\left(u^{-1}\right)\right) \Delta(u)\left(\theta(e)+\theta\left(u^{-1}\right)\right) \\
& -\phi\left(u^{-1}\right) \Delta\left(u^{2}\right) \theta\left(u^{-1}\right) \\
& =\Delta(u)+\Delta(u) \theta\left(u^{-1}\right)+\phi\left(u^{-1}\right) \Delta(u)+\phi\left(u^{-1}\right) \Delta(u) \theta\left(u^{-1}\right) \\
& -\phi\left(u^{-1}\right) \Delta\left(u^{2}\right) \theta\left(u^{-1}\right) .
\end{aligned}
$$

We finally get,

$$
\begin{align*}
\phi\left(u^{-1}\right) \Delta\left(u^{2}\right) \theta\left(u^{-1}\right) & =\phi\left(u^{-1}\right) \Delta(u)+\Delta(u) \theta\left(u^{-1}\right), \\
\text { i.e., } \Delta\left(u^{2}\right) & =\phi(u) \Delta(u)+\Delta(u) \theta(u) . \tag{17}
\end{align*}
$$

Thus, for $\|u\|<1, \Delta$ is a Jordan $(\theta, \phi)$-derivation.
Now, let $\|u\|>1$. Then $t^{-1} u$ is invertible for some positive integer $t$ with $\left\|t^{-1} u\right\|<1$. Then by (17),

$$
\Delta\left(\left(t^{-1} u\right)^{2}\right)=\phi\left(t^{-1} u\right) \Delta\left(t^{-1} u\right)+\Delta\left(t^{-1} u\right) \theta\left(t^{-1} u\right)
$$

Multiplying both sides of the above equation by $t^{2}$ and using the additivity of $\Delta$ we get,

$$
\Delta\left(u^{2}\right)=\phi(u) \Delta(u)+\Delta(u) \theta(u)
$$

Again let $u$ be an arbitrary element. Then for some integer $t,\|u\|<t$, i.e., $\left\|t^{-1} u\right\|<1$. So, $e-t^{-1} u$ is invertible and hence $u-t e$ is also invertible. Then

$$
\begin{aligned}
\Delta\left((u-t e)^{2}\right) & =\phi(u-t e) \Delta(u-t e) \\
& +\Delta(u-t e) \theta(u-t e), \\
i . e ., \Delta\left(u^{2}\right)-2 t \Delta(u) & =\phi(u-t e) \Delta(u)+\Delta(u) \theta(u-t e) \\
& =(\phi(u)-\phi(t e)) \Delta(u) \\
& +\Delta(u)(\theta(u)-\theta(t e)) \\
& =(\phi(u)-t) \Delta(u)+\Delta(u)(\theta(u)-t) \\
& =\phi(u) \Delta(u)+\Delta(u) \theta(u)-2 t \Delta(u), \\
\text { i.e., } \Delta\left(u^{2}\right) & =\phi(u) \Delta(u)+\Delta(u) \theta(u) .
\end{aligned}
$$

(i) $\Longrightarrow$ (iii):

Replacing $u$ by $u+v$ in (17), for all $u, v \in \mathbb{A}$ we get,

$$
\begin{align*}
\Delta(u v)+\Delta(v u) & =\phi(v) \Delta(u)+\phi(u) \Delta(v)+\Delta(u) \theta(v) \\
& +\Delta(v) \theta(u) \tag{18}
\end{align*}
$$

Taking $z=\Delta(u(u v+v u)+(u v+v u) u)$ and using (18), we get,

$$
\begin{align*}
z & =\Delta(u(u v+v u)+(u v+v u) u) \\
& =\phi(u) \Delta(u v+v u)+\phi(u v+v u) \Delta(u) \\
& +\Delta(u v+v u) \theta(u)+\Delta(u) \theta(u v+v u) \\
& =\phi(u)\{\phi(u) \Delta(v)+\Delta(u) \theta(v)\}+\phi(u)\{\phi(v) \Delta(u) \\
& +\Delta(v) \theta(u)\}+\phi(u v) \Delta(u)+\phi(v u) \Delta(u)+\{\phi(u) \Delta(v) \\
& +\Delta(u) \theta(v)\} \theta(u)+\{\phi(v) \Delta(u)+\Delta(v) \theta(u)\} \theta(u) \\
& +\Delta(u) \theta(u v)+\Delta(u) \theta(v u) \\
& =\phi\left(u^{2}\right) \Delta(v)+\phi(u) \Delta(u) \theta(v)+\phi(u v) \Delta(u) \\
& +\phi(u) \Delta(v) \theta(u)+\phi(u v) \Delta(u)+\phi(v u) \Delta(u) \\
& +\phi(u) \Delta(v) \theta(u)+\Delta(u) \theta(u v)+\phi(v) \Delta(u) \theta(u) \\
& +\Delta(v) \theta\left(u^{2}\right)+\Delta(u) \theta(u v)+\Delta(u) \theta(v u) \\
& =2 \phi(u v) \Delta(u)+\phi\left(u^{2}\right) \Delta(v)+\phi(u) \Delta(u) \theta(v) \\
& +2 \phi(u) \Delta(v) \theta(u)+\phi(v u) \Delta(u)+\phi(v) \Delta(u) \theta(u) \\
& +2 \Delta(u) \theta(u v)+\Delta(v) \theta\left(u^{2}\right)+\Delta(u) \theta(v u) . \tag{19}
\end{align*}
$$

Again,

$$
\begin{align*}
z & =2 \Delta(u v u)+\Delta\left(u^{2} v\right)+\Delta\left(v u^{2}\right) \\
& =2 \Delta(u v u)+\phi(v) \Delta\left(u^{2}\right)+\phi\left(u^{2}\right) \Delta(v) \\
& +\Delta\left(u^{2}\right) \theta(v)+\Delta(v) \theta\left(u^{2}\right) \\
& =2 \Delta(u v u)+\phi(v u) \Delta(u)+\phi(v) \Delta(u) \theta(u) \\
& +\phi\left(u^{2}\right) \Delta(v)+\phi(u) \Delta(u) \theta(v) \\
& +\Delta(u) \theta(v u)+\Delta(v) \theta\left(u^{2}\right) . \tag{20}
\end{align*}
$$

Comparing (19) and (20) we get,

$$
\Delta(u v u)=\phi(u v) \Delta(u)+\phi(u) \Delta(v) \theta(u)+\Delta(u) \theta(u v) .
$$

(iii) $\Longrightarrow$ (ii) follows by putting $v=u^{-1}$ in (iii).

Following a similar way as Semrl [24], we present the following two lemmas which will help to give a representation of $(\theta, \phi)$ - $\mathbb{A}$-quadratic functional via Jordan $(\theta, \phi)$-derivation.

Lemma 3.9 Let $\mathbb{A}$ be a unital Banach *-algebra with unit element $e$ and $\Delta: \mathbb{A} \rightarrow \mathbb{A}$ a Jordan $(\theta, \phi)$-derivation. Let $\theta$ and $\phi$ be two additive self mappings on $\mathbb{A}$ with $\theta(u v)=\theta(v) \theta(u), \phi(u v)=\phi(u) \phi(v)$ and $\theta(e)=\phi(e)=e$. Then for all $u, v, w$ and invertible $z \in \mathbb{A}$,
(i) $\phi(z) \Delta\left(z^{-1} u\right) \theta(z)=\Delta(u z)-\phi(u) \Delta(z)-\Delta(z) \theta(u)$,
(ii) $\Delta(w v w u)=\phi(w) \Delta(v u) \theta(w)+\phi(w v) \Delta(w u)-$ $\phi(w v) \Delta(u) \theta(w)+\Delta(w u) \theta(w v)-\phi(w) \Delta(u) \theta(w v)$.

Proof: (i) Let $u z=e$. So, $u=e z^{-1}$. Now using the conditions (ii) and (iii) of the Lemma 3.8 we get,

$$
\begin{aligned}
& \phi(z) \Delta\left(z^{-1} u\right) \theta(z) \\
& =\phi(z) \Delta\left(z^{-1} e z^{-1}\right) \theta(z) \\
& =\phi(e) \Delta\left(z^{-1}\right) \theta(z)+\Delta(e)+\phi(z) \Delta\left(z^{-1}\right) \theta(e) \\
& =\phi(u z) \Delta\left(z^{-1}\right) \theta(z)+\Delta(u z)+\phi(z) \Delta\left(z^{-1}\right) \theta(u z) \\
& =\phi(u) \phi(z) \Delta\left(z^{-1}\right) \theta(z)+\Delta(u z)+\phi(z) \Delta\left(z^{-1}\right) \theta(z) \theta(u) \\
& =\Delta(u z)-\phi(u) \Delta(z)-\Delta(z) \theta(u) .
\end{aligned}
$$

(ii) Using the Lemma 3.8 we have,

$$
\begin{aligned}
& \Delta(w v w u) \\
& =\Delta\left(w u\left(u^{-1} v\right) w u\right) \\
& =\phi\left(w u u^{-1} v\right) \Delta(w u)+\phi(w u) \Delta\left(u^{-1} v\right) \theta(w u) \\
& +\Delta(w u) \theta\left(w u u^{-1} v\right) \\
& =\phi(w v) \Delta(w u)+\phi(w) \phi(u) \Delta\left(u^{-1} v\right) \theta(u) \theta(w) \\
& +\Delta(w u) \theta(w v) \\
& =\phi(w v) \Delta(w u)+\phi(w)\{\Delta(v u)-\phi(v) \Delta(u) \\
& -\Delta(u) \theta(v)\} \theta(w)+\Delta(w u) \theta(w v) \\
& =\phi(w v) \Delta(w u)+\phi(w) \Delta(v u) \theta(w)-\phi(w) \phi(v) \Delta(u) \theta(w) \\
& -\phi(w) \Delta(u) \theta(v) \theta(w)+\Delta(w u) \theta(w v) \\
& =\phi(w v) \Delta(w u)+\phi(w) \Delta(v u) \theta(w)-\phi(w v) \Delta(u) \theta(w) \\
& -\phi(w) \Delta(u) \theta(w v)+\Delta(w u) \theta(w v) .
\end{aligned}
$$

Lemma 3.10 Let $\mathbb{A}$ be a unital Banach *-algebra with unit element $e$. Let $\phi$ and $\theta$ be two additive self mappings on $\mathbb{A}$ such that $\theta(u v)=\theta(v) \theta(u), \phi(u v)=\phi(u) \phi(v)$ and $\theta(e)=\phi(e)=e$. Suppose that the mappings $\psi_{1}, \psi_{2}: \mathbb{A} \rightarrow \mathbb{A}$ satisfy the conditions:
(i) $2 \psi_{1}(u)+2 \psi_{1}(v)=4 \psi_{1}\left(\frac{1}{2}(u+v)\right)+\phi(u-v) \psi_{2}(0) \theta(u-$ v),
(ii) $2 \psi_{2}(u)+2 \psi_{2}(v)=4 \psi_{2}\left(\frac{1}{2}(u+v)\right)+\phi(u-v) \psi_{1}(0) \theta(u-$ $v)$,
and
(iii) $\psi_{1}(w)=\phi(w) \psi_{2}\left(w^{-1}\right) \theta(w)$
for all $u, v \in \mathbb{A}$ and all invertible $w \in \mathbb{A}$. Then there exists an element $z \in \mathbb{A}$ and a $\operatorname{Jordan}(\theta, \phi)$-derivation $\Delta$ on $\mathbb{A}$ such that

$$
\psi_{1}(u)=\phi(u) \psi_{2}(0) \theta(u)+\phi(u) z+z \theta(u)+\psi_{1}(0)+\Delta(u)
$$

for all $u \in \mathbb{A}$.
Proof: Suppose that

$$
\begin{equation*}
2 z=\psi_{1}(e)-\psi_{1}(0)-\psi_{2}(0)=\psi_{2}(e)-\psi_{1}(0)-\psi_{2}(0) \tag{21}
\end{equation*}
$$

Let $\Delta, \tilde{\Delta}: \mathbb{A} \rightarrow \mathbb{A}$ be such that

$$
\begin{equation*}
\psi_{1}(u)=\phi(u) \psi_{2}(0) \theta(u)+\phi(u) z+z \theta(u)+\psi_{1}(0)+\Delta(u) \tag{22}
\end{equation*}
$$

$\psi_{2}(u)=\phi(u) \psi_{1}(0) \theta(u)+\phi(u) z+z \theta(u)+\psi_{2}(0)+\tilde{\Delta}(u)$.

From condition (iii), using (22) and (23) we get, for all invertible $u \in \mathbb{A}$,

$$
\begin{align*}
\psi_{1}(u) & =\phi(u) \psi_{2}\left(u^{-1}\right) \theta(u) \\
& =\phi(u)\left\{\phi\left(u^{-1}\right) \psi_{1}(0) \theta\left(u^{-1}\right)+\phi\left(u^{-1}\right) z+z \theta\left(u^{-1}\right)\right. \\
& \left.+\psi_{2}(0)+\tilde{\Delta}\left(u^{-1}\right)\right\} \theta(u) \\
& =\psi_{1}(0)+z \theta(u)+\phi(u) z+\phi(u) \psi_{2}(0) \theta(u) \\
& +\phi(u) \tilde{\Delta}\left(u^{-1}\right) \theta(u) \\
\text { i.e., } \Delta(u) & =\phi(u) \tilde{\Delta}\left(u^{-1}\right) \theta(u) . \tag{24}
\end{align*}
$$

Now, putting $v=0$ in condition $(i)$, we get,

$$
\begin{equation*}
2 \psi_{1}(u)+2 \psi_{1}(0)=4 \psi_{1}\left(\frac{1}{2} u\right)+\phi(u) \psi_{2}(0) \theta(u) \tag{25}
\end{equation*}
$$

Using (23), from (22) we get,

$$
\begin{align*}
\psi_{1}\left(\frac{1}{2} u\right) & =\frac{1}{4} \phi(u) \psi_{2}(0) \theta(u)+\frac{1}{2} \phi(u) z \\
& +\frac{1}{2} z \theta(u)+\psi_{1}(0)+\Delta\left(\frac{1}{2} u\right) \\
\text { i.e., } 2 \psi_{1}(u)+2 \psi_{1}(0) & =2 \phi(u) \psi_{2}(0) \theta(u)+2 \phi(u) z+2 z \theta(u) \\
& +4 \psi_{1}(0)+4 \Delta\left(\frac{1}{2} u\right) \\
\text { i.e., } \frac{1}{2} \Delta(u) & =\Delta\left(\frac{1}{2} u\right) \tag{26}
\end{align*}
$$

Now from condition $(i)$, using (22) we get,

$$
\begin{aligned}
2 \psi_{1}(u)+2 \psi_{1}(v) & =4\left\{\phi\left(\frac{1}{2}(u+v)\right) \psi_{2}(0) \theta\left(\frac{1}{2}(u+v)\right)\right. \\
& +\phi\left(\frac{1}{2}(u+v)\right) z+z \theta\left(\frac{1}{2}(u+v)\right)+\psi_{1}(0) \\
& \left.+\Delta\left(\frac{1}{2}(u+v)\right)\right\}+\phi(u-v) \psi_{2}(0) \theta(u-v) \\
& =\phi(u+v) \psi_{2}(0) \theta(u+v)+2 \phi(u+v) z \\
& +2 z \theta(u+v)+4 \psi_{1}(0)+4 \Delta\left(\frac{1}{2}(u+v)\right) \\
& +\phi(u) \psi_{2}(0) \theta(u)-\phi(u) \psi_{2}(0) \theta(v) \\
& -\phi(v) \psi_{2}(0) \theta(u)+\phi(v) \psi_{2}(0) \theta(v) \\
& =2 \psi_{1}(u)-2 \Delta(u)+2 \psi_{1}(v)-2 \Delta(v) \\
& +4 \Delta\left(\frac{1}{2}(u+v)\right)
\end{aligned}
$$

i.e., $\Delta(u)+\Delta(v)=\Delta(u+v)(u \operatorname{sing}(26))$.

Hence $\Delta$ is additive.
Now let $u \in \mathbb{A}$ be invertible with $\|u\|<1$. Then $e+u$ is also invertible and

$$
\begin{equation*}
(e+u)^{-1}=e-(e+u)^{-1} u \tag{27}
\end{equation*}
$$

From (22),

$$
\begin{align*}
\psi_{1}(e) & =\phi(e) \psi_{2}(0) \theta(e)+\phi(e) z+z \theta(e)+\psi_{1}(0)+\Delta(e) \\
& =\psi_{2}(0)+2 z+\psi_{1}(0)+\Delta(e) \quad(\phi(e)=\theta(e)=e), \\
i . e ., \Delta(e) & =0(b y(21)) . \tag{28}
\end{align*}
$$

Similarly,

$$
\begin{equation*}
\tilde{\Delta}(e)=0 . \tag{29}
\end{equation*}
$$

Now using (27), (28), (29) and the additivity of $\Delta$, from (24) we get,

$$
\begin{aligned}
\Delta(u) & =\Delta(e+u)=\phi(e+u) \tilde{\Delta}\left((e+u)^{-1}\right) \theta(e+u) \\
& =-\phi(e+u) \tilde{\Delta}\left((e+u)^{-1} u\right) \theta(e+u) \\
& =-\phi(e+u) \phi\left((e+u)^{-1}\right) \phi(u) \Delta\left(u^{-1}\right. \\
& +e) \theta(u) \theta\left((e+u)^{-1}\right) \theta(e+u) \\
& =-\phi(u) \Delta\left(u^{-1}\right) \theta(u) .
\end{aligned}
$$

Using additivity of $\Delta$, it is easy to see that $\Delta(u)=$ $-\phi(u) \Delta\left(u^{-1}\right) \theta(u)$ holds for each invertible $u \in \mathbb{A}$. Now applying Lemma 3.8 we get, $\Delta$ is a Jordan $(\theta, \phi)$-derivation.

Theorem 3.11 Let $X$ be a vector space and $\mathbb{A}$ be a unital Banach *-algebra with unit element $e$ such that $X$ is a left $\mathbb{A}$ module. Let $\theta$ and $\phi$ be two additive self mappings on $\mathbb{A}$ with $\theta(u v)=\theta(v) \theta(u), \phi(u v)=\phi(u) \phi(v)$ and $\theta(e)=\phi(e)=e$.

For a Jordan $(\theta, \phi)$-derivation $\Delta$ on $\mathbb{A}$, let a mapping $Q$ : $X \rightarrow \mathbb{A}$ satisfy

$$
\begin{align*}
Q(u x+v y) & =\phi(u) Q(x) \theta(u)+\phi(u) w \theta(v)+\phi(v) w \theta(u) \\
& +\phi(v) Q(y) \theta(v)+\Delta(v u)-\phi(v) \Delta(u) \\
& -\Delta(u) \theta(v) \tag{30}
\end{align*}
$$

for all $x, y \in X$ and $u, v, w \in \mathbb{A}$ with $u$ invertible. Then $Q$ is a $(\theta, \phi)$ - $\mathbb{A}$-quadratic functional. Moreover, when $\phi$ is the identity mapping on $\mathbb{A}$ and $\theta$ is an involution on $\mathbb{A}$, then $Q$ becomes an $\mathbb{A}$-quadratic functional.

Proof: Using Lemma 3.9 in (30) we get,

$$
\begin{align*}
Q(u x+v y) & =\phi(u) Q(x) \theta(u)+\phi(u) w \theta(v)+\phi(v) w \theta(u) \\
& +\phi(v) Q(y) \theta(v)+\phi(u) \Delta\left(u^{-1} v\right) \theta(u) \tag{31}
\end{align*}
$$

Substituting $u^{-1}$ for $u$ and putting $v=e$, and applying Lemma 3.8 in (31) we get,

$$
\begin{align*}
& Q\left(u^{-1} x+y\right) \\
& =\phi\left(u^{-1}\right) Q(x) \theta\left(u^{-1}\right)+w \theta\left(u^{-1}\right)+\phi\left(u^{-1}\right) w+Q(y) \\
& +\phi\left(u^{-1}\right) \Delta(u) \theta\left(u^{-1}\right) \\
& =\phi\left(u^{-1}\right) Q(x) \theta\left(u^{-1}\right)+w \theta\left(u^{-1}\right)+\phi\left(u^{-1}\right) w \\
& +Q(y)-\Delta\left(u^{-1}\right) \tag{32}
\end{align*}
$$

Again putting $u=e$ and substituting $v=u$ in (31) we get,

$$
\begin{align*}
Q(x+u y) & =Q(x)+w \theta(u)+\phi(u) w \\
& +\phi(u) Q(y) \theta(u)+\Delta(u) \tag{33}
\end{align*}
$$

Using (32) and (33) we get,

$$
\begin{align*}
& \phi(u) Q\left(u^{-1} x+y\right) \theta(u) \\
& =\phi(u)\left\{\phi\left(u^{-1}\right) Q(x) \theta\left(u^{-1}\right)+w \theta\left(u^{-1}\right)+\phi\left(u^{-1}\right) w\right. \\
& \left.+Q(y)-\Delta\left(u^{-1}\right)\right\} \theta(u) \\
& =Q(x)+w \theta(u)+\phi(u) w+\phi(u) Q(y) \theta(u) \\
& -\phi(u) \Delta\left(u^{-1}\right) \theta(u) \\
& =Q(x)+w \theta(u)+\phi(u) w+\phi(u) Q(y) \theta(u)+\Delta(u) \\
& =Q(x+u y) \\
& =Q\left(u\left(u^{-1} x+y\right)\right) \tag{34}
\end{align*}
$$

Taking $x=u z, z \in \mathbb{A}$ and $y=0$ in (34) we get,

$$
\begin{equation*}
\phi(u) Q(z) \theta(u)=Q(u z) \tag{35}
\end{equation*}
$$

Again $\Delta(e)=0$. So, from (31) we get,

$$
\begin{aligned}
Q(x+y)+Q(x-y) & =Q(x)+w+w+Q(y)+Q(x) \\
& -w-w+Q(y) \\
& =2 Q(x)+2 Q(y)
\end{aligned}
$$

This shows that $Q$ is a $(\theta, \phi)$ - $\mathbb{A}$-quadratic functional. In (35), taking $\phi$ as the identity mapping on $\mathbb{A}$ and $\theta$ as an involution on $\mathbb{A}$, we get,

$$
Q(u z)=u Q(z) u^{*}
$$

Hence $Q$ becomes an $\mathbb{A}$-quadratic functional.
The following theorem gives a characterization of $\mathbb{A} \otimes_{\gamma} \mathbb{B}$ sesquilinear functional in terms of Jordan $(\theta, \phi)$-derivations on the individual hermitian Banach *-algebras $\mathbb{A}$ and $\mathbb{B}$.

Theorem 3.12 Let $X, Y$ be two vector spaces and $\mathbb{A}, \mathbb{B}$ be two unital hermitian Banach *-algebras with unit elements $e_{1}$ and $e_{2}$ respectively. Let $X$ be a unitary left $\mathbb{A}$ - module and $Y$
be a unitary left $\mathbb{B}$-module. For two additive self mappings $\phi_{1}$ and $\theta_{1}$ on $\mathbb{A}$, let $\Delta_{1}$ be a Jordan $\left(\theta_{1}, \phi_{1}\right)$-derivation on $\mathbb{A}$, and for two additive self mappings $\phi_{2}$ and $\theta_{2}$ on $\mathbb{B}$, let $\Delta_{2}$ be a Jordan $\left(\theta_{2}, \phi_{2}\right)$-derivation on $\mathbb{B}$. If
(i) $\phi_{1}$ and $\phi_{2}$ are identity mappings on $\mathbb{A}$ and $\mathbb{B}$ respectively, (ii) $\theta_{1}$ and $\theta_{2}$ are involutions on $\mathbb{A}$ and $\mathbb{B}$ respectively, and
(iii) $Q_{1}: X \rightarrow \mathbb{A}$ and $Q_{2}: Y \rightarrow \mathbb{B}$ be two mappings satisfying

$$
\begin{aligned}
& Q_{i}\left(u_{i} x_{i}+v_{i} y_{i}\right) \\
& =\phi_{i}\left(u_{i}\right) Q_{i}\left(x_{i}\right) \theta_{i}\left(u_{i}\right)+\phi_{i}\left(u_{i}\right) w_{i} \theta_{i}\left(v_{i}\right)+\phi_{i}\left(v_{i}\right) w_{i} \theta_{i}\left(u_{i}\right) \\
& +\phi_{i}\left(v_{i}\right) Q_{i}\left(y_{i}\right) \theta_{i}\left(v_{i}\right)+\Delta_{i}\left(v_{i} u_{i}\right)-\phi_{i}\left(v_{i}\right) \Delta_{i}\left(u_{i}\right) \\
& -\Delta_{i}\left(u_{i}\right) \theta_{i}\left(v_{i}\right)
\end{aligned}
$$

for ( $i=1,2$ ) and for all $u_{1}, v_{1}, w_{1} \in \mathbb{A}$ with $u_{1}$ invertible, $u_{2}, v_{2}, w_{2} \in \mathbb{B}$ with $u_{2}$ invertible, $x_{1}, y_{1} \in X$ and $x_{2}, y_{2} \in Y$, then there exists an $\mathbb{A} \otimes_{\gamma} \mathbb{B}$-sesquilinear functional on $X \otimes Y$.

The proof follows from Theorem 3.12 and then Theorem 3.1.

## IV. Hyers-Ulam stability of Jordan $(\theta, \phi)$-DERIVATION

In this section, we undertake an analysis of the HyersUlam stability concerning Jordan $(\theta, \phi)$-derivation. In 1940, Ulam [25] introduced the stability problem of functional equations involving group homomorphism.
Let $G_{1}$ be a group and $\left(G_{2}, d\right)$ be a metric group and $\epsilon$ is a positive number. Does there exists a number $\delta>0$, such that if a mapping $f$ from $G_{1}$ to $G_{2}$ satisties the following inequality

$$
d(f(u v), f(u) f(v)) \leq \delta
$$

for each $u, v \in G_{1}$, then there exists a homomorphism $h$ from $G_{1}$ to $G_{2}$ such that

$$
d(f(u), h(u)) \leq \epsilon
$$

for every $u \in G_{1}$ ?.
The homomorphism from $G_{1}$ to $G_{2}$ are stable if this problem has a solution. Hyers [14] gave the same concept of this Ulam's problem for Banach spaces using norm in place of metric. There are many interesting results on stability analysis considering different systems (refer to [4], [17], [18], [22]).

Lemma 4.1 [20] Let $\Delta$ be an additive mapping from a vector space $X$ to a vector space $Y$ such that $\Delta(\lambda u)=\lambda \Delta(u)$ for every $u \in X$ and $\lambda \in \mathbb{C}^{1}$ where $\mathbb{C}^{1}=\{\lambda \in \mathbb{C}:|\lambda|=1\}$, then $\Delta$ is a linear mapping.

Lemma 4.2 [11] Let $X$ be a Banach space and $(G,+)$ be an abelian group. Let $T: G \times G \rightarrow[0, \infty)$ be such that

$$
T(u, v)=2^{-1} \sum_{j=0}^{\infty} 2^{-j} T\left(2^{j} u, 2^{j} v\right) \leq \infty
$$

for each $u, v \in G$. If $\Delta$ is a mapping from $G$ into $X$ such that

$$
\|\Delta(u+v)-\Delta(u)-\Delta(v)\| \leq T(u, v)
$$

for each $u, v \in G$, then there exists a unique additive mapping $h$ from $G$ into $X$ such that

$$
\|\Delta(u)-h(u)\| \leq T(u, u)
$$

for every $u \in G$.
Let $\mathbb{A}$ be a normed algebra and $\mathbb{M}$ be a Banach $\mathbb{A}$ bimodule. The mapping $T: \mathbb{A} \times \mathbb{A} \rightarrow(0, \infty]$ is said to have property $P$ if

$$
\begin{equation*}
T(u, v)=2^{-1} \sum_{j=0}^{\infty} 2^{-j} T\left(2^{j} u, 2^{j} v\right)<\infty \tag{36}
\end{equation*}
$$

for each $u, v \in \mathbb{A}$ (refer to [4]). For two additive self mappings $\theta$ and $\phi$ on $\mathbb{A}$, a mapping $\Delta: \mathbb{A} \rightarrow \mathbb{M}$ is said to have the property $Q-(\theta, \phi)$ if
(i) $\|\Delta(\lambda u+v)-\lambda \Delta(u)-\Delta(v)\| \leq T(u, v)$,
(ii) $\| \Delta\left(u^{2}+v^{2}\right)-\Delta(u) \theta(u)-\phi(u) \Delta(u)-\Delta(v) \theta(v)-$ $\phi(v) \Delta(v) \| \leq T(u, v)$
for each $u, v \in \mathbb{A}$ and every $\lambda \in \mathbb{C}^{1}$.
A mapping $f_{\Delta}: \mathbb{A} \rightarrow \mathbb{M}$ is defined by

$$
\begin{equation*}
f_{\Delta}(u)=\lim _{j \rightarrow \infty} 2^{-j} \Delta\left(2^{j} u\right) \tag{37}
\end{equation*}
$$

for every $u \in \mathbb{A}$ (refer to [4]).
Theorem 4.3 Let $\mathbb{A}$ be a normed algebra and $\mathbb{M}$ be a Banach $\mathbb{A}$-bimodule. Let $\theta$ and $\phi$ be two additive self mappings on $\mathbb{A}$. Suppose that $T$ is a mapping from $\mathbb{A} \times \mathbb{A}$ into $(0, \infty]$ which satisfies the property $P$ and $\Delta$ is a mapping from $\mathbb{A}$ into $\mathbb{M}$ satisfying the property $Q-(\theta, \phi)$. Then there exists a unique Jordan $(\theta, \phi)$-derivation $f_{\Delta}$ such that

$$
\left\|\Delta(u)-f_{\Delta}(u)\right\| \leq T(u, u)
$$

for every $u \in \mathbb{A}$.
Proof: Define $f_{\Delta}$ as in (37). Proceeding similar to Theorem 2.3 of [4], and applying Lemma 4.1 and Lemma 4.2, it can be shown that $f_{\Delta}$ is a linear mapping.

Now we show that $f_{\Delta}$ is Jordan $(\theta, \phi)$-derivation.
Since $\Delta$ satisfies the property $Q-(\theta, \phi)$, replacing $u, v$ by $2^{j} u, 2^{j} v$ in (ii) we get,

$$
\begin{aligned}
& \| \Delta\left(2^{2 j}\left(u^{2}+v^{2}\right)\right)-\Delta\left(2^{j} u\right) \theta\left(2^{j} u\right)-\phi\left(2^{j} u\right) \Delta\left(2^{j} u\right) \\
& -\Delta\left(2^{j} v\right) \theta\left(2^{j} v\right)-\phi\left(2^{j} v\right) \Delta\left(2^{j} v\right) \| \leq T\left(2^{j} u, 2^{j} v\right)
\end{aligned}
$$

Since $\theta$ and $\phi$ are additive mappings, so, $\theta\left(2^{j} u\right)=2^{j} \theta(u)$ and $\phi\left(2^{j} v\right)=2^{j} \phi(v)$. So the above equation becomes

$$
\begin{aligned}
& \| \Delta\left(2^{2 j}\left(u^{2}+v^{2}\right)\right)-2^{j} \Delta\left(2^{j} u\right) \theta(u)-2^{j} \phi(u) \Delta\left(2^{j} u\right) \\
& -2^{j} \Delta\left(2^{j} v\right) \theta(v)-2^{j} \phi(v) \Delta\left(2^{j} v\right) \| \leq T\left(2^{j} u, 2^{j} v\right) .
\end{aligned}
$$

Multiplying the above equation by $2^{-2 j}$ we get,

$$
\begin{aligned}
& \| 2^{-2 j} \Delta\left(2^{2 j}\left(u^{2}+v^{2}\right)\right)-2^{-j} \Delta\left(2^{j} u\right) \theta(u)-2^{-j} \phi(u) \Delta\left(2^{j} u\right) \\
& -2^{-j} \Delta\left(2^{j} v\right) \theta(v)-2^{-j} \phi(v) \Delta\left(2^{j} v\right) \| \leq 2^{-2 j} T\left(2^{j} u, 2^{j} v\right) .
\end{aligned}
$$

Using (37) and taking limit as $j \rightarrow \infty$, from the above equation we get,

$$
\begin{aligned}
f_{\Delta}\left(u^{2}+v^{2}\right) & =f_{\Delta}(u) \theta(u)+\phi(u) f_{\Delta}(u) \\
& +f_{\Delta}(v) \theta(v)+\phi(v) f_{\Delta}(v)
\end{aligned}
$$

Hence $f_{\Delta}$ is a Jordan $(\theta, \phi)$-derivation.
Remark 4.4 In 2017, Dar et al. [9] explored the concept of generalized derivations within rings equipped with an involution, showing their resemblance to mappings that strongly preserve commutativity. In this context, investigation can be done considering generalized $(\theta, \phi)$-derivation in the tensor
product spaces. In [3], Ashraf discussed commutativity of a 2-torsion free prime ring in terms of Jordan left $(\theta, \theta)$ derivation with an application. Investigating the commutativity of the tensor product of prime Banach *-algebras through sesquilinear functionals represents another scope of research in this domain. Moreover, investigation on the characteristics of Lie ideals of a Banach *-algebra $\mathbb{A}$ with the help of $(\theta, \phi)$ -$\mathbb{A}$-quadratic functionals is also an interesting topic for further discussion.

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