A Relative Deviation Detection for Time Series Data Based on Equality

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Abstract—Outlier detection is an important problem in various fields. A lot of algorithms have been proposed, meanwhile a lot of definitions. Unsatisfying point is that definitions seem vague, which makes the problem an ad hoc one. We analyze the nature of outliers, and give a supplementary definition. Based on it, we develop an efficient relative deviation degree (RDD) algorithm to identify outliers, which converts outlier problem to pattern and degree problem. We give two type of application in time series data – line type and curve type and introduce a longest k-turn subsequence problem. We treat the structure of pattern as a kind of order, which is a novel view. We also present experimental results on synthetic and real datasets showing the efficiency of our technique.

Index Terms—Curve, Outlier, Pattern, Relative Deviation Degree.

I. INTRODUCTION

Outlier problem could be traced to its origin in the middle of the eighteenth century ([21] p27), when the main discussion is about justification to reject or retain an observation. From then, most methods in the early work have been developed in the field of statistics. As the classic LS estimator is poor to outliers, different robust estimators were presented in turn. From L1 estimator [8] to M-estimators [10], then to S-estimators [18], robust estimators have good performance to resist outliers. But as robust estimators are also based on statistical models, which is that the statistician always has a statistical model in mind (explicitly or implicitly) when analyzing data, e.g., a model based on a normal distribution or some other idealized parametric model such as an exponential distribution [15], and in reality, the distribution of a data set is not always curtain, these methods have their limits. Besides statistical methods, many other kinds of algorithms have been proposed. From distance-based [6] to density-based [13]; from deviation-based [2][9] to neural network [11][16] and genetic algorithm [17], etc. Meanwhile a lot of ad hoc definitions are presented, and we are faced to the problem as Jagadish [9] stated that each of them gives a different answer, and none of them is conceptually satisfying. It is undoubtedly that we should make clear the definition of an outlier. But unfortunately, our general basic definition seems to be a descriptive one rather than an exact one. Let's

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An outlier is an observation that deviates so much from other observations as to arouse suspicions that it was generated by a different mechanism.

And a further definition from Barnett and Lewis [21].

An observation (or subset of observations) which appears to be inconsistent with the remainder of that set of data.

Barnett and Lewis stated that "the phrase 'appears to be inconsistent' is crucial. It is a matter of subjective judgement on the part of the observer whether or not some observation (or subset of observations) is picked out for scrutiny."

Obviously, we can't get a certain answer on these definitions. Some additive definition should be given. This paper originates from this problem and aims to detect outlier patches in time series data. We show a neglected hidden feature of outlier problem - pattern, which may be used to describe outlier problem in a more general view. Based on it, we present a simple relative deviation detection algorithm, which is equal to a simple robust regression. We then develop it to a general form and apply it to curve type. By giving a new concept "turn", we extend what called longest increasing subsequence problem [3] to longest turn subsequence problem. Combining it with our general relative deviation detection algorithm, we identify outliers in curve type successfully, which is similar to the mechanism of human beings. Our solution is simple and fast, besides, is clear in definition.

We give related works in Section 2 and discuss the essence of outlier in Section 3 and present an additive definition, followed by our RDD algorithm in Section 4. In section 5, we present longest turn subsequence problem and give out outlier detection algorithm to curve type data. We will give complexity and experiments in section 6, conclusion and future work are in section 7.

II. RELATED WORKS

Identifying multiple outliers in linear models is not as simple as detecting a single outlier, owing to masking and swamping problems [19]. Multiple outliers, especially those which occur closely in time, often have severe masking effects that can render the usual outlier detection methods ineffective [1]. Ana Justel et al. [1] presented adaptive Gibbs sampling, which overcomes the inefficiency of standard Gibbs sampling to detect outlier patches. But among 200 cases, it failed in 13 cases. It seems not escaped from what Jagadish et al. evaluated the statistical methods, especially, "in the case of time series data, the situation is more murky." [9] Jagadish et al. then proposed a technique for mining deviants in time series. Their proposal is to use the well

recognized information theoretic principle of representation length. Though their algorithm is of beautiful form, but two parameters, the total storage and the number of deviants, should be assigned in advance, which makes the definition of deviant, hence outlier, a dependent one.

In [7], Keogh et al. seemed treating outliers as individually surprising datapoints, and instead of processing outliers, they were interested in finding surprising patterns, i.e., combinations of datapoints whose structure and frequency somehow defies our expectations. Their novel definition about pattern surprising is that if the frequency of its occurrence differs substantially from that expected by chance, given some previously seen data. They believe the definition of surprise may be impossible to elicit from a domain expert and feel their new definition to be of advantage of not requiring an explicit definition of surprise. The use of "frequency" is also similar to human beings' method, and forwarding one step, we could discover the essence of outlier. But neglecting characters of structure also brings shortage, which make the algorithm not so "general". We may see this point easily from the random walk data experiment done in this paper. Furthermore, "TARZAN" algorithm has a threshold c that "can be identified by gathering statistics about the distribution of the scores and/or assuming the distribution of the scores to be normal, which indicates that finding surprising patterns in essence is also based on a kind of "deviation degree", which, holds true in outlier detection, motivates our new RDD (relative deviation degree) algorithm.

III. ESSENCE OF OUTLIER

In their first edition ([20] p1), Barnett and Lewis quoted from Ferguson, "It is rather because..., that the loss in the accuracy of the experiment caused by throwing away a couple of good values is small compared to the loss caused by keeping even one bad value. The problem, then, is to introduce some degree of objectivity into the rejection of the outlying observations". Outlier problem tends to be treated as an uncertain problem but measured by an objective quantity. After giving the definition of outlier ([21] p7), they drew a conclusion that "more fundamentally, the concept of an outlier must be viewed in relative terms". Though this conclusion was made in statistical field, it could be reasonably extended to other fields. And the attitude to relativity leads to the distinction of our approach from all the others. Barnett and Lewis seem to seek "a more appropriate model", and Keogh et al. gave an "absolute" relative definition to "surprise". In contrast, we accept and emphasize relativity, thus develop a supplementary definition.

Definition 1: An outlier is an observation with a degree greater than a threshold in comparison with other observations referred to or associated with a specified pattern.

In this way, outlier problem changes to pattern problem. Here we distinguish two kinds of patterns to make clear the definition of outlier. One is known and of certainty, the other is unknown and of some certainty or uncertainty. The latter is like the classic "black swan" problem [5, 12], if and only if a



Fig. 2: Regression line for S1

black swan is discovered, it won't be an outlier then. To the former, outlier problem is "yes or no" problem; while to the latter, it is probability problem. Since even to former, we can measure outliers by a degree away from normal ones, we may generalize outlier problem to pattern and degree problem. That is, when we talk about outlier, we can't separate it from a specified pattern and a deviant degree. In application, the accuracy of outlier degree is up to the accuracy of expression of the chosen patterns.

IV. RELATIVE DEVIATION DEGREE (RDD)

We present our RDD algorithm by a simple example, then generalize it.

Problem 1: Given a time series data *S1* as Fig. 1, suppose data match linear model, find out outliers.

SI = (3.1, 2.9, 2.85, 3, 3.05, 2.9, 3.2, 5.2, 8.5, 5.4, 5.3, 5.1, 3.1, 3.05, 3, 2.99, 3, 3.02, 3.2)

By classic LS regression, we get a line y=3.79-0.001x; and by robust LTS regression, line y=2.907+0.007x, as shown in Fig. 2. Now based on the above definition, we present our novelty RDD algorithm.

Given a time series data $S = d_1 d_2 \dots d_N$, denote point (i,d_i) by p_i , and $\angle p_i p_i p_k$ by $\angle jik$.

Relative Deviant Degree Algorithm 1



for(*i*, *j* from 1 to *N*,
$$j \neq i$$
)
 $w_{ij} = X_i \times Y_j$
 $RDD_k = -In \frac{\sum\limits_{i,j=1}^{n} (s_k^{ij} \times w_{ij})}{\sum\limits_{i,j=1}^{n} w_{ij}} \times \frac{\sum\limits_{i,j=1}^{n} (o_k^{ij} \times w_{ij})}{\sum\limits_{i,j=1}^{n} w_{ij}}$

if $RDD_k > c$ then output k

Notes

- Similarity function is used to evaluate the similar degree of point *k* related to the system of *i* and *j*, which is the pattern "line" in this case.
- Offset function calculates the real distance between *k* and system of *i* and *j*.
- *w_{ij}* is the weight of system of *ij*, denotes the relative effective degree.
- Relative deviant degree combines two aspects of views from similarity and real distance.
- *c* is the threshold, can be identified by the same way as [7].

By our algorithm, to problem 1 we get *RDD* measure to each element in Table 1. Points at 8, 9, 10, 11 and 12 are identified as outliers.

Though RDD algorithm has commons in form with robust regression, our algorithm differs from robust one at the point that we approach from the inside structure of the pattern and stress on the whole effect, thus with more balance. Note that RDD algorithm is same as robust regression, can be possible with a highest breakdown point (50%). Now we modify our algorithm 1 to a general form. First, we introduce definition of view V.

Definition 2: Given a time series data *S*, a sub-series of *S* is also a time series where each element of it is an element of *S*. We denote $e \prec S$ when *e* is a sub-series of *S*.

Definition 3: A view of *S*, V_{α} , is a set of sub-series of *S* of same length α , that is $V_{\alpha} = \{ e | e \prec S, |e| = \alpha \}$

Algorithm 1'

	1
Input: time series data S	maximum/minin
Output: outliers of S	
• Let V_a be an evaluating view, $e \in V_a$.	We then intro
• Given a similarity function sim: $S \times S^a \rightarrow [0,1]$, denoted	subsequence pro
by sim_k^e	
• Given an offset function off: $S \times S^a \rightarrow \mathbb{R}^+_{a}$, denoted	Problem 3: Giv
by Off_k^e	with k turns, a
• According to the dimension of V_a , define different	subsequence hav
weight w_e and RDD_k by sim and off functions.	
for any element e in V_a	We give a simpl
calculate w_e	and following al
calculate RDD_k	
if $RDD_k > c$ then output k	Algorithm 2:
	denote <i>best[i][t</i>
	point <i>i</i> with <i>t</i> tur
	P[i][t], predece
T 7 O	1

V. CURVE-TYPE OUTLIER

In this section, we extend RDD algorithm to curve type. In real application, curve-pattern data are general. So we give following problem.

Table 1: RDD values for sequence

Table 1. RDD values for sequence 51						
Position	1	2	3	4	5	
RDD	0.001	0.025	0.061	0.018	0.031	
Position	6	7	8	9	10	
RDD	0.067	0.138	17.956	27.693	23.879	
Position	11	12	13	14	15	
RDD	18.482	14.609	0.021	0.003	0.005	
Position	16	17	18	19		
RDD	0.006	0.008	0.010	0.002		



Fig. 3: Example curve-type sequence

Problem 2:

Given a sequence *S* of length *N*, $\{d_1, d_2, \dots, d_N\}$, which matches pattern "curve", find outliers.

An example is shown in Fig. 3.

Though we might divide curve into several lines, it is not a satisfactory solution. By analysis to character of curves, we find that each smooth curve can be expressed by several ordered sets. We thus develop a dynamic programming algorithm to detect the order of curve type data, which can be traced to the problem of longest increasing subsequence. We first give definitions, then present our algorithm.

Definition 4: Given a smooth curve, except for boundary points, each extremum point is called a "turn point"; the number of extremum points is called turns. We denote maximum point by sign "+", and minimum point by sign "—". If a sequence *S* has *t* turns and the 1st one is a maximum/minimum points, then it is denoted by [+/-, t].

We then introduce a new problem, longest *k*-turn subsequence problem.

Problem 3: Given a curve-pattern series data S of length N, with k turns, and a specified view, searching a longest subsequence having k turns.

We give a simple specified view, passing a specified point *i*, and following algorithm.

denote best[i][t], the longest subsequence from point 1 to point *i* with *t* turns; P[i][t], predecessor point of *i* in the longest *t*-turn subsequence best[i][t].

Input: time series data *S* Output: the longest *t*-turn subsequence starting from point 1.



Algorithm 3 return the longest *t*-turn subsequence passing any point *i*.

Algorithm 3:

Input: time series data S

Output: the longest *t*-turn subsequence passing point *i*.

- Dividing the whole series data into two parts, $S1: d_i$, d_{i-1}, \dots, d_1 ; and $S2: d_i, d_{i+1}, d_{i+2}, \dots, d_N$.
- Work out *best1[][t]* in *S1* and *best2[][t]* in *S2* on each *t*
- Combine them to identify the longest *best[][T]*

Now we give solution to problem 2.

Algorithm 4:

Input: time series data *S* Output: outliers of *S*

- Specify a curve pattern [*sign*, *t*]
- similarity function denoted by simⁱ_k, offset function denoted by offⁱ_k
- [1] To any d_i , work out a subset $P(S)_i$ with t turns, sign and maximum length by algorithm 3.

[2] To $d_k \in P(S)_i$, $sim_k^i = 1$, $Off_k^i = 0$;

$$d_k \notin P(S)_i$$
, $sim_k^i = 0$, calculate off_k^i by interpolation.

[3] Calculate RDD_k by algorithm 1'

with weight $w_i = \sum_{k=1}^{N} sim_k^i$ and $RDD_k = -ln \frac{\sum_{i=1}^{N} (sim_k^i \times w_i)}{\sum_{i=1}^{N} w_i} \times \frac{\sum_{i=1}^{N} (off_k^i \times w_i)}{\sum_{i=1}^{N} w_i}$ [4] if $RDD_k > c$ then output k

Note: To any series sets, since outliers deviate from others, it may disturb the order of sets. So we can use a kind or kinds of order to descript the pattern. Definition 2 and corresponding algorithms hold true to any kinds of order.

VI. COMPLEXITY AND EXPERIMENTS

To Algorithm 1, for each point should be evaluated by any other two ones, time consumption is $O(N^3)$ when number of data is *N*. But since each evaluating pairs are isolated, this algorithm is of parallelity, which makes it possible to be run in O(N). Correspondingly, algorithm 1' can be done in



Fig. 5: RDD values for synthetic sequences of Fig.4

 $O(N^{\alpha+1})$ time ($\alpha > 0$), and in condition of parallelity, it decreases to O(N).

Robust simple regression, e.g. LTS, requires sorting of the squared residuals, which takes O(NlogN) operations [14]. Considering operations needed by whole subsamples in data, (2)

$$\binom{2}{N}$$
, total operations is $O(N^3 log N)$.

Algorithm 2 can be done in $O(N^2T)$ time. And for the longest increasing subsequence problem is known to be solvable in time $O(N \log N)$ [3], we may improve algorithm 2 to a quicker state in some way.

Algorithm 4 can be done in $O(N^3T)$ time and in $O(N^2T)$ time in parallelity.

Following experiments are based on algorithm 4. Original sine data are got from function y=sin(x/47*2*PI); parabola data is from $y=(x-24)^2$. *x* is an integer in [0,47]. We first observe data without outliers (Fig.4) and then with outliers (Fig. 6).

When there are no outliers in data series, we can get *RDD* as Fig. 5, no point is identified as outlier:

When outlier patches are introduced, size +1 to the x index 7, 8, 9, 10 in sine data and size +100 to the x index from 37 to 41 in parabola data, we get corresponding *RDD* shown in Fig. 6. In A, points 8, 9, 10, 11 are identified; in B, angle order is adopted, and points 38, 39, 40, 41, 42 are detected rightly.

Next, we give results to two real time series data, which are one day data, measured every 30 minutes from 0 to 24 hours. One is CO2 flux data, the other is h-sat data, both achieved from Yucheng station, China in MODIS project by National Institute for Environmental Studies, Japan.

In A of Fig. 7, besides apparent points like 9, 11, 12, some inner points like 22 and 27 are detected successfully; in B, two continuous outliers 45 and 46 are identified.

Finally, we give a comparison to paper [9], where Jagadish et al presented an elegant algorithm for mining deviants. Their algorithm was thought fast and optimal. The complexity of their algorithm is $O(N^2 B_m k_m^2)$, where N is the length of sequence, B_m is a parameter chosen for buckets, and k_m a parameter chosen for number of deviants. Here we only discuss M1 data set, which is a time series showing the



Fig. 6: Synthetic sequences with outliers and corresponding RDD values



Fig. 7: Real sequences with outliers and corresponding RDD values

total number of hours worked by people of a given age in a year. Parameters are: N = 100, $B_m = 40$, $k_m = 10$. Their result is the deviant clusters searched with size between 1 and 10 points.

Clusters *c1*, *c2*, *c3* labeled in Fig. 10 were identified. In detail, *c1* contains points 23 to 30; *c2* contains points between 48 and 51; and *c3* at point 90. Meanwhile, our result is listed in Table 2. *RDD* values of points not listed are all less than 2.9, among them most are less than 0.2, the outlier with minimum *RDD* is point 40. From Table 2, we can find that not only the three clusters are detected, but also an outlier at c4 (40). Note that our algorithm is $O(N^3T)$ with T = 1 and not considering parellelity. Suppose k_m is ten percent of N, which is reasonable according to [9]. When $N \ge 100$, their algorithm takes time more than $O(N^3B_m)$.

Both algorithms need to specify parameters in advance. But our algorithm only need one parameter concerned with pattern, and might be removed by following study. What is more, from respective theoretic foundation perspective, both are optimal.

VII. CONCLUSION AND FUTURE WORK

This work makes three new contributions. First, we have presented a supplementary definition to outlier, which lets us discuss outliers without vagueness. Second, we proposed efficient algorithms — RDD for identification of deviant points. Third, we present "longest k-turn subsequence" problem and convert outlier problem to order-searching problem.

Experiments show the effectiveness of RDD algorithm. By comparison to statistical method and a deviation-based algorithm, we find our algorithm is faster and more accurate.

General speaking, our approach is based on pattern, and pattern is treated as relations between its elements, something what called structure. A relative mechanism is introduced to process this kind of relation, so in essence we build our method on equality of elements. Pattern can be divided into two classes: analytical pattern and non-analytical pattern. If a pattern can be expressed analytically, that is, relation among internal elements can be expressed in some form, we can use RDD formulation to extract outliers from normal sets. Non-analytical pattern will be discussed in another paper.



Fig. 8 (M1 data)

point	23	24	25	26	27
RDD	6182.3	22.2	3743.5	43.8	2983.7
point	28	29	30	31	32
RDD	3801.8	66.6	2932.1	8641.6	92.2
point	40	41	48	49	90
RDD	1092.6	170.4	23425.0	10246.0	7208.4

Table 2: Selected points and their RDD values for M1 data

Above all, pattern itself can be treated as a set, a non-disturbed set. If there is a set which includes abnormal elements, these elements may disturb the orders held by a pattern. To the curve pattern, we will study adapted algorithm in our future work so that we don't need to specify a parameter in advance.

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