

Reactive Power Optimization Based on Adaptive Immune Algorithm

Lin Jikeng Wang Xudong Zheng Weihong

Abstract – The adaptive immune algorithm (AIA) developed from immune algorithm (IA), owns faster computation speed and better convergence than that of GA and other stochastic type algorithms, due to its characteristic of having two layers optimization. The adaptive immune algorithm automatically adjusts the parameters to achieve fast convergence without falling in the local minimum point, according to the value of the distance between the antibodies. It leads to great reduction of the computation time, compared with other methods. The paper proposes to apply adaptive immune algorithm for reactive power optimization. The coding method for the control variables based on decimal system is introduced in detail. The test results of example systems demonstrate that the proposed reactive power optimization based on AIA method has advantages in terms of computation speed and convergence, and has great potential to be applied in practical power systems.

Keyword-- Reactive Power Optimization, Adaptive Immune Algorithm, Computation Speed, Coding method, decimal system

I. INTRODUCTION

THE purpose of reactive power optimization is to minimize the system loss or other optimum performance indices, subjecting to security and operation constraints. There are many solutions for it, such as linear programming, nonlinear programming, secondary programming, sensitive analysis, and mixed integer planning [1-4]. These methods are generally based on some presumptions and have some defects. With the development of artificial intelligent optimization technologies, the stochastic methods of global searching and optimization have attracted many interests, and have been applied in power system reactive power optimization.

In [5-7], methods based on GA, Tabu and fuzzy control, expert system, and neural network, are proposed with demonstration of good results.

¹The immune algorithm (IA), based on the mechanism of the amalgamation between antigen and antibody in biologic immune system, has been focused recently. IA has a faster computation speed and better convergence than that of GA and other stochastic type algorithms [8], due to its

characteristic of having two layers optimization. IA has been applied to many fields in power system, such as optimal flow, distribution network planning, generator maintenance [9,10].

In this paper, AIA (Adaptive immune algorithm) [11] is applied to reactive power optimization of power system. The test results based on IEEE-14 system, IEEE-118 system and a practical system indicate that the reactive optimization based on the AIA presents remarkable performance in terms of computation speed and convergence rate, compared with those methods based on GA, IA.

II. AIA

The selection rate α , extension radius r , and mutation radius R are the key parameters for the IA and are fixed [10]. In optimization processing based on IA, the bigger α , r and R are, the higher the diversity of the colony is. However, the evolution of antibodies might be very slow. On the contrary, if the parameters are smaller, the algorithm can rapidly converge to local optimum, with the diversity of the colony significant decrease. Therefore, some inconsistency exists between the convergence rate and colony diversity for the IA.

If α , r and R are automatically adjusted according to the diversity of the antibodies, the algorithm might have fast convergence speed. If the diversity of the antibodies is defined as the average distance among antibodies, the smaller the distance is, the more similar the antibodies are, and the lower the colony diversity is, and vice versa. With α , r and R being adjusted according to the diversity of the antibodies, the AIA gains good performance. Suppose that the antibody colony of the k th generation B_k contains m antibodies— $v_i, i = 1, 2, \dots, m$, the average distance among these antibodies is calculated as:

$$d^{(k)} = \frac{1}{m(m-1)} \sum_{i=1}^m \sum_{j=1}^m d(v_i^{(k)}, v_j^{(k)}), \quad i \neq j \quad (1)$$

The diversity for antibody colony B_k is defined as:

$$D^{(k)} = \begin{cases} d^{(k)}/d_{\max} & d^{(k)} < d_{\max} \\ 1 & d^{(k)} \geq d_{\max} \end{cases} \quad (2)$$

Where d_{\max} is constant.

The parameter α , r and R of the k th generation are automatically adjusted using the following equations:

$$\alpha^{(k)} = \alpha_0 + \eta_\alpha D^{(k)} \quad (3)$$

$$r^{(k)} = r_0 + \eta_r (1 - D^{(k)}) \quad (4)$$

¹ Lin Jikeng (Ph.D) works as associated professor at the School of Electrical Power and Automation, Tianjin University, Tianjin, P. R. China. E-mail:mejclin@126.com.

Wang Xudong is a master degree candidate of Tianjin University, Tianjin, P. R. China

Zheng Weihong (B. D) works as a senior engineering at the Dispatch Center of Tianjin Electric Power Corporation, Tianjin, P.R.China

$$R^{(k)} = R_0 + \eta_R (1 - D^{(k)}) \quad (5)$$

where $\alpha^{(k)}$, $r^{(k)}$, and $R^{(k)}$ are selection rate, extension radius and mutation radius of the k th generation, respectively; α_0 , r_0 , and R_0 are the initial values of the related parameters respectively; η_α , η_r , and η_R are the adjusting ranges of the related parameters respectively. Then, the AIA process is as follows:

(1) Initialization: Let $k=0$; randomly generate n real coding antibodies to form the initial antibody colony A_k ; calculate the evaluation of each antibody, which is the reciprocal of the objective function value.

(2) Calculate $\alpha^{(k)}$, $r^{(k)}$, and $R^{(k)}$ with equations (1-4).

(3) Selection operation: Select integer $(n * \alpha^k) = m$ antibodies whose evaluations are the m highest in colony A_k to form antibody colony B_k .

(4) Extension operation: the neighborhood of each antibody in antibody colony B_k is:

$$SN(v_i) = \{v \mid \|v - v_i\| \leq r^k, v \in \Omega, r^k > 0, v_i \in B_k\},$$

where Ω is the feasible solution space, $\|\bullet\|$ is the Euclid norm, r^k is extension radius; Each antibody in the antibody colony B_k generates some new antibodies randomly in its neighborhood and all the new antibodies add to the antibody colony randomly and the totalation

in the B_k to form the new antibody colony— C_k , in which the number of the antibodies is n_1 . The roulette method is applied to determine the number of new antibodies generated by each antibody in colony B_k .

(5) Mutation operation: The n_1 -integer $(n_1 * \alpha^k)$ antibodies whose evaluations are the n_1 -integer $(n_1 * \alpha^k)$ worst in colony C_k will mutate into the antibodies in the larger area as following:

$$MN(v_j) = \{v \mid \|v - v_j\| \leq R^k, v \in \Omega, R^k > 0\}, \text{ and}$$

$R^k \gg r^k$, the mutated antibodies and the rest in colony C_k form the antibody colony D_k .

(6) Replacement operation: the L antibodies whose evaluations are the L worst in colony D_k are replaced by the antibodies generated randomly to make up the antibody colony E_k .

(7) Retaining operation: the L antibodies whose evaluations belong to the L worst in colony E_k are replaced by L antibodies whose evaluations belong to the L best in colony A_k to form the next generation A_{k+1} . If the convergence criterion is satisfied, the procedure is over; otherwise, let $k=k+1$, return to step (2).

The evolutionary procedure of colony by AIA is shown as fig. 1:

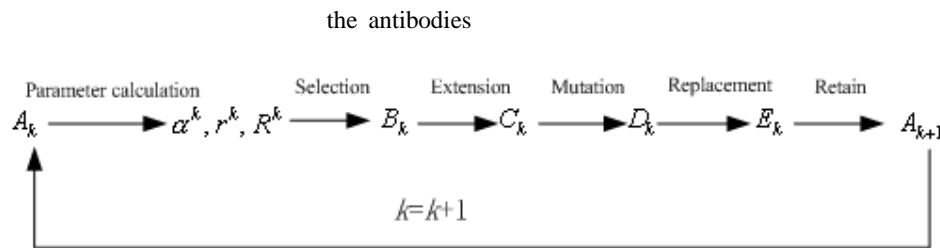


Fig.1: The procedure of the evolution for the AIA

It can be seen that in the above algorithm, the $\alpha^{(k)}$, $r^{(k)}$ and $R^{(k)}$ are adjusted according to the distance among the antibodies in the current colony, and the compromise between the rapid convergence and high diversity of colony is achieved, so that it can prevent converging to local optimum and can have great improvement on computation speed.

III. THE MATHEMATIC MODEL FOR REACTIVE POWER OPTIMIZATION

The mathematic model for reactive power optimization is as follows:

(1) Objective function

The objective function of reactive power optimization is:

$$\begin{aligned} & \text{Min}_{(T_K, K \in N_T, Q_{G,i}, i \in N_G, V_i, i \in N_{PV})} F = P_L + \\ & \lambda_u \sum \left(\frac{V_i - V_i^{\text{lim}}}{V_{i,\text{max}} - V_{i,\text{min}}} \right)^2 + \lambda_Q \sum \left(\frac{Q_{G,i} - Q_{G,i}^{\text{lim}}}{Q_{G,i,\text{max}} - Q_{G,i,\text{min}}} \right)^2 \end{aligned}$$

in which

$$V_i^{\text{lim}} = \begin{cases} V_{i,\text{max}} & V_i \geq V_{i,\text{max}} \\ V_{i,\text{min}} & V_i \leq V_{i,\text{min}} \end{cases}$$

$$Q_{G,i}^{\text{lim}} = \begin{cases} Q_{G,i,\text{max}} & Q_{G,i} \geq Q_{G,i,\text{max}} \\ Q_{G,i,\text{min}} & Q_{G,i} \leq Q_{G,i,\text{min}} \end{cases} \quad (6)$$

where P_L is the branch-loss; V_i , $V_{i,\text{min}}$, and $V_{i,\text{max}}$ are the voltage of PQ bus, and its lower limit and upper limit, respectively; $Q_{G,i}$, $Q_{G,i,\text{min}}$, and $Q_{G,i,\text{max}}$ are the input reactive power of PV bus, and its lower limit

and the upper limit, respectively; $T_k (K \in N_T)$ is the tap position of transformer, and N_T is the total number of transformers; $Q_{C,i} (i \in N_C)$ is the compensation capacity of capacitor (or reactor), and N_C is the total number of capacitors (or reactors); $V_i (i \in N_{PV})$ is the generator terminal voltage of PV bus, and N_{PV} is the total number of PV buses.

In equation (6), the second and third parts are penalties on voltage and generator reactive power output limit violation respectively, and λ_u , λ_Q are the penalty coefficients.

(2) The constraint conditions

$$P_{G_i} = P_{D_i} + \sum_{j=1}^{j=n} V_i V_j (G_{ij} \cos \theta_{ij} + B_{ij} \sin \theta_{ij}) \quad (7)$$

$$Q_{G_i} = Q_{D_i} + \sum_{j=1}^{j=n} V_i V_j (G_{ij} \sin \theta_{ij} - B_{ij} \cos \theta_{ij}) \quad (8)$$

$$i \in \{1, 2, \dots, n\}$$

$$Q_{G_i}^{\min} \leq Q_{G_i} \leq Q_{G_i}^{\max} \quad i \in N_{PV} \quad (9)$$

$$V_i^{\min} \leq V_i \leq V_i^{\max} \quad i \in n \quad (10)$$

$$T_k^{\min} \leq T_k \leq T_k^{\max} \quad k \in N_T \quad (11)$$

$$Q_{C_i}^{\min} \leq Q_{C_i} \leq Q_{C_i}^{\max} \quad i \in N_C \quad (12)$$

where, P_{G_i} and Q_{G_i} are the input real power and reactive power at i th bus, respectively; P_{D_i} and Q_{D_i} are the loads of real power and reactive power at i th bus, respectively; n is the total buses number; The voltages of PV buses, the compensated amounts of compensators (or reactors), and the tap positions of transformers are the control variables. The rest variables in equations (6)-(12) are state variables.

IV. THE REACTIVE POWER OPTIMIZATION BASED ON AIA

Since the control variables of reactive power optimization are the mixture of continuous variables and discrete variables, an efficient coding method for them must be designed, which will speedup the immune evolutionary procedure. The decimal coding method is applied for it.

A. The Coding Method

The configuration of antibody is given by

$$X = [\overline{V}_G \mid \overline{Q}_C \mid \overline{T}] \quad (13)$$

where, $\overline{V}_G = \{\overline{V}_{G_1}, \dots, \overline{V}_{G_n}\}$, $\overline{Q}_C = \{\overline{Q}_{C_1}, \dots, \overline{Q}_{C_M}\}$, $\overline{T} = \{\overline{T}_1, \dots, \overline{T}_S\}$; X is the coding of antibody; \overline{V}_G , \overline{Q}_C and \overline{T} are the terminal voltage vector of generators, the vector of reactive compensations, and the tap position vector of transformers, respectively; \overline{V}_{G_i} , \overline{Q}_{C_i} and \overline{T}_i

are components of relevant control vectors. The coding method for each control variable is as follows.

(1). Generator terminal voltage

Assume the number of PV generators is N . The adjustable range of i th generator terminal voltage, which is expressed as $V_{G_i}^{\min} \leq V_{G_i} \leq V_{G_i}^{\max}$ usually having limits between 1.1 and 0.9, is divided into w units (i.e. $w=200$, each unit is about 0.001, which definitely satisfies the precision requirement.). Variable

$GV_{i,k} (1 \leq i \leq N, 1 \leq k \leq w, i, k$ is an integer), the generation terminal voltage of PV buses, is expressed as

$$GV_{i,k} = V_{G_i}^{\min} + \frac{V_{G_i}^{\max} - V_{G_i}^{\min}}{w} \times k$$

which relates the voltage value of all generators with the integer k . Then the coding value of \overline{V}_{G_i} in equation (13) could be obtained as

$$\overline{V}_{G_i} = k$$

and the relevant voltage could be obtained by decoding through the formula $V_{G_i} = GV_{i,k}$.

(2). Compensation capacity of compensator

Suppose that the number of buses with adjustable compensator is M , the group number of the i th compensation device is N , and the compensation capacity of each group is Q^c . The variable

$CB_{i,t} (1 \leq i \leq M, 1 \leq t \leq N, i$ and t are integer), which is the compensation value of the i th reactive compensation devices having t group capacity banks being put on, is expressed as $CB_{i,t} = CB_{i,t-1} + Q^c$. Then the coding value

\overline{Q}_{C_i} in equation (13) is obtained as $\overline{Q}_{C_i} = t$, and the relevant compensation capacity could be obtained by

decoding through the equation $Q_{C_i} = CB_{i,t}$.

(3). The tap position of transformer.

Suppose that the number of transformers is S , and the position number for the tap of the i th transformer is L , and the difference between two successive transformer tap positions (tap step) is Δk . The variable

$TB_{i,j} (1 \leq i \leq S, 1 \leq j \leq L)$, which is the ratio of the tap position of transformers, is expressed as

$TB_{i,j} = TB_{i,j-1} + \Delta k$. Then the coding value of \overline{T}_i in

equation (13) is obtained as $\overline{T}_i = j$. The ratio of the i th transformer could be obtained by decoding through the formula $T_i = TB_{i,j}$.

B. The Procedure For The Reactive Power Optimization Based On AIA

The procedure for the reactive power optimization based on AIA is as follows:

(1) Let the initial values of selection rate α , extension radius r and mutation radius R be: α_0 , r_0 and R_0 respectively, and the relevant adjusting range be η_α , η_r and η_R respectively. Randomly generate n antibodies X of integer coding, whose configuration is as formula (13),

to constitute antibody colony A_k , $k=0$.

(2) Perform the power flow calculation for each of the relevant decoding values of the antibody in colony A_k , and discard the antibody whose decoding value could not satisfy the power flow equation; then calculate the value of objective function by equation (6), and achieve the evaluation for each antibody preserved.

(3) Calculate $\alpha^{(k)}$, $r^{(k)}$ and $R^{(k)}$ using equations (1-4).

(4) Do the Selection operation, Extension operation, Mutation operation and Replacement operation just like that introduced at part 2 of this paper one after the other; if the convergence criterion is met, then the procedure ends; otherwise $k=k+1$, return to (2) to start the next generation evolution.

V. SIMULATION EXAMPLES

The reactive power optimization based on AIA is applied to the IEEE14, IEEE118 system and a practical system, and the results are compared with those obtained based on GA, IA. The initial parameters for the above method are nearly similar.

For IEEE14 system, the colony scale is 100, and the optimization results are shown in table 1, where branch-loss and computation time are the average value of results of many time calculations. The fitting value curves are presented at figure 2.

TABLE 1: THE OPTIMIZATION RESULTS FOR THE IEEE14 SYSTEM

Algorithms	Optimized branch-loss(MW)	Iterative times	Calculation time
GA	13.502	30	58s
IA	13.390	30	61s
AIA	12.308	30	3.5s

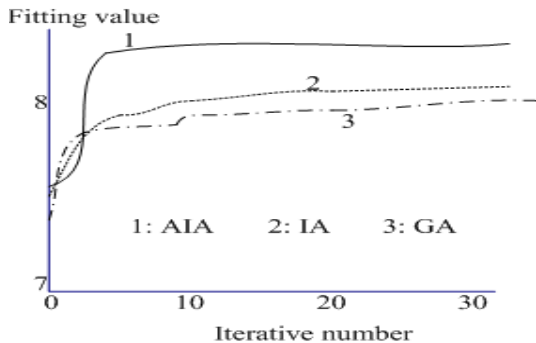


Fig.2: The curve of the fitting value for IEEE14 system

For the IEEE118 system, the colony scale is 150, and the optimization results are shown in table 2, and the curves of fitting value are shown in figure 3.

TABLE 2: THE OPTIMIZATION RESULTS FOR IEEE118 SYSTEM

Algorithm ms	Optimized branch-loss(MW)	Iterative times	Calculation time
GA	122.10	560	761s

IA	121.65	450	604s
AIA	115.75	170	268s

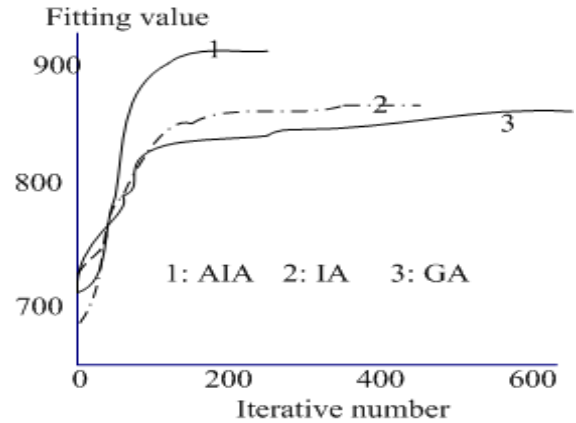


Fig.3: The curves of the fitting value for each method for IEEE118 system

It could be seen clearly that from the table 1-2, the reactive power optimization method based on AIA proposed has superiority in the aspects of the computation speed and precision, compared to the other methods. The superiority is more obvious with the system scale enlarging. Fig. 2 and 3 also clearly indicate that the fitting value of AIA quickly surpasses those of other two methods and lead to more reasonable evaluation, since the bigger the fitting value, the more reasonable the system evaluation.

The reactive power optimization method based on AIA is also tested on a practical system in China. The system is composed of: 226 buses, 293 branches, 20 voltage adjustable generators, 77 tap adjustable transformers, and 46 capacitors. The total load of system is $P_l = 360.13 MW$, $Q_l = 43.33 MW$. The simulation result is shown in table 3:

TABLE3: THE RESULTS FOR A PRACTICAL SYSTEM

State	loss(MW)	Average voltage	Violation buses
Before	22.395	0.942	147
After	20.394	1.047	0

It could be seen that from the Tab.3, that the method of reactive power optimization based on AIA proposed is very effective even for a practice system.

VI. CONCLUSION

In this paper, the AIA is proposed for reactive power optimization. AIA automatically adjusts all parameters such as selecting rate α , cloning radius r and mutation radius R , according to the distance measure between antibody and antibody, and lead to greatly reduce computation time. The AIA based reactive power optimization has remarkable superiority in computation speed and convergence speed, compared to those methods based on GA and IA. It has great potential for practical implementations.

VII. REFERENCES

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