

# A Novel Coupled-Inductor Switched-Capacitor Inverter for High-Gain Boost DC-AC Conversion

Yuen-Haw Chang and Jyun-Jia Liao

**Abstract**—A novel coupled-inductor switched-capacitor inverter (CISCI) is proposed by combining a non-overlapping circuit and sinusoidal pulse-width-modulation (SPWM) controller for the high-gain boost DC-AC conversion and closed-loop regulation. The power part is composed of two cascaded sub-circuits, including: (i) a booster with coupled-inductor and switched-capacitor (one coupled-inductor, 2 pumping capacitor, and one switch controlled by a non-overlapping circuit), and (ii) a half-bridge DC-link inverter (2 capacitors and 2 switches controlled by SPWM), so as to obtain an AC range:  $+\frac{(2+n+nD)}{2(1-D)}V_s \sim -\frac{(2+n+nD)}{2(1-D)}V_s$ , where  $D$  is the duty cycle and  $n$  is the turn ratio of coupled-inductor. Practically, the maximum output voltage can reach 12.5 times voltage of source  $V_s$  while  $D=0.5$ ,  $n=8$ . Here, the SPWM is employed to enhance regulation capability for the different output amplitude and frequency, as well as robustness to source/loading variation. Finally, the closed-loop CISCI is designed and simulated by OrCAD SPICE for some cases: steady-state and dynamic responses. All results are illustrated to show the efficacy of the proposed scheme.

**Index Terms**—coupled-inductor switched-capacitor inverter, high-gain boost, DC-AC conversion, sinusoidal pulse-width-modulation.

## I. INTRODUCTION

Recently years, due to the popularity of mobile devices, e.g. digital camera, e-book, smart phone, notebook, and pad ... etc., the power modules of these products always ask for some good characteristics: small volume, light weight, higher efficiency, and better regulation capability. Generally, the traditional power converters have a large volume and a heavy weight because of magnetic elements. Therefore, more manufactures and researchers pay much attention to this topic, and ultimately, requiring DC-DC/DC-AC step-up/down converters realized on a compact chip by mixed-mode VLSI technology.

The switched-capacitor (SC) power converter has received more and more attention because it has only semiconductor switches and capacitors. Thus, this kind of SC converters is one of the good solutions for low-power and high-gain DC-DC/DC-AC conversion. Up to now, the various SC types have been suggested for power conversion.

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In 1976, Dickson charge pumping was proposed based on a diode-chain structure via pumping capacitors [1]. In 1990s, Ioinovici proposed a SC with two capacitor cells working complementarily, as well as current-mode SC [2][3]. In 2007, Chang proposed a CPLD-based implementation of SC step-down DC-DC converter for multiple output choices [4]. In 2011-2013, Chang *et al.* proposed a series of multistage/multiphase SC step-up/down DC-DC/DC-AC converter/inverter [5-8]. In 2013, Chang *et al.* proposed a 2-stage 4-phase switched-capacitor boost DC-AC inverter with sinusoidal PFM control [9]. In 2014, Chang *et al.* proposed a closed-loop high-gain switched-capacitor-inductor-based boost DC-AC Inverter [10].

In order to reach a higher voltage gain, it is one of the feasible ways to adopt the device of coupled-inductor. Nevertheless, the stress on transistors and the volume of magnetic device could be considered. In 2014, Chen *et al.* proposed a coupled-inductor boost integrated flyback converter including high-voltage gain and ripple-free input current [11]. Hamid Bahrami *et al.* suggested a modified step-up boost converter with coupled-inductor and super-lift techniques [12]. In 2015, Chen *et al.* proposed a novel switched-coupled-inductor DC-DC step-up converter and its derivatives [13]. Wu *et al.* proposed a non-isolated high step-up DC-DC converter adopting switched-capacitor cell [14]. Based on the above research, the authors make an attempt on combining SC circuit with one coupled-inductor to propose a closed-loop CISCI here for a higher gain under a fewer element count.

## II. CONFIGURATION OF CISCI

Fig.1 shows the configuration of the closed-loop coupled-inductor switched-capacitor inverter (CISCI) proposed, and it contains two major parts: power part and control part for achieving the high-gain boost DC-AC conversion and closed-loop regulation. These two parts are discussed as follows.

### A. Power Part

The power part of this inverter as in upper half of Fig.1 is composed of a coupled-inductor and switched-capacitor booster and a half-bridge DC-link circuit connected in cascaded between supply  $V_s$  and output  $V_{out}$  for DC-AC power conversion. This inverter contains coupled-inductor ( $L_1, L_2$ ), three switches ( $S_1, S_a, S_b$ ), four pumping capacitors ( $Ca_1$ - $Ca_4$ ), three diodes ( $D_1$ - $D_3$ ), and one output capacitor ( $CL$ ), where it is assumed that  $Ca_1=Ca_2$  and  $Ca_3=Ca_4$ . The

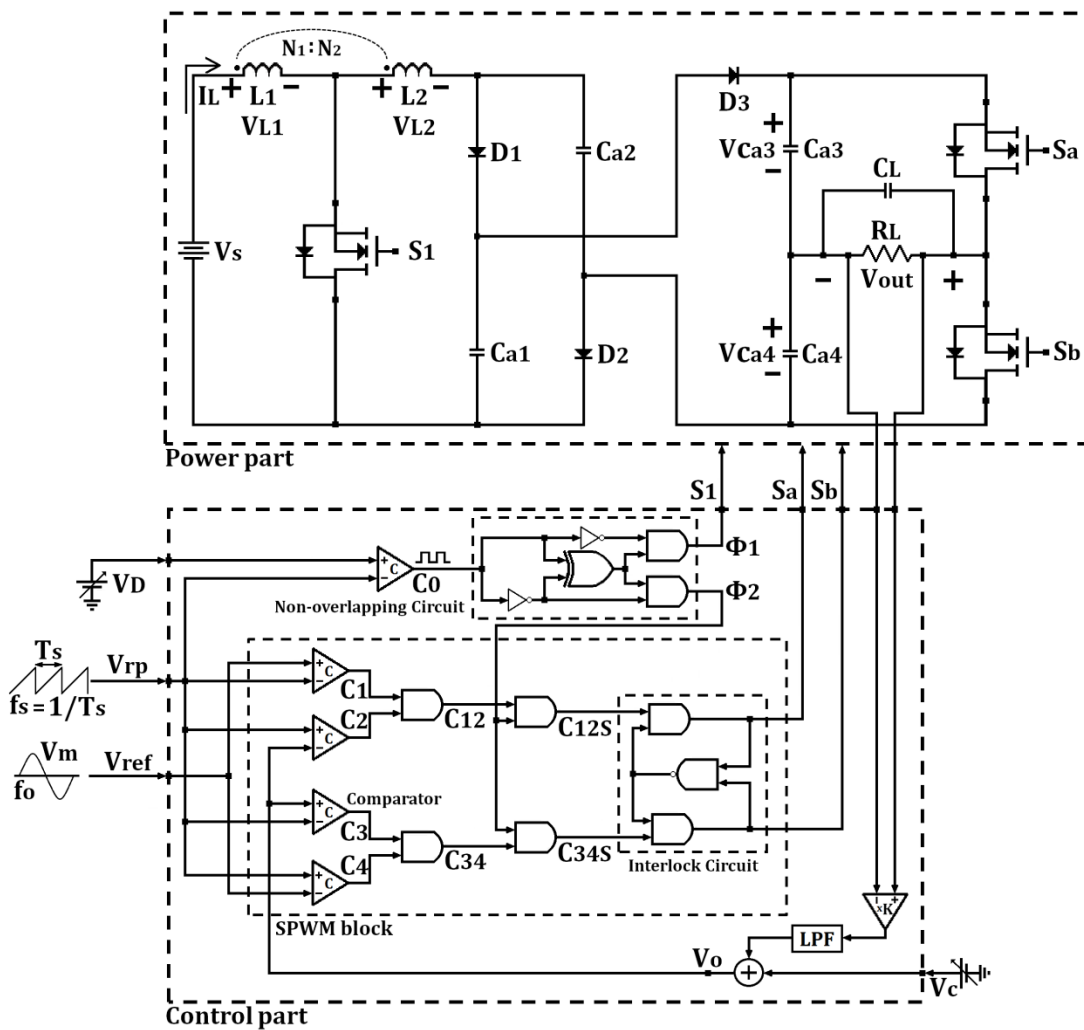


Fig. 1. Configuration of closed-loop CISCI.

coupled-inductor is modeled as an ideal transformer with a turn ratio  $n$  ( $n=N_2/N_1$ ). The main function of the booster is to raise the voltage gain between  $V_s$  and  $V_{Ca3}$  ( $V_{Ca4}$ ) up to  $(2+n+nD)/(2(1-D))$  at most, where  $D$  ( $0 < D < 1$ ) is the duty cycle and  $DT_s$  is the period of charging coupled-inductor in a switching cycle  $T_s$  ( $T_s=1/f_s$ ,  $f_s$  is the switching frequency of control part). And then, by using switches  $S_a$  and  $S_b$  in the half-bridge DC-link, plus the capacitor voltage  $V_{Ca3}$  and  $V_{Ca4}$ , the AC output can be achieved for the range of  $V_{out}$ :  $+(2+n+nD)/(2(1-D))V_s \sim -((2+n+nD)/(2(1-D)))V_s$ . Fig.2 shows the theoretical waveforms within a output cycle  $T_o$  ( $T_o=1/f_o$ ,  $f_o$  is the output frequency). Here, for the convenience of explanation, an output cycle  $T_o$  contains 20 (or above actually) switching cycle  $T_s$ . Each  $T_s$  has two Phase: Phase I and II with the different durations  $DT_s$  and  $(1-D)T_s$ . The detailed operations are discussed as follows.

1) Phase I:

During this time interval,  $S_1$  is turned ON and  $S_a, S_b$  are turned OFF. Diodes  $D_3$  is turned ON and diodes  $D_1, D_2$  are turned OFF. The relevant topology is shown in Fig. 3(a). The inductor  $L_1$  is charged by source  $V_s$ , and the energy is simultaneously transferred from the first side of the coupled-inductor to the secondary side. And then, the inductor  $L_2$  is discharged in series together with  $Ca_1$ - $Ca_2$  to transfer the stored energy to capacitors  $Ca_3$ - $Ca_4$  in series.

2) Phase II:

During this time interval,  $S_a$  or  $S_b$  is turned ON and  $S_1$  is turned OFF. Diodes  $D_1, D_2$  are turned ON and diode  $D_3$  is turned OFF.

(i) While  $S_a$  is ON:

The relevant topology is shown in Fig. 3(b). The capacitors  $Ca_1$ - $Ca_2$  are charged by  $V_s, VL_1$ , and  $VL_2$  in series. At the same time,  $Ca_3$  is discharged to supply the energy to  $CL$  and  $RL$ .

$$\text{(Output range of } V_{out}: 0 \sim + \frac{2+n+nD}{2(1-D)}V_s)$$

(ii) While  $S_b$  is ON:

The relevant topology is shown in Fig. 3(c). The capacitors  $Ca_1$ - $Ca_2$  are charged by  $V_s, VL_1$ , and  $VL_2$  in series. At the same time,  $Ca_4$  is discharged to supply the energy to  $CL$  and  $RL$ .

$$\text{(Output range of } V_{out}: 0 \sim - \frac{2+n+nD}{2(1-D)}V_s)$$

Based on the cyclical operations of Phase I and II, the overall step-up gain can reach to the value of  $(2+n+nD)/2(1-D)$ . Further, with the help of the half-bridge DC-link, the AC output can be realized for the range of  $+(2+n+nD)/2(1-D)V_s \sim -((2+n+nD)/2(1-D))V_s$ .

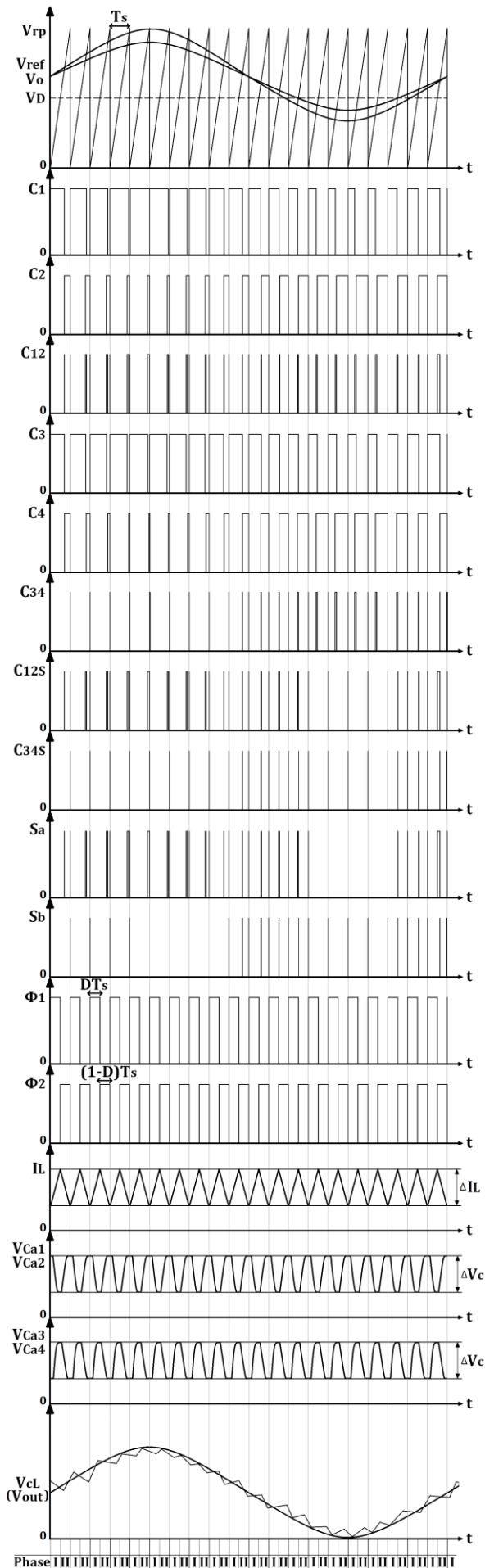


Fig. 2. Theoretical waveforms of CISCI.

### B. Control Part

The control part of CISCI is composed of a non-overlapping and SPWM block as in the lower half of Fig. 1. The operations of these two blocks are discussed as follows.

#### 1) Non-overlapping Circuit:

First, an adjustable voltage  $V_D$  is compared with a ramp function  $V_{rp}$  to generate a non-symmetrical clock signal  $C_0$ . And then, this clock is sent to the non-overlapping circuit so as to obtain a set of non-overlapping phase signals  $\Phi_1$  and  $\Phi_2$ . Here,  $\Phi_1$  is the driver signal of switch  $S_1$  for charging the coupled-inductor. Thus,  $D$  is exactly the on-time ratio (duty cycle) of  $S_1$ , and  $DT_s$  of Phase I can be regulated by the value of  $V_D$ . The main goal is to generate the driver signal of MOSFETs for the different topologies.

#### 2) SPWM block:

From the controller signal flow, the signal  $V_{out}$  is attenuated and fed back into the OP-amp low-pass filter (LPF) for high-frequency noise rejection. Next, by using a further DC-shift of  $V_c$ ,  $V_o$  is obtained and compared with the desired output  $V_{ref}$  via 4 comparators, and following by using logic-AND to produce a set of control signals  $C_{12}$ ,  $C_{34}$  for realizing SPWM. When  $e > 0$  and  $|e|$  is raising ( $e = V_{ref} - V_o$ ), the pulse width of  $C_{12}$  is getting bigger. When  $e < 0$  and  $|e|$  is raising, the pulse width of  $C_{34}$  is getting bigger. And then, via the interlock circuit (avoid  $S_a$  and  $S_b$  being 1 simultaneously) plus coming into the phase of  $\Phi_2$ ,  $S_a$  and  $S_b$  can be obtained for the SPWM control, and the main goal is to keep  $V_o$  on following  $V_{ref}$  (sinusoidal reference) to enhance the regulation capability of this proposed inverter. To summarize, based on  $V_o$  and  $V_{ref}$ , the relevant rules of producing the control/driver signals are listed as below.

- 1)  $\Phi_1, \Phi_2$ : non-overlapping anti-phase signals from  $C_0$ ;  
 $S_1 = \Phi_1$ ;
- 2) If  $V_D > V_{rp}$ , then  $C_0 = 1$ ; If  $V_D < V_{rp}$ , then  $C_0 = 0$ .
- 3) If  $V_{ref} > V_{rp}$ , then  $C_1 = 1$ ; If  $V_{ref} < V_{rp}$ , then  $C_1 = 0$ ;  
If  $V_{rp} > V_o$ , then  $C_2 = 1$ ; If  $V_{rp} < V_o$ , then  $C_2 = 0$ ;  
If  $V_o > V_{rp}$ , then  $C_3 = 1$ ; If  $V_o < V_{rp}$ , then  $C_3 = 0$ ;  
If  $V_{ref} > V_{rp}$ , then  $C_4 = 1$ ; If  $V_{ref} < V_{rp}$ , then  $C_4 = 0$ ;
- 4) If  $C_1 = 1$  and  $C_2 = 1$ , then  $C_{12} = 1$  (otherwise  $C_{12} = 0$ );  
If  $C_3 = 1$  and  $C_4 = 1$ , then  $C_{34} = 1$  (otherwise  $C_{34} = 0$ );
- 5) If  $C_{12} = 1$  and  $\Phi_2 = 1$ , then  $C_{12S} = 1$  (else  $C_{12S} = 0$ );  
If  $C_{34} = 1$  and  $\Phi_2 = 1$ , then  $C_{34S} = 1$  (else  $C_{34S} = 0$ );
- 6) SPWM control signals: ( $\wedge$ : logic-AND)  
 $S_a = C_{12S} \wedge C_0$ , for  $V_{ref} > V_o$ ;  
 $S_b = C_{34S} \wedge C_0$ , for  $V_{ref} < V_o$ .

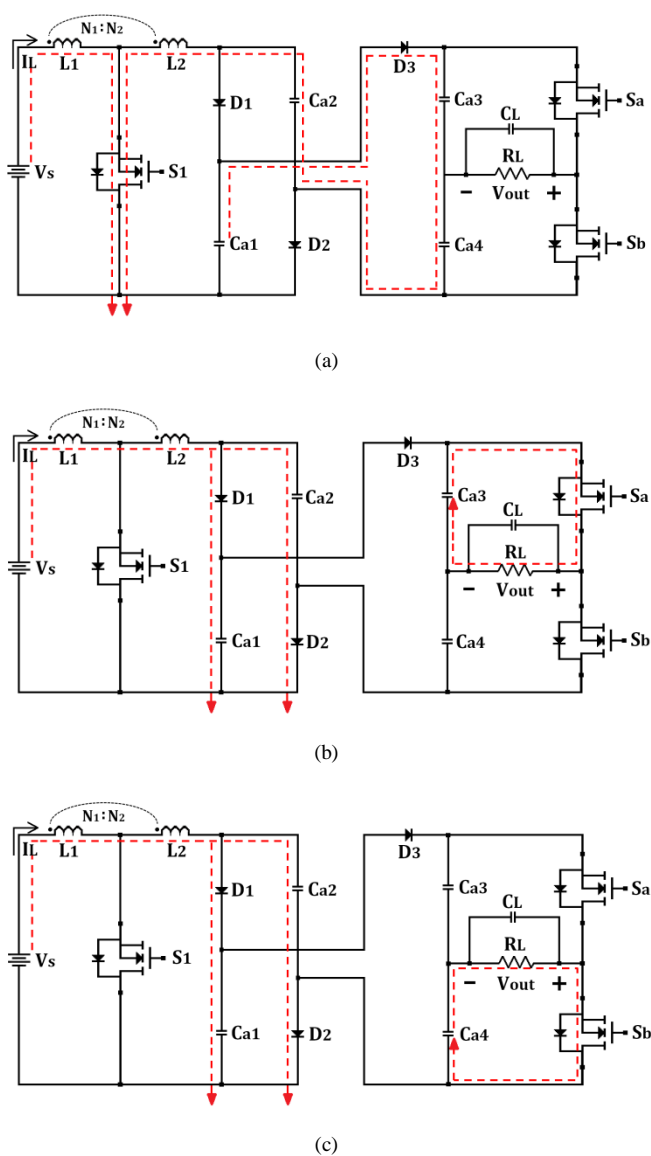


Fig. 3. Topologies for Phase (a) I, (b) II (Sa:ON), and (c) II (Sb:ON).

### III. EXAMPLES OF CISC I

In this paper, the proposed CISC I is simulated by OrCAD, and all the parameters are listed in TABLE I. There are totally 3 cases for steady-state responses and 4 cases for dynamic responses respectively. Then, these results are illustrated to verify the efficacy of the proposed inverter.

#### 1) Steady-State Responses:

Case 1:  $f_o = 60$  Hz,  $V_m = 150$  V

Let the supply source  $V_s$  be DC 12V, load  $R_L$  be  $500\Omega$ , and the peak value and output frequency of  $V_{ref}$  are  $V_m = 150$  V,  $f_o = 60$  Hz. The waveform of  $V_{out}$  is obtained as in Fig. 4(a).  $V_{out}$  has the practical peak value of 140V, and the practical output frequency is about 60Hz. The efficiency is 62.5% and THD is 1.858%.

Case 2:  $f_o = 60$  Hz,  $V_m = 160$  V

Let the supply source  $V_s$  be DC 12V, load  $R_L$  be  $500\Omega$ , and the practical peak value and output frequency of  $V_{ref}$  are  $V_m = 160$  V,  $f_o = 60$  Hz. The

waveform of  $V_{out}$  is obtained as in Fig. 4(b).  $V_{out}$  has the peak value of 145V, and the practical output frequency is about 50Hz. The efficiency is 66.25%, and THD is 2.384%.

Case 3:  $f_o = 60$  Hz,  $V_m = 170$  V

Let the supply source  $V_s$  be DC 12V, load  $R_L$  be  $500\Omega$ , and the practical peak value and output frequency of  $V_{ref}$  are  $V_m = 170$  V,  $f_o = 60$  Hz. The waveform of  $V_{out}$  is obtained as in Fig. 4(c).  $V_{out}$  has the peak value of 150V, and the practical output frequency is about 60Hz. The efficiency is 67.5%, and THD is 3.103%.

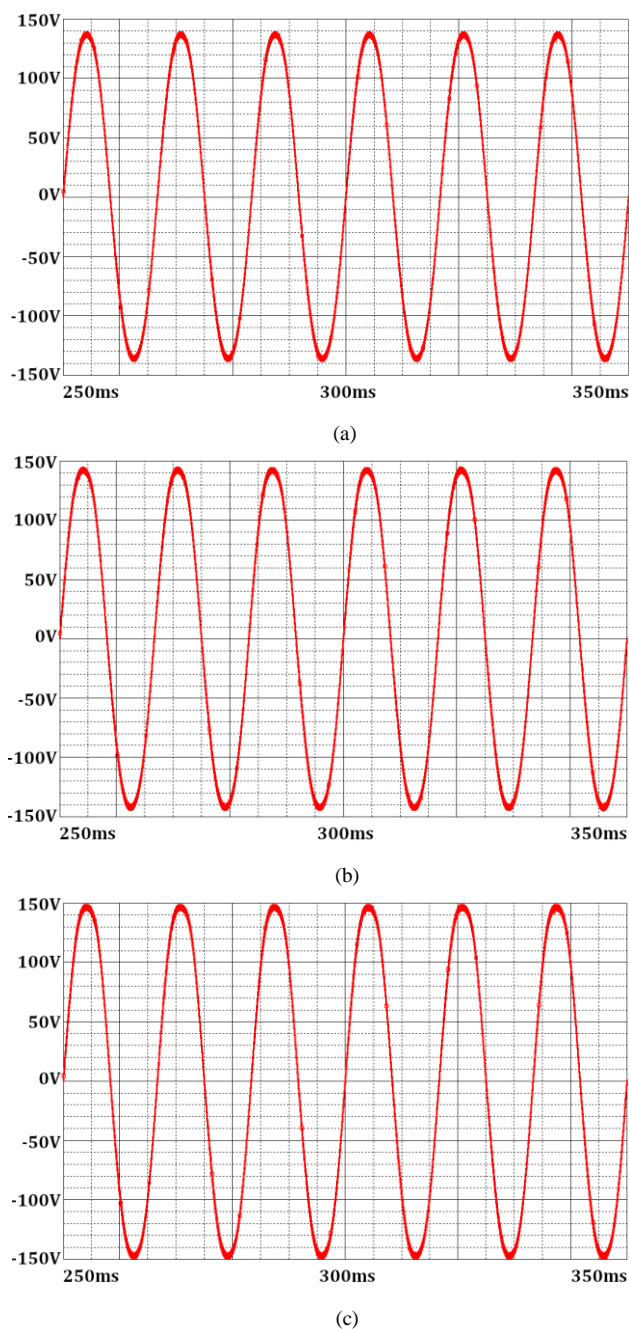


Fig. 4. Output  $V_{out}$  for  $V_{ref}$ : (a)  $f_o = 60$  Hz,  $V_m = 150$  V; (b)  $f_o = 60$  Hz,  $V_m = 160$  V; (c)  $f_o = 60$  Hz,  $V_m = 170$  V.

TABLE I  
Circuit parameters of CISCL.

Supply source (Vs)	12V
Pumping capacitor (Ca1, Ca2)	25 $\mu$ F
Coupled-inductor(L1, L2)	100 $\mu$ H, 6400 $\mu$ H (n=8)
Pumping capacitor (Ca3, Ca4)	110 $\mu$ F
Output capacitor (CL)	1.25 $\mu$ F
Power MOSFETs (S1, Sa, Sb)	ASW
On-state resistor of MOSFETs (S1)	50 $\mu$ $\Omega$
On-state resistor of MOSFETs (Sa, Sb)	2.275 $\Omega$
Diode (D1, D2, D3)	D1N5822
Load resistor (RL)	500 $\Omega$
Switching frequency (fs)	50kHz
Output frequency (fo)	60Hz

2) Dynamic Responses:

Since the voltage of battery is getting low as the battery is working long time, or the bad quality of battery results in the impurity of source voltage, such a variation of source voltage Vs must be considered, as well as variation of load RL or/and reference Vref (fo or Vm).

Case 1: VS variation

Assume that Vs is normally at DC 12V, and then it has an instant voltage jump of 12V $\rightarrow$ 10V on 300ms (Vref: fo=60Hz, Vm=170V). The waveform of Vout is shown as in Fig. 5(a). Obviously, Vout has a slight decrease into about 130V (i.e. 91.93V(RMS)).

Case 2: RL variation

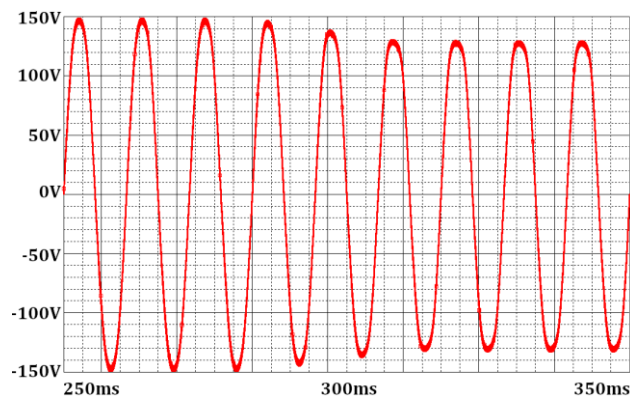
Assume that RL is 500 $\Omega$  normally, and it suddenly changes from 500 $\Omega$  to 250 $\Omega$  on 300ms (Vref: fo =60Hz, Vm =170V). Fig. 5(b) shows the transient waveform of Vout at the moment of loading variation. Obviously, Vout has a small drop but Vout can still be following Vref.

Case 3: fo variation

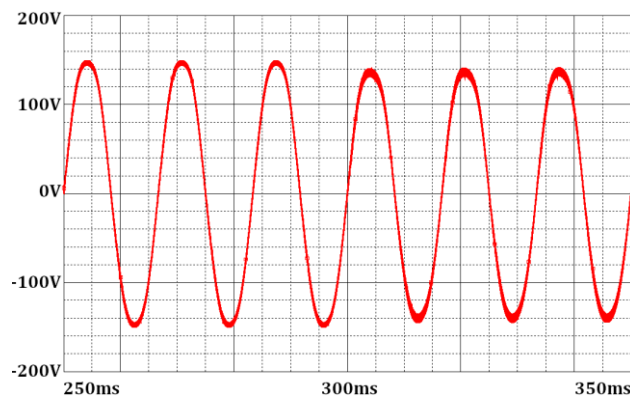
Assume that the frequency fo of Vref is 60Hz normally, After a period of 300ms, and it suddenly changes from 60Hz to 40Hz. Fig. 5(c) shows the transient waveform of Vout at the moment of variation: fo =60Hz $\rightarrow$ 40Hz. Obviously, Vout is still able to follow Vref even the frequency of Vref changes.

Case 4: Vm variation

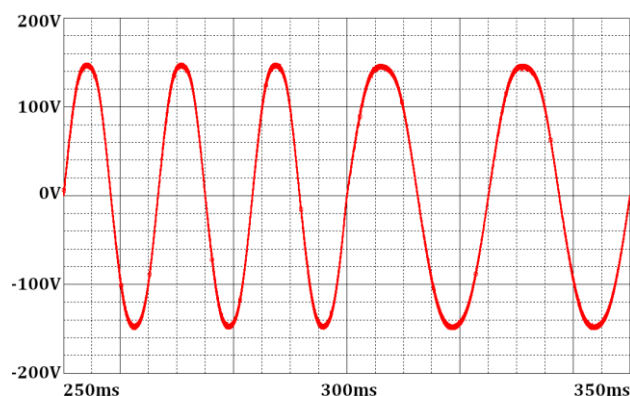
Assume that Vm is 170V normally, After a period of 300ms, and it changes from 170V to 150V. Fig. 5(d) shows the transient waveform of Vout at the moment of variation: Vm=170V $\rightarrow$ 150V. Obviously, Vout is still able to follow Vref even the amplitude of the desired Vref changes.



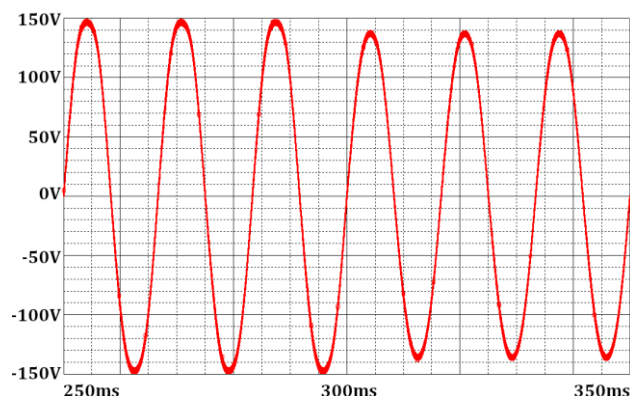
(a)



(b)



(c)



(d)

Fig. 5. Output Vout for the variation of (a) Vs; (b) RL; (c) fo; (d) Vm.

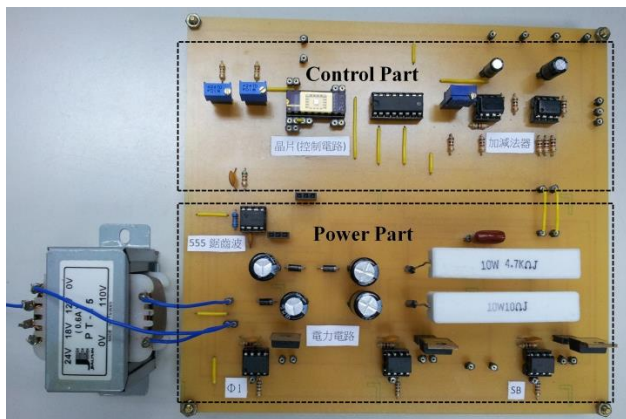


Fig. 6. Prototype circuit of the proposed inverter.

According to the above results, it is obvious that  $V_{out}$  is following  $V_{ref}$  for the cases, including  $V_s$  source variation,  $R_L$  loading variation,  $f_o$  frequency variation,  $V_m$  amplitude variation. These results show that this proposed inverter has a good closed-loop dynamic performance.

#### IV. CONCLUSION

A novel coupled-inductor switched-capacitor inverter (CISCI) is proposed by combining a non-overlapping circuit and sinusoidal pulse-width-modulation (SPWM) controller for the high-gain boost DC-AC conversion and closed-loop regulation. Finally, the CISCI is designed and simulated, and all results are illustrated to show the efficacy of the proposed scheme. The advantages of the scheme are listed as follows. (i) This CISCI needs just one coupled-inductor element (inductor). Except this, other components (i.e. SC) will be able to be made in IC fabrication future. (ii) This proposed inverter can provide the voltage gain of  $(2+n+nD)/2(1-D)$  at most just with 4 pumping capacitors plus one coupled-inductor. (iii) For a higher gain, it can be realized with extending the number of pumping capacitors or increasing the turn ratio of coupled-inductor. (iv) The SPWM technique is adopted not only to enhance output regulation capability for the different desired output, but also to reinforce the output robustness against source/loading variation. At present, the prototype circuit of this inverter is implemented in the laboratory as shown in the photo of Fig. 6. Some experimental results will be obtained and measured for the verification of the proposed inverter.

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