

Product Construction of Finite-State Machines

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Abstract— Two algorithms to construct a product machine from two finite-state machines are presented and analyzed. The first algorithm is simple and correctly produces a product machine, but the product machine may include unreachable states and associated transitions. The second algorithm produces a functionally correct product machine that has no unreachable states.

Index Terms—deterministic finite-state machine, product machine construction, theory, unreachable state.

I. INTRODUCTION

The union or the intersection of two regular languages is still a regular language, that is, regular languages are closed under the operations union and intersection, e.g., [1]. In fact, from two given deterministic finite-state machines, a product machine can be constructed such that the product machine simulates the two given machines simultaneously and accepts a language that is the intersection or the union of the languages of the given machines.

This article discusses and analyzes two algorithms to construct a product machine from two given machines. The first algorithm is simple and correctly produces a product machine. However, the product machine may include unreachable states and associated transitions. The second algorithm addresses this problem and produces a functionally correct product machine that has no unreachable states.

II. BASIC DEFINITIONS

A deterministic finite-state machine (DFSM) consists of a set of states Q , an alphabet Σ , a transition function δ from $Q \times \Sigma$ to Q , a start state s in Q , a set of accept states F , which is a subset of Q . Formally, a DFSM is the 5-tuple $(Q, \Sigma, \delta, s, F)$.

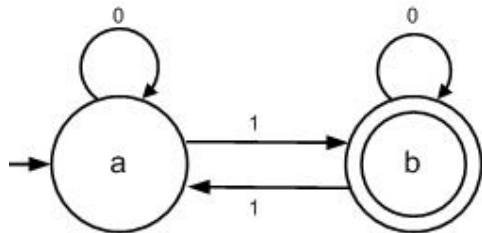


Fig.1 $M_1 = (\{a, b\}, \{0, 1\}, \delta_1, a, \{b\})$

Graphically, a finite-state machine is usually shown as a state diagram. As an example, Fig.1 shows a DFSM $M_1 = (\{a,$

$b\}, \{0, 1\}, \delta_1, a, \{b\})$, where the set of states is $\{a, b\}$, the alphabet is $\{0, 1\}$, the start state is the state a , the state b is the only accept state, and the transition function δ_1 is shown by the collection of labeled arrows between the states: for example, since there is an arrow labeled 1 from state a to state b , $\delta_1(a, 1) = b$. The start state is marked by an incoming arrow that does not have a source state, and the accept state is indicated by a double circle. The machine M_1 accepts those strings that have an odd number of 1's and any number of 0's.

Table I. State Transition Table for M_1

	0	1
a	a	b
b	b	a

Often, a transition function is defined with a state transition table. Table I shows the state transition table for M_1 . The table defines the transition function δ_1 in a tabular form. For example, the fact $\delta_1(a, 1) = b$ is shown by the value b in the entry $[a, 1]$ of the table (that is, in the row labeled a and in the column labeled 1).

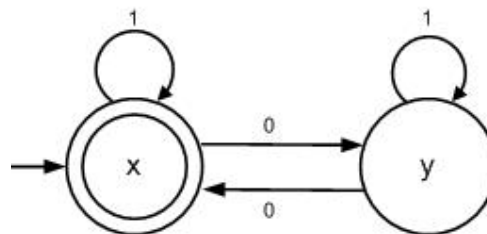


Fig.2 $M_2 = (\{x, y\}, \{0, 1\}, \delta_2, x, \{x\})$

Table II. State Transition Table for M_2

	0	1
x	y	x
y	x	y

Fig. 2 shows another machine $M_2 = (\{x, y\}, \{0, 1\}, \delta_2, x, \{x\})$. The machine accepts those strings that have an even number of 0's and any number of 1's. The transition function δ_2 is shown as a transition table in Table II.

III. PRODUCT MACHINE CONSTRUCTION

A product machine is constructed from two machines, simulates the behavior of the two machines simultaneously, and accepts either the intersection or the union of the languages of the two machines. A product machine that accepts the *intersection* of the languages of the two machines

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$M_a = \{Q_a, \Sigma, \delta_a, s_a, F_a\}$ and $M_b = \{Q_b, \Sigma, \delta_b, s_b, F_b\}$ is a DFSM
 $M_p = \{Q_a \times Q_b, \Sigma, \delta_p, (s_a, s_b), F_a \times F_b\}$.

The set of states of the product machine can be easily found. It is the Cartesian product $Q_a \times Q_b$. Obviously, each state of M_p is a pair of states, denoted by (a, b) . In the product machine, the pair is unordered. i.e., (a, b) and (b, a) are considered the same state of the product machine.

The start state of M_p is the pair that consists of the start states of M_a and M_b . The accept states of M_p can also be identified easily: for a state (a, b) of the product machine M_p to be an accept state, one of a and b must be an accept state of M_a and the other must be an accept state of M_b , i.e., both a and b must be accept states in M_a and M_b .

Suppose T_a and T_b are the state transition tables for M_a and M_b . The state transition table T_p for the product machine M_p can be constructed by the following simple algorithm:

```

for each state a in  $Q_a$ 
  for each state b in  $Q_b$ 
    for each symbol r in  $\Sigma$ 
       $T_p[(a, b), r] = (T_a[a, r], T_b[b, r]);$ 
    
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Let N_a be the number of states in Q_a , N_b be the number of states in Q_b and N_Σ be the number of symbols in Σ . The running time of this commonly known algorithm is obviously $O(N_a N_b N_\Sigma)$.

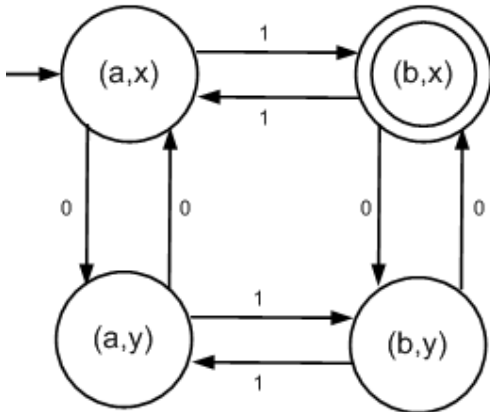


Fig.3 $M_3 =$ Product DFSM of M_1 and M_2

Table III. State Transition Table for M_3

	0	1
(a,x)	(a,y)	(b,x)
(a,y)	(a,x)	(b,y)
(b,x)	(b,y)	(a,x)
(b,y)	(b,x)	(a,y)

The machine M_3 shown in Fig. 3 is the product machine constructed from the two machines M_1 and M_2 given in the previous section. Table III shows the state transition table of M_3 constructed using the algorithm given above. Apparently, M_3 accepts those strings having an odd number of 1's **and** an even number of 0's.

A product machine that accepts the *union* of the languages of two machines M_1 and M_2 can be constructed in the same

way except that, in order for a state (a, b) of the product machine to be an accept state, at least one of the states a and b must be an accept state of M_a or M_b . As an example, if the three states of M_3 (a,x) , (b,x) and (b,y) are accept states, then M_3 will accept the union of the languages of M_1 and M_2 . That is, M_3 will accept those strings having an odd number of 1's or an even number of 0's.

IV. AVOIDING UNREACHABLE STATES

The algorithm discussed in the previous section may produce a product machine that has states that cannot be reached from its start state. Removing the unreachable states of a machine does not alter the function of the machine.

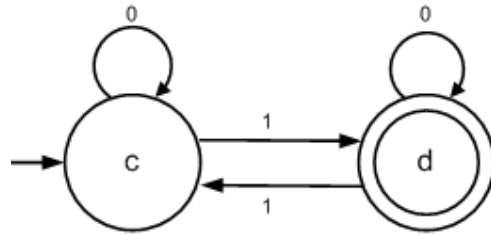


Fig.4 $M_4 = (\{c, d\}, \{0, 1\}, \delta_a, c, \{d\})$

Table IV. State Transition Table for M_4

	0	1
c	c	d
d	d	c

As an example, consider the machine M_4 shown in Fig. 4 and its state transition table in Table IV. To make the example simple, the machine M_4 is obtained by renaming the states of M_1 and accepts the same language as M_1 .

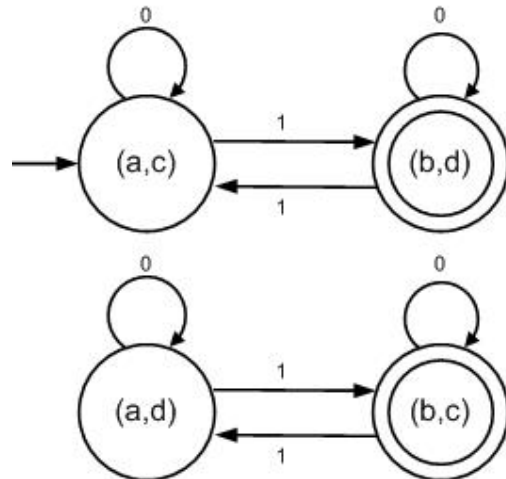


Fig.5 A Product Machine with Unreachable States

The product machine of M_1 and M_4 constructed using the algorithm discussed in the previous section to accept the intersection of the languages of M_1 and M_4 is shown in Fig. 5. Indeed, the product machine functions correctly: it accepts the strings that both M_1 and M_4 accept, but it includes the

unreachable states (a, d) and (b, c), which can be eliminated without changing the function of the machine.

An algorithm that constructs a product machine that does not include unreachable states will now be presented. Suppose T_a and T_b are the state transition tables for two machines M_a and M_b , whose product machine is to be constructed. The algorithm will produce a product machine M_p . M_p initially has no transitions and only one state: the start state, which is the pair that consists of the start states of M_a and M_b . As the algorithm proceeds, more states and transitions will be added to M_p . When the algorithm terminates, M_p will be the product machine of M_a and M_b with no unreachable states. The algorithm also makes use of a set R , which initially contains the start state of M_p . The purpose of using the set R is to keep track of those states in M_p whose outgoing transitions have yet to be added to M_p . The algorithm is given below.

```
repeat the following
{
  remove a state (a,b) from R;
  for each symbol r in  $\Sigma$  do the following
  {
    if  $(T_a[a,r], T_b[b,r])$  is not in  $M_p$ 
      add  $(T_a[a, r], T_b[b, r])$  to  $M_p$  and to R; //end if
    add to  $M_p$  a transition on r from (a,b) to  $(T_a[a,r], T_b[b,r])$ ;
  } //end for-each
}
until R is empty; //end repeat-until
```

The *if* statement in the algorithm guarantees that each state is added to M_p and R only once. It is worth noting that a new state is added to M_p if and only if there is a transition from a state already in M_p to the new state. Since initially the start state is the only state in M_p , all of the states of M_p are reachable from the start state.

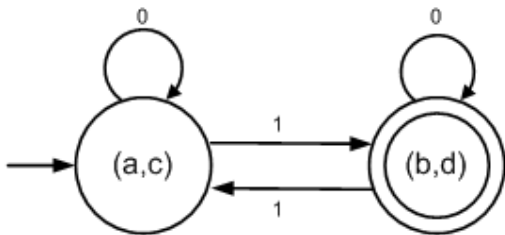


Fig.6 A Product Machine with No Unreachable States

As an example of using the algorithm, suppose the product machine of M_1 and M_4 is to be constructed by the above algorithm. Let T_1 and T_4 be the transition tables of M_1 and M_4 . Initially R and M_p contain only the state (a,c). As the algorithm begins, (a,c) is removed from R . For the symbol 0, since the state $(T_1[a,0], T_2[c,0]) = (a,c)$ is already in M_p , (a,c) is not added to M_p or R . The transition from (a,c) to (a,c) on the symbol 0 is then added to M_p . For the symbol 1, since the state $(T_1[a,1], T_2[c,1]) = (b,d)$ is not in M_p , (b,d) is added to M_p and R . The transition from (a,c) to (b,d) on the symbol 1 is then added to M_p . Since R is not empty, another iteration of the *repeat-until* loop begins. The state (b,d) is removed from

R . For the symbol 0, since the state $(T_1[b,0], T_2[d,0]) = (b,d)$ is already in M_p , (b,d) is not added to M_p or R . The transition from (b,d) to (b,d) on the symbol 0 is then added to M_p . For the symbol 1, since the state $(T_1[b,1], T_2[d,1]) = (a,c)$ is already in M_p , (a,c) is not added to M_p or R . The transition from (b,d) to (a,c) on the symbol 1 is then added to M_p . The *repeat-until* loop then terminates because R is now empty. The resultant product machine M_p is shown in Fig. 6. Obviously, the product machine has no unreachable state and, as expected, it accepts the same language as M_1 and M_4 do.

The *if* statement requires searching the set of states in M_p . Let E be the number of transitions in the product machine (i.e., the number of arrows in its state diagram) and N_Σ be the number of symbols in the alphabet. The number of states is E/N_Σ because every state has N_Σ outgoing transitions. With an efficient implementation, searching a set of E/N_Σ elements takes $O(\log(E/N_\Sigma))$ time. An analysis shows that searching is performed for every transition added, and the algorithm takes $O(E \log(E/N_\Sigma))$ time.

V. SUMMARY

Two algorithms to construct a product machine from two finite-state machines are presented and analyzed. The first algorithm is simple and correctly produces a product machine but the product machine may include unreachable states and associated transitions. The second algorithm produces a functionally correct product machine that has no unreachable states.

REFERENCES

- [1] M. Sipser, *Introduction to the Theory of Computation*. Boston: Thomson Course Technology, 2006, ch.1.