

Land-Use Classification Using Convolutional Neural Network with Bagging and Reduced Categories

Noritaka Shigei, Kazuki Mandai, Satoshi Sugimoto, Ryoma Takaesu, and Yoichi Ishizuka

Abstract—In this paper, we tackle with the land-use classification from aerial photographs in the hilly and mountainous areas and apply two kinds of approaches to the problem. The one is the ensemble learning approach to improve the classification accuracy for overall classes, and the other is the optimization of the number of classes to improve the classification accuracy for coniferous forest. Our ensemble learning approach adopts Bagging and uses a Convolutional Neural Network (CNN) classifier as a weak learner. The optimization of the number of classes utilizes the spectral clustering algorithm and the confusion matrix of the classification result obtained by a CNN classifier. The effectiveness of the proposed approaches is demonstrated by numerical simulations.

Index Terms—convolutional neural network, land-use classification, Bagging, aerial photograph

I. INTRODUCTION

IN countries with few plains like Japan, it is unavoidable to develop hilly areas and their surroundings as residential or urban areas. In order to effectively implement disaster countermeasures, it is needed to grasp the land use and to identify the hazard areas. In particular, for landslide disasters due to rainy weather, which greatly depend on vegetation, the detection of coniferous forests being with high probability of occurrence of disaster[1] is important.

Various types of land-use classification data exist. As one of them, in Japan, Ministry of Land, Infrastructure, Transport and Tourism (MLIT) provides the digital data of land-use classification in National Land Numerical Information (NLNI)[2]. The data was originally created from the 1:250,000 scale map of Geospatial Information Authority of Japan (GSI) in 1997 and has been updated based on the updated 1:250,000 scale map of GSI, satellite images, etc., in 1987, 1991, 1997, 2006, 2009 and 2014. In recent years, with the spread of unmanned airplanes, etc., aerial photographs can be easily taken. Utilization of aerial photographs in land use classification will lead to more accurate classification and speedup of updating.

Convolutional Neural Network (CNN)[3] is one of promising methods for the land-use classification from aerial photographs, because of its great success for many applications of image recognition. Application of CNN to the land-use classification has been extensively studied. In [4], the effectiveness of fine-tuning of pre-trained CNN is demonstrated. In [5], it is proposed to use multiple multiscale

N. Shigei and K. Mandai are with the Graduate School of Science and Engineering, Kagoshima University, 1-21-40 Korimoto, Kagoshima, Japan, e-mail: shigei@eee.kagoshima-u.ac.jp, k6015742@kadai.jp

S. Sugimoto, R. Takaesu and Y. Ishizuka are with Nagasaki University.

This work was partially supported by JSPS KAKENHI Grant Number JP17K00170.

images as input. In [6], two-stage network consisting of pretrained network and trainable CNN is proposed. In [7], the effectiveness of the combination with sparse autoencoder is demonstrated. In [8], the combination of CNN and extreme learning is proposed. These proposed methods have been shown to be effective for the UC-Merced dataset[9], which is a benchmark dataset consisting of 21 land-use classes. However, in the benchmark dataset, coniferous forests, which are with high risk of disasters, are included in the forest class. Thus, it is an open problem whether the CNN based approach can accurately distinguish coniferous forests from other types of forests in the land-use classification problem.

In this paper, we tackle with the land-use classification problem covering the hilly and mountainous areas and apply two kinds of approaches to the problem. The one is the ensemble learning approach to improve the classification accuracy for overall classes, and the other is the optimization of the number of classes to improve the classification accuracy for coniferous forest. Our ensemble learning approach adopts the Bagging algorithm[10] and uses a CNN classifier as a weak learner. The optimization of the number of classes utilizes the spectral clustering algorithm[11] and the confusion matrix of the classification result obtained by a CNN classifier. The effectiveness of the proposed approaches is demonstrated for our original dataset sampled from the hilly and mountainous areas in Japan.

II. LAND-USE CLASSIFICATION USING CNN FROM AERIAL PHOTOGRAPHS

This section describes the land-use classification problem including specific classes and the CNN classifier used as the basic model in this paper.

A. Land-Use Classification for Hilly and Mountainous Areas

In this paper, we deal with the land-use classification problem in hilly and mountainous areas. Unlike the case where the entire area is targeted, in this case, very similar images exist between images of different classes. Figure 1 shows sample images of nine classes in the classification problem dealt with in this paper. Every images contain plants, are greenish in color and are similar. In particular, bamboo forest, broadleaf forest and coniferous forest are very similar, and it seems difficult for even human beings to distinguish them. Coniferous forests are known to have a high probability of sediment-related disasters[1]. Therefore, this paper focuses particularly on improving the detection rate of this coniferous forest.

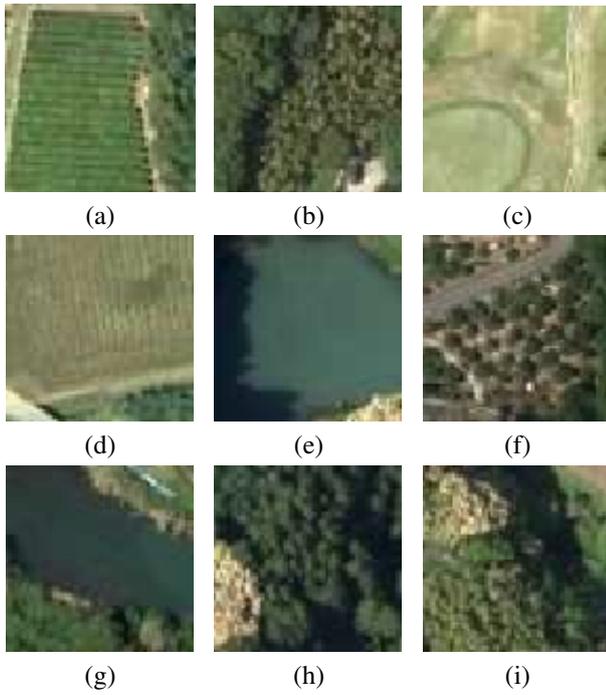


Fig. 1. Class examples of our dataset: (a) tea plantation, (b) bamboo forest, (c) golf course, (d) field, (e) pond, (f) orchard, (g) river, (h) broadleaf forest and (i) coniferous forest (Source: GSI tiles).

B. CNN Classifier

In this paper, we use CNN based on LeNet[3] as the basic model of classifiers applied to the land-use classification problem. The structure of CNN is shown in Figure 2. The network consists of input layer, three pairs of convolution and pooling layers, fully-connected layer and softmax layer. The input layer accepts an RGB color image of size $N \times N$ consisting of three channels. The output $f^{(k)}$ for $k \in [K]$ corresponds to the probability that the input image belongs to the class k , where $[K] = \{1, 2, \dots, K\}$. Thus, $k_{\max} = \arg \max_{k \in [K]} f^{(k)}$ is the class determined by the CNN classifier. In Figure 2, n_{ci} , k_{ci} , s_{ci} and p_{ci} for $i \in [3]$ are parameters for i -th convolution layer and are the number of filters, the filter size, the interval between filter applications and the number of pixels added to the input, respectively. The parameters p_{pi} , k_{pi} and s_{pi} are for i -th pooling layer and are the pooling method (such as max, average and stochastic), the filter size and the interval between filter applications, respectively.

III. IMPROVEMENT OF CLASSIFICATION ACCURACY

In this section, we present two types of methods for improving the classification accuracy.

A. Bagging based on CNN

Bagging (Bootstrap AGGREGatING)[10] is one of ensemble learning methods, in which the accuracy of the classifier or regressor is improved by combining multiple learners into one classifier or regressor. In general, since the performance of each learner is lower than the original one, the learner in ensemble learning is called weak learner. It is known that Bagging is effective for unstable procedures such as neural networks, classification and regression trees, where unstable means that small changes in data have a great influence on

learning. Therefore, in this paper, we propose that CNN, which is a kind of neural networks, is used as a weak learner.

Let D be the training data set. Let M be the number of weak learners. Let N_s be the number of data items for each weak learner. The algorithm of the learning stage of Bagging is as follows:

Step 1: Generate M data sets D_1, D_2, \dots, D_M , each of size N_s , by randomly sampling from D with replacement.

Step 2: For each $m \in [M]$, train m -th weak learner L_m by using data set D_m as training data. \square

In Bagging, the classifier or regressor is constructed by aggregating the outputs of the weak learners. In general, the majority vote and the average are used for classifier and regressor, respectively. In this paper, we construct the classifier by aggregating the outputs of the weak learners based on the accuracy of each weak learner. Let $f_m^{(k)}$ be the k -th output from softmax layer of m -th weak learner. Let $a_m^{(k)}$ be the m -th weak learner's recall for the class k as follows:

$$a_m^{(k)} = \frac{|D(m, k)|}{|D(k)|}, \quad (1)$$

where $D(k)$ is the set of data items of class k in D and $D(m, k)$ is the set of data items in D that L_m classifies as class k . Then, the aggregated classification result \hat{k} is as follows:

$$\hat{k} = \arg \max_{k \in [K]} \left(\sum_{m \in [M]} a_m^{(k)} f_m^{(k)} \right). \quad (2)$$

B. Reduction of the number of classes

In general, the classification accuracy in classification problems decreases as the number of classes increases. When the recall of a particular class is important, the number of classes should be reduced so as to maximize the obtained recall rate. In this paper, we propose utilize spectral clustering (SC) to reduce the number of classes. SC is the method for dividing the data set into subsets according to the similarity defined between all pairs of data[11]. In general, the similarity used in SC is defined by a similarity matrix $S = (s_{ij})$, where S is a symmetric matrix and $s_{ij} \geq 0$ represents the similarity between i -th and j -th data points. Given a similarity matrix S , SC can divide the data set into subsets by using the eigenvalues of S .

In order to apply SC to the reduction of the number of classes, we propose to utilize a confusion matrix $C = (c_{ij})$ to make the similarity matrix S . The confusion matrix C is obtained from the classification result of a classifier of CNN solving the classification problem with K classes, where c_{ij} is the ratio of the data items classified as class j by the classifier in $D(i)$. c_{ij} is considered to represent how similar the class i and class j are. Since it is not guaranteed that C is symmetric, C is converted into the S as follows:

$$s_{ij} = \begin{cases} c_{ii} & \text{for } i = j \\ \frac{c_{ij} + c_{ji}}{2} & \text{for } i \neq j. \end{cases} \quad (3)$$

The procedure for obtaining the re-assignment of the classes with a reduced number of classes K_{red} is as follows: Let $k_{\text{target}} \in [K]$ be the target class whose recall rate should be improved.

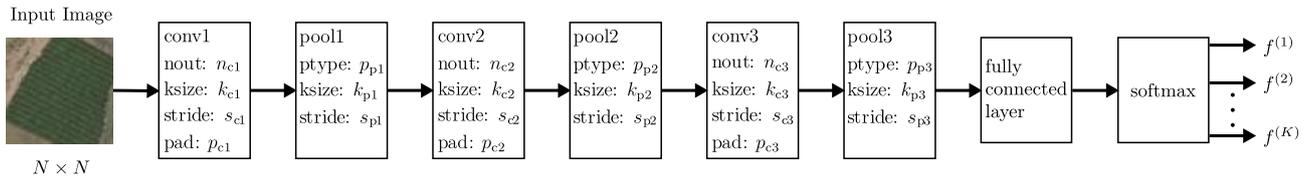


Fig. 2. The used CNN model (Source of input image: GSI tiles).

Step 1: Let $\mathcal{K} \leftarrow [K]$, where \mathcal{K} is the set of classes to be applied SC. Let $\mathcal{K}_{\text{list}} \leftarrow \{\mathcal{K}\}$, where each element of $\mathcal{K}_{\text{list}}$ is the set of classes assigned to the same re-assigned class.

Step 2: Construct the similarity matrix S of size $|\mathcal{K}| \times |\mathcal{K}|$ from the confusion matrix C . Apply SC to the similarity matrix S and divide $|\mathcal{K}|$ classes in \mathcal{K} into two subsets \mathcal{K}_1 and \mathcal{K}_2 . Let $\mathcal{K}_{\text{list}} \leftarrow \mathcal{K}_{\text{list}} \setminus \{\mathcal{K}\} \cup \{\mathcal{K}_1, \mathcal{K}_2\}$.

Step 3: If there exists the set of classes $\mathcal{K}' \in \mathcal{K}_{\text{list}}$ such that $\mathcal{K}' = \{k_{\text{target}}\}$, then $\mathcal{K}_{\text{list}}$ is a candidate of re-assignment of classes. If $|\mathcal{K}_{\text{list}}| = K - 1$, then terminate the procedure.

Step 4: Let $\mathcal{K} \leftarrow \arg \min_{\mathcal{K}' \in \{\mathcal{K}_1, \mathcal{K}_2\}} \text{sim}(\mathcal{K}')$, where $\text{sim}(\mathcal{K})$ is the similarity among the elements in \mathcal{K} . Go to Step 2. \square

Any of candidates obtained in Step 3 has smaller number of classes $K_{\text{red}} = |\mathcal{K}_{\text{list}}|$ then the original one K . The best one among the candidates is determined by using numerical simulations.

IV. NUMERICAL SIMULATION

In order to confirm the effectiveness of the proposed methods, we perform numerical simulations. The simulation conditions are as follows: The number of used images is 450 in total and is 50 for each of $K = 9$ classes. The image is obtained from the database of Geospatial Information Authority of Japan (GSI). The parameters for CNN is shown in Table I, where the parameters used for Bagging are selected so that the number of weights used in CNN is smaller than in the conventional case. Every evaluation values are calculated by 5-fold cross validation with 450 images. That is, 450 images are divided into five subsets of 90 images in which the number of images for each class is equally 10, and for each of five subsets, the subset is used as test data set and the other four subsets are used as training data set. All the evaluation values are averages of five values obtained by the five runs using five test data sets.

Firstly, the conventional CNN is evaluated for the number of training iterations ranging from 10,000 to 500,000. Figure 3 shows the overall accuracy and the recall for class “coniferous” versus the number of training iterations. Note that, since class “coniferous” is with high risk of disasters as mentioned in the introduction, in this paper, class “coniferous” will be assumed to be the target class. The overall accuracy is the ratio of correctly identified patterns of every classes to all the patterns. The recall for class A is the ratio of correctly identified patterns of class A to all the patterns. According to Figure 3, the best overall accuracy and the best recall are 0.736 and 0.70 at the number of training iterations 200,000, respectively. In the conventional CNN, the accuracy and the recall are not improved even if the number of training iterations increases.

Secondly, the conventional CNN and the Bagging based on CNN are compared. The Bagging based on CNN is evaluated

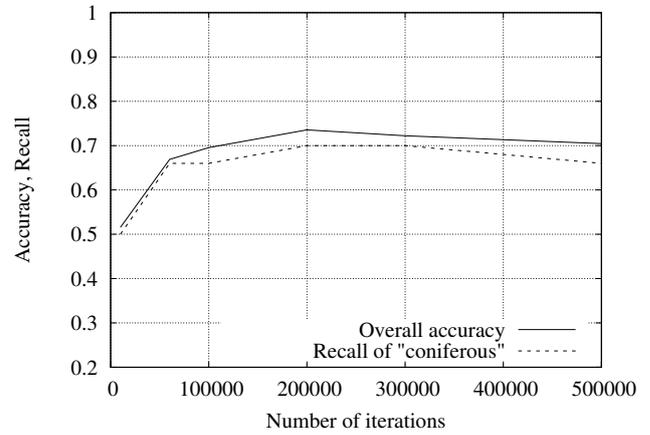


Fig. 3. The overall accuracy and the recall for class “coniferous” versus the number of training iterations.

TABLE I
 PARAMETERS USED FOR CNN.

Param.	Conv.	Bagging
n_{c1}	32	8
k_{c1}	5×5	5×5
s_{c1}	1	1
p_{c1}	2	2
p_{p1}	MAX	MAX
k_{p1}	3×3	3×3
s_{p1}	2	2
n_{c2}	32	32
k_{c2}	5×5	5×5
s_{c2}	1	1
p_{c2}	2	2
p_{p2}	AVE	AVE
k_{p2}	3×3	3×3
s_{p2}	2	2
n_{c3}	64	32
k_{c3}	5×5	5×5
s_{c3}	1	1
p_{c3}	2	2
p_{p3}	AVE	AVE
k_{p3}	3×3	3×3
s_{p3}	2	2

with the number of weak learners M ranging from 2 to 10. In the following all simulations, the number of training iterations for the conventional CNN is 600,000 and that for weak learners of Bagging is 100,000. Table II shows the recall for each of 9 classes and the overall accuracy. The best accuracy for each evaluation item is in bold. The result shows the following tendencies.

- The proposed Bagging based on CNN outperforms the conventional CNN for almost every evaluation items even when the number of weak learners M is the minimum two.

TABLE II
 THE RECALL FOR EACH CLASS AND THE OVERALL ACCURACY OF CONVENTIONAL CNN AND BAGGING BASED ON CNN.

Method	M	tea	bam.	golf	fie.	pond	orch.	riv.	bro.	con.	Overall accuracy
Conventional	–	0.76	0.74	0.86	0.66	0.82	0.20	0.54	0.38	0.66	0.669
Bagging	2	0.74	0.84	1.00	0.76	0.82	0.64	0.68	0.58	0.70	0.751
	3	0.78	0.78	0.98	0.86	0.84	0.70	0.62	0.58	0.74	0.764
	4	0.86	0.82	0.98	0.86	0.80	0.70	0.62	0.60	0.70	0.771
	5	0.84	0.82	0.98	0.84	0.84	0.70	0.62	0.56	0.70	0.767
	6	0.88	0.82	0.98	0.84	0.84	0.74	0.68	0.56	0.72	0.784
	7	0.86	0.84	1.00	0.88	0.84	0.72	0.62	0.56	0.70	0.780
	8	0.86	0.84	0.98	0.88	0.82	0.74	0.66	0.54	0.72	0.782
	9	0.84	0.82	0.98	0.86	0.82	0.72	0.64	0.52	0.74	0.771
	10	0.84	0.82	0.98	0.86	0.84	0.72	0.64	0.50	0.74	0.771

TABLE III
 THE RECALL, PRECISION AND F_1 -SCORE FOR THE TARGET CLASS “CONIFEROUS”.

(a) For conventional CNN with/without RNC.

$K_{red} = 5$			$K_{red} = 6$			$K_{red} = 7$			$K_{red} = 8$			$K = 9$		
Rec.	Prec.	F_1	Rec.	Prec.	F_1	Rec.	Prec.	F_1	Rec.	Prec.	F_1	Rec.	Prec.	F_1
0.74	0.771	0.755	0.68	0.708	0.694	0.76	0.691	0.724	0.78	0.736	0.757	0.66	0.717	0.688

(b) For Bagging based on CNN with/without RNC.

M	$K_{red} = 5$			$K_{red} = 6$			$K_{red} = 7$			$K_{red} = 8$			$K = 9$		
	Rec.	Prec.	F_1	Rec.	Prec.	F_1	Rec.	Prec.	F_1	Rec.	Prec.	F_1	Rec.	Prec.	F_1
2	0.66	0.767	0.710	0.70	0.795	0.745	0.72	0.818	0.766	0.68	0.810	0.739	0.70	0.761	0.729
3	0.72	0.800	0.758	0.74	0.804	0.771	0.74	0.771	0.755	0.74	0.787	0.763	0.74	0.771	0.755
4	0.72	0.800	0.758	0.74	0.804	0.771	0.76*	0.792	0.776	0.74	0.804	0.771	0.70	0.761	0.729
5	0.74	0.804	0.771	0.72	0.800	0.758	0.76*	0.809	0.784	0.74	0.804	0.771	0.70	0.761	0.729
6	0.72	0.800	0.758	0.72	0.800	0.758	0.76*	0.826*	0.792*	0.72	0.818	0.766	0.72	0.766	0.742
7	0.68	0.791	0.731	0.70	0.795	0.745	0.74	0.804	0.771	0.72	0.800	0.758	0.70	0.761	0.729
8	0.68	0.791	0.731	0.72	0.800	0.758	0.74	0.822	0.779	0.72	0.800	0.758	0.72	0.766	0.742
9	0.70	0.795	0.745	0.72	0.800	0.758	0.74	0.804	0.771	0.72	0.783	0.750	0.74	0.771	0.755
10	0.70	0.795	0.745	0.74	0.787	0.763	0.72	0.818	0.766	0.72	0.800	0.758	0.74	0.771	0.755

• Larger number of weak learners M does not necessarily give better results. In other words, there exists some optimal number of weak learners. For overall accuracy, $M = 6$ is the best choice.

Thirdly, the effect of the Reduction of the Number of Classes (RNC) presented in III-B is evaluated. The aim of RNC is to improve the classification accuracy of some specific (target) class. As mentioned in the introductions mentioned, since coniferous forests are with high risk of disasters, the class “coniferous” is assumed to be the target class. The procedure of the evaluation is as follows: 1) perform the conventional CNN for $K = 9$, 2) perform the procedure presented in III-B with the confusion matrix C obtained by 1) and 3) perform the evaluated methods such as the conventional CNN and the Bagging for each of K_{red} 's obtained in 2). In 2), the following four candidates for re-assignment of classes with the reduced number of classes $K_{red} = 5, 6, 7, 8$ are obtained:

- 5 classes: {(a), (f), (g)}, {(b)}, {(c), (d), (e)}, {(h)}, {(i)}
- 6 classes: {(a)}, {(b)}, {(c), (d), (e)}, {(f), (g)}, {(h)}, {(i)}
- 7 classes: {(a)}, {(b)}, {(c), (d), (e)}, {(f)}, {(g)}, {(h)}, {(i)}
- 8 classes: {(a)}, {(b)}, {(c), (d)}, {(e)}, {(f)}, {(g)}, {(h)}, {(i)}

Table III shows the recall, precision and F_1 score for the target class “coniferous”. Table III.(a) shows the results of conventional CNN with/without RNC, where the cases of $K_{red} = 5, 6, 7$ and 8 are with RNC and the case of $K = 9$ is without RNC. In the table, the best value for each evaluation

item is in bold. The result shows the following tendencies.

- For the conventional CNN, the RNC improves all of recall, precision and F_1 score.
- In particular, the recall rate for $K_{red} = 8$ of RNC is 12 percent point better than the one without RNC, that is for $K = 9$.
- It seems that larger values of K_{red} provide better recall rates.

Table III.(b) shows the results of Bagging based on CNN with/without RNC. The best value of an evaluation item for each K_{red} or K is in bold and the best value of an evaluation item in the table is marked with an asterisk “*”. The result shows the following tendencies.

- For Bagging without RNC, that is, $K = 9$, it seems that any of recall, precision and F_1 score does not depend on the number of weak learners M . However, for any M , the Bagging without RNC achieves better recall, precision and F_1 score than the conventional CNN without RNC.
- For Bagging with RNC, that is, $K_{red} = 5, 6, 7$ and 8, like the recall and the overall accuracy in Table II, larger number of weak learners M does not necessarily give better results. In other words, there exists some optimal number of weak learners. $M = 5, M = 3$ or 4, $M = 6$ and $M = 6$ or 7 are best for $K_{red} = 5, 6, 7$ and 8, respectively.

Finally, Table IV summarizes the best recall, precision and F_1 score of target class “coniferous” for each of CNN, Bagging, CNN with RNC and Bagging with RNC. In the table, the best value for each evaluation item is in bold. The following tendencies are observed from the table.

TABLE IV
 THE BEST RECALL, PRECISION AND F₁ SCORE OF TARGET CLASS
 “CONIFEROUS” FOR CNN AND BAGGING WITH/WITHOUT RNC.

Method	K/K_{red}	M	Rec.	Prec.	F ₁
CNN	9	–	0.66	0.717	0.688
Bagging	9	3,9,10	0.74	0.771	0.755
CNN with RNC	8	–	0.78	0.736	0.755
Bagging with RNC	7	6	0.76	0.826	0.792

- Bagging, RNC and these combinations are better than the conventional CNN in any of recall, precision and F₁ score.
- CNN with RNC achieves the best recall. Therefore, the combination of CNN and RNC would be effective for improving the recall.
- Bagging achieves the best precision and F₁ score, and its recall is relatively high. Therefore, the combination of Bagging and RNC would be effective for realizing the best trade-off between recall and precision.

V. CONCLUSIONS

We demonstrate that the proposed Bagging can improve the overall accuracy. Concerning to the improvement of the classification accuracy of the target class “coniferous”, it is considered that the Bagging based on CNN has an effect on improving the precision, and the RNC is effective in improving the recall. In addition, the combination of Bagging and RNC improves both of recall and precision.

Future works include applying other ensemble methods such as boosting to the problem and verification with the large number of data. In addition, since Bagging is suitable for parallel implementation, it will be considered to implement Bagging by using secure multiparty computation (SMC)[12], which is a secure calculation method on cloud server.

REFERENCES

[1] K. Tajiri, H. Nakayama and S. Imaizumi, “Statistical Analysis of Slope-failure at Kumamoto Prefecture using Geotechnical Information Data Base system,” *Soils and Foundations*, vol. 32, issue 2, pp. 159-168, Jun. 1992 (in Japanese).

[2] Ministry of Land, Infrastructure, Transport, and Tourism, “National Land Numerical Information Download Service,” 2016.

[3] Y. LeCun, L. Bottou, Y. Bengio and P. Haffner, “Gradient-Based Learning Applied to Document Recognition,” *Proc. of the IEEE*, vol. 86, no. 11, pp. 2278-2324, 1998.

[4] M. Castelluccio, G. Poggi, C. Sansone and L. Verdoliva, “Land Use Classification in Remote Sensing Images by Convolutional Neural Networks,” *arXiv preprint arXiv:1508.00092*, 2015.

[5] F. P. S. Luus, B. P. Salmon, F. van den Bergh and B. T. J. Maharaj, “Multiview Deep Learning for Land-Use Classification,” *IEEE Geoscience and Remote Sensing Letters*, vol. 12, no. 12, pp. 2448-2452, 2015.

[6] D. Marmanis, M. Datcu, T. Esch and U. Stilla, “Deep Learning Earth Observation Classification Using ImageNet Pretrained Networks,” *IEEE Geoscience and Remote Sensing Letters*, vol. 13, no. 1, pp. 105-109, 2016.

[7] E. Othman, Y. Bazi, N. Alajlan, H. Alhichri and F. Melgani, “Using Convolutional Features and a Sparse Autoencoder for Land-Use Scene Classification,” *International Journal of Remote Sensing*, vol. 37, issue 10, pp. 2149-2167, 2016.

[8] Q. Weng, Z. Mao, J. Lin and W. Guo, “Land-Use Classification via Extreme Learning Classifier Based on Deep Convolutional Features,” *IEEE Geoscience and Remote Sensing Letters*, vol. 14, no. 5, pp. 704-708, 2017.

[9] Y. Yang and S. Newsam, “Bag-of-Visual-Words and Spatial Extensions for Land-Use Classification,” *Proc. of Int. Conf. on Advances in Geographic Information Systems*, pp. 270-279, 2010.

[10] L. Breiman, “Bagging Predictors,” *Machine Learning*, vol. 24, pp. 123-140, 1996.

[11] J. Shi and J. Malik, “Normalized Cuts and Image Segmentation,” *IEEE Trans. on Pattern Analysis and Machine Intelligence*, vol. 22, no. 8, pp. 888-905, 2000.

[12] Hirofumi Miyajima, N. Shigei, Hiromi Miyajima, N. Shiratori, “Analog Q-learning Methods for Secure Multiparty Computation,” *IAENG International Journal of Computer Science*, 45:4, pp. 623-629, 2018.