

Periodic Solutions in Shifts Delta(+/-) for a Nabla Dynamic System of Nicholson’s Blowflies on Time Scales

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Abstract—In this paper, based on some properties of nabla exponential function $\hat{e}_p(t, t_0)$ and shift operators δ_{\pm} on time scales, by using Krasnoselskii’s fixed point theorem in a cone and some mathematical methods, sufficient conditions are established for the existence and nonexistence of positive periodic solutions in shifts δ_{\pm} for a nabla dynamic system of Nicholson’s blowflies on time scales of the following form:

$$x^{\nabla}(t) = -a(t)x(t) + \sum_{i=1}^m b_i(t)x(\delta_{-}(\tau_i, t))e^{-c_i(t)x(\delta_{-}(\tau_i, t))},$$

where $t \in \mathbb{T}, \mathbb{T} \subset \mathbb{R}$ is a periodic time scale in shifts δ_{\pm} with period $P \in [t_0, \infty)_{\mathbb{T}}$ and $t_0 \in \mathbb{T}$ is nonnegative and fixed. Finally, two numerical examples are presented to illustrate the feasibility and effectiveness of the results.

Index Terms—positive periodic solution; Nicholson’s blowflies model; nabla dynamic equation; shift operator; time scale.

I. INTRODUCTION

THE theory of time scales was introduced by S. Hilger [1] in order to unify, extend, and generalize ideas from discrete calculus, quantum calculus, and continuous calculus to arbitrary time scale calculus. A time scale is a nonempty arbitrary closed subset of reals. The time scales approach not only unifies differential and difference equations, but also solves some other problems such as a mix of stop-start and continuous behaviors [2,3] powerfully. Nowadays the theory on time scales has been widely applied to ecological dynamic systems.

In 1980, Gurney et al. [4] proposed a mathematical model

$$x'(t) = -\delta x(t) + px(t - \tau)e^{-ax(t - \tau)}$$

to describe the dynamics of Nicholson’s blowflies, where $x(t)$ is the size of the population at time t , p is the maximum per capita daily egg production, $1/a$ is the size at which the population reproduces at its maximum rate, δ is the per capita daily adult death rate, and τ is the generation time. Nicholson’s blowflies model and its analogous equations on time scales have attracted much attention in the past few years; see, for example, [5,6].

The existence problem of periodic solutions is of importance to biologists since most models deal with certain types of populations. In the paper of Kaufmann and Raffoul [7], the authors were the first to define the notion of periodic time

scales, by satisfying the additivity “there exists a $\omega > 0$ such that $t \pm \omega \in \mathbb{T}, \forall t \in \mathbb{T}$.” Under this additivity all periodic time scales are unbounded above and below. However, there are many time scales that are of interest to biologists and scientists such as $\overline{q^{\mathbb{Z}}}$ and $\cup_{k=1}^{\infty} [3^{\pm k}, 2.3^{\pm k}] \cup \{0\}$ which do not satisfy the additivity. To overcome such difficulties, Advivar introduced a new periodicity concept on time scales which does not oblige the time scale to be closed under the operation $t \pm \omega$ for a fixed $\omega > 0$. He defined a new periodicity concept with the aid of shift operators δ_{\pm} which are first defined in [8] and then generalized in [9].

In recent years, periodic solutions in shifts δ_{\pm} for some nonlinear dynamic equations on time scales with delta derivative have been studied by many authors; see, for example, [10-13]. However, to the best of our knowledge, there are few papers published on the existence of periodic solutions in shifts δ_{\pm} for a dynamic equation on time scales with nabla derivative.

Motivated by the above, in the present paper, we first study some properties of the nabla exponential function $\hat{e}_p(t, t_0)$ and shift operators δ_{\pm} on time scales, and then we consider the following nabla dynamic system of Nicholson’s blowflies on time scales:

$$x^{\nabla}(t) = -a(t)x(t) + \sum_{i=1}^m b_i(t)x(\delta_{-}(\tau_i, t))e^{-c_i(t)x(\delta_{-}(\tau_i, t))}, \quad (1)$$

where $t \in \mathbb{T}, \mathbb{T} \subset \mathbb{R}$ is a periodic time scale in shifts δ_{\pm} with period $P \in [t_0, \infty)_{\mathbb{T}}$ and $t_0 \in \mathbb{T}$ is nonnegative and fixed; $a, b_i \in C_{ld}(\mathbb{T}, (0, \infty))$ ($i = 1, 2, \dots, m$) are Δ -periodic in shifts δ_{\pm} with period ω and $-a \in \mathcal{R}^+$; $c_i \in C_{ld}(\mathbb{T}, (0, \infty))$ are periodic in shifts δ_{\pm} with period ω for $i = 1, 2, \dots, m$; τ_i ($i = 1, 2, \dots, m$) are fixed if $\mathbb{T} = \mathbb{R}$ and $\tau_i \in [P, \infty)_{\mathbb{T}}$ if \mathbb{T} is periodic in shifts δ_{\pm} with period P .

For convenience, we introduce the notation

$$f^* = \sup_{t \in [t_0, \delta_{+}^{\omega}(t_0)]_{\mathbb{T}}} f(t), \quad f_* = \inf_{t \in [t_0, \delta_{+}^{\omega}(t_0)]_{\mathbb{T}}} f(t),$$

where f is a positive and bounded periodic function.

Take the initial condition

$$x(s) = \phi(s), \phi \in C_{ld}([\delta_{-}(\tau^*, 0), 0]_{\mathbb{T}}, (0, \infty)), \phi \neq 0, \quad (2)$$

where $\tau^* = \max_{1 \leq i \leq m} \tau_i$.

It is easy to prove that the initial value problem (1) and (2) has a unique non-negative solution $x(t)$ on $[0, \infty)_{\mathbb{T}}$.

The main purpose of this paper is to establish sufficient conditions for the existence and nonexistence of positive

Manuscript received June 5, 2017; revised September 6, 2017. This work was supported in part by the Key Project of Scientific Research in Colleges and Universities in Henan Province (Nos.16A110008; 18A110005).

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periodic solutions in shifts δ_{\pm} of system (1) using Krasnosel'skii's fixed point theorem in a cone and some mathematical methods.

II. PRELIMINARIES

Let \mathbb{T} be a nonempty closed subset (time scale) of \mathbb{R} . The forward jump operator $\sigma : \mathbb{T} \rightarrow \mathbb{T}$ is defined by $\sigma(t) = \inf\{s \in \mathbb{T} : s > t\}$ for all $t \in \mathbb{T}$, while the backward jump operator $\rho : \mathbb{T} \rightarrow \mathbb{T}$ is defined by $\rho(t) = \sup\{s \in \mathbb{T} : s < t\}$ for all $t \in \mathbb{T}$.

A point $t \in \mathbb{T}$ is called left-dense if $t > \inf \mathbb{T}$ and $\rho(t) = t$, left-scattered if $\rho(t) < t$, right-dense if $t < \sup \mathbb{T}$ and $\sigma(t) = t$, and right-scattered if $\sigma(t) > t$. If \mathbb{T} has a left-scattered maximum m , then $\mathbb{T}^k = \mathbb{T} \setminus \{m\}$; otherwise $\mathbb{T}^k = \mathbb{T}$. If \mathbb{T} has a right-scattered minimum m , then $\mathbb{T}_k = \mathbb{T} \setminus \{m\}$; otherwise $\mathbb{T}_k = \mathbb{T}$. The backwards graininess function $\nu : \mathbb{T}_k \rightarrow [0, +\infty)$ is defined by $\nu(t) = t - \rho(t)$.

A function $f : \mathbb{T} \rightarrow \mathbb{R}$ is ld-continuous provided it is continuous at left-dense point in \mathbb{T} and its right-side limits exist at right-dense points in \mathbb{T} .

The function $p : \mathbb{T} \rightarrow \mathbb{R}$ is ν -regressive if $1 - \nu(t)p(t) \neq 0$ for all $t \in \mathbb{T}_k$. The set of all ν -regressive and ld-continuous functions $p : \mathbb{T} \rightarrow \mathbb{R}$ will be denoted by $\mathcal{R}_{\nu} = \mathcal{R}_{\nu}(\mathbb{T}, \mathbb{R})$. Define the set $\mathcal{R}_{\nu}^+ = \{p \in \mathcal{R}_{\nu} : 1 - \nu(t)p(t) > 0, \forall t \in \mathbb{T}\}$.

If p is a ν -regressive function, then the nabla exponential function \hat{e}_p is defined by

$$\hat{e}_p(t, s) = \exp \left\{ \int_s^t \hat{\xi}_{\nu(\tau)}(p(\tau)) \nabla \tau \right\}$$

for all $s, t \in \mathbb{T}$, with the cylinder transformation

$$\hat{\xi}_h(z) = \begin{cases} -\frac{\text{Log}(1-hz)}{h} & \text{if } h \neq 0, \\ z & \text{if } h = 0. \end{cases}$$

Lemma 1. [14] If $p \in \mathcal{R}_{\nu}$, and $a, b, c \in \mathbb{T}$, then

- (i) $\hat{e}_0(t, s) \equiv 1$ and $\hat{e}_p(t, t) \equiv 1$;
- (ii) $\hat{e}_p(\rho(t), s) = (1 - \nu(t)p(t))\hat{e}_p(t, s)$;
- (iii) $\hat{e}_p(t, s)\hat{e}_p(s, r) = \hat{e}_p(t, r)$;
- (iv) $(\hat{e}_p(t, s))^{\nabla} = p(t)\hat{e}_p(t, s)$;
- (v) $(\hat{e}_p(c, \cdot))^{\nabla} = -p(\hat{e}_p(c, \cdot))^{\rho}$ and $\int_a^b p(t)\hat{e}_p(c, \rho(t))\nabla t = \hat{e}_p(c, a) - \hat{e}_p(c, b)$;
- (vi) $\int_a^b f(\rho(t))g^{\nabla}(t)\nabla t = (fg)(b) - (fg)(a) - \int_a^b f^{\nabla}(t)g(t)\nabla t$.

For more details about the calculus on time scales, see [14].

Let \mathbb{T}^* be a non-empty subset of the time scale \mathbb{T} and $t_0 \in \mathbb{T}^*$ be a fixed number, define operators $\delta_{\pm} : [t_0, +\infty) \times \mathbb{T}^* \rightarrow \mathbb{T}^*$. The operators δ_+ and δ_- associated with $t_0 \in \mathbb{T}^*$ (called the initial point) are said to be forward and backward shift operators on the set \mathbb{T}^* , respectively. The variable $s \in [t_0, +\infty)_{\mathbb{T}}$ in $\delta_{\pm}(s, t)$ is called the shift size. The value $\delta_+(s, t)$ and $\delta_-(s, t)$ in \mathbb{T}^* indicate s units translation of the term $t \in \mathbb{T}^*$ to the right and left, respectively. The sets

$$\mathbb{D}_{\pm} := \{(s, t) \in [t_0, +\infty)_{\mathbb{T}} \times \mathbb{T}^* : \delta_{\mp}(s, t) \in \mathbb{T}^*\}$$

are the domains of the shift operator δ_{\pm} , respectively. Hereafter, \mathbb{T}^* is the largest subset of the time scale \mathbb{T} such that the shift operators $\delta_{\pm} : [t_0, +\infty) \times \mathbb{T}^* \rightarrow \mathbb{T}^*$ exist.

Definition 1. [15] (Periodicity in shifts δ_{\pm}) Let \mathbb{T} be a time scale with the shift operators δ_{\pm} associated with the initial

point $t_0 \in \mathbb{T}^*$. The time scale \mathbb{T} is said to be periodic in shifts δ_{\pm} if there exists $p \in (t_0, +\infty)_{\mathbb{T}^*}$ such that $(p, t) \in \mathbb{D}_{\pm}$ for all $t \in \mathbb{T}^*$. Furthermore, if

$$P := \inf\{p \in (t_0, +\infty)_{\mathbb{T}^*} : (p, t) \in \delta_{\pm}, \forall t \in \mathbb{T}^*\} \neq t_0,$$

then P is called the period of the time scale \mathbb{T} .

Definition 2. [15] (Periodic function in shifts δ_{\pm}) Let \mathbb{T} be a time scale that is periodic in shifts δ_{\pm} with the period P . We say that a real-valued function f defined on \mathbb{T}^* is periodic in shifts δ_{\pm} if there exists $\omega \in [P, +\infty)_{\mathbb{T}^*}$ such that $(\omega, t) \in \mathbb{D}_{\pm}$ and $f(\delta_{\pm}^{\omega}(t)) = f(t)$ for all $t \in \mathbb{T}^*$, where $\delta_{\pm}^{\omega} := \delta_{\pm}(\omega, t)$. The smallest number $\omega \in [P, +\infty)_{\mathbb{T}^*}$ is called the period of f .

Definition 3. (∇ -periodic function in shifts δ_{\pm}) Let \mathbb{T} be a time scale that is periodic in shifts δ_{\pm} with the period P . We say that a real-valued function f defined on \mathbb{T}^* is ∇ -periodic in shifts δ_{\pm} if there exists $\omega \in [P, +\infty)_{\mathbb{T}^*}$ such that $(\omega, t) \in \mathbb{D}_{\pm}$ for all $t \in \mathbb{T}^*$, the shifts δ_{\pm}^{ω} are ∇ -differentiable with ld-continuous derivatives and $f(\delta_{\pm}^{\omega}(t))\delta_{\pm}^{\nabla\omega}(t) = f(t)$ for all $t \in \mathbb{T}^*$, where $\delta_{\pm}^{\omega} := \delta_{\pm}(\omega, t)$. The smallest number $\omega \in [P, +\infty)_{\mathbb{T}^*}$ is called the period of f .

Similar to the proofs of Lemma 2, Corollary 1 and Theorem 2 in [15], we can get the following two lemmas.

Lemma 2. $\delta_+^{\omega}(\rho(t)) = \rho(\delta_+^{\omega}(t))$ and $\delta_-^{\omega}(\rho(t)) = \rho(\delta_-^{\omega}(t))$ for all $t \in \mathbb{T}^*$.

Lemma 3. Let \mathbb{T} be a time scale that is periodic in shifts δ_{\pm} with the period P , and let f be a ∇ -periodic function in shifts δ_{\pm} with the period $\omega \in [P, +\infty)_{\mathbb{T}^*}$. Assume that $f \in C_{ld}(\mathbb{T})$, then

$$\int_{t_0}^t f(s)\nabla s = \int_{\delta_{\pm}^{\omega}(t_0)}^{\delta_{\pm}^{\omega}(t)} f(s)\nabla s.$$

Lemma 4. [16] Let \mathbb{T} be a time scale that is periodic in shifts δ_{\pm} with the period P . Assume that the shifts δ_{\pm}^{ω} are ∇ -differentiable on $t \in \mathbb{T}^*$ where $\omega \in [P, +\infty)_{\mathbb{T}^*}$. Then the ν -graininess function $\nu : \mathbb{T} \rightarrow [0, +\infty)$ satisfies

$$\nu(\delta_{\pm}^{\omega}(t)) = \delta_{\pm}^{\nabla\omega}(t)\nu(t).$$

Lemma 5. [16] Let \mathbb{T} be a time scale that is periodic in shifts δ_{\pm} with the period P . Assume that the shifts δ_{\pm}^{ω} are ∇ -differentiable on $t \in \mathbb{T}^*$ where $\omega \in [P, +\infty)_{\mathbb{T}^*}$ and $p \in \mathcal{R}_{\nu}$ is ∇ -periodic in shifts δ_{\pm} with the period ω . Then

- (i) $\hat{e}_p(\delta_{\pm}^{\omega}(t), \delta_{\pm}^{\omega}(t_0)) = \hat{e}_p(t, t_0)$ for $t, t_0 \in \mathbb{T}^*$;
- (ii) $\hat{e}_p(\delta_{\pm}^{\omega}(t), \rho(\delta_{\pm}^{\omega}(s))) = \hat{e}_p(t, \rho(s)) = \frac{\hat{e}_p(t, s)}{1 - \nu(t)p(t)}$ for $t, s \in \mathbb{T}^*$.

Lemma 6. [14] Assume that r is ν -regressive and $f : \mathbb{T} \rightarrow \mathbb{R}$ is ld-continuous. Let $t_0 \in \mathbb{T}$, $y_0 \in \mathbb{R}$, then the unique solution of the initial value problem

$$y^{\nabla} = r(t)y + f(t), \quad y(t_0) = y_0$$

is given by

$$y(t) = \hat{e}_r(t, t_0)y_0 + \int_{t_0}^t \hat{e}_r(t, \rho(\tau))f(\tau)\nabla\tau.$$

Set

$$X = \{x : x \in C_{ld}(\mathbb{T}, \mathbb{R}), x(\delta_+^{\omega}(t)) = x(t)\}$$

with the norm $\|x\| = \sup_{t \in [t_0, \delta_+^\omega(t)]_{\mathbb{T}}} |x(t)|$, then X is a Banach space.

Lemma 7. *The function $x(t) \in X$ is an ω -periodic solution in shifts δ_{\pm} of system (1) if and only if $x(t)$ is an ω -periodic solution in shifts δ_{\pm} of*

$$x(t) = \int_t^{\delta_+^\omega(t)} G(t, s) \sum_{i=1}^m b_i(s) x(\delta_-(\tau_i, s)) \times e^{-c_i(s)x(\delta_-(\tau_i, s))} \nabla s, \tag{3}$$

where

$$G(t, s) = \frac{\hat{e}_{-a}(t, \rho(s))}{\hat{e}_{-a}(t_0, \delta_+^\omega(t_0)) - 1}.$$

Proof: If $x(t)$ is an ω -periodic solution in shifts δ_{\pm} of system (1). By using Lemmas 1 and 6, for any $s \in [t, \delta_+^\omega(t)]_{\mathbb{T}}$, we have

$$x(s) = \hat{e}_{-a}(s, t)x(t) + \int_t^s \hat{e}_{-a}(s, \rho(\theta)) \times \sum_{i=1}^m b_i(\theta)x(\delta_-(\tau_i, \theta))e^{-c_i(\theta)x(\delta_-(\tau_i, \theta))} \nabla \theta.$$

Let $s = \delta_+^\omega(t)$ in the above equality, we have

$$x(\delta_+^\omega(t)) = \hat{e}_{-a}(\delta_+^\omega(t), t)x(t) + \int_t^{\delta_+^\omega(t)} \hat{e}_{-a}(\delta_+^\omega(t), \rho(\theta)) \times \sum_{i=1}^m b_i(\theta)x(\delta_-(\tau_i, \theta))e^{-c_i(\theta)x(\delta_-(\tau_i, \theta))} \nabla \theta.$$

Noticing that $\hat{e}_{-a}(t, \delta_+^\omega(t)) = \hat{e}_{-a}(t_0, \delta_+^\omega(t_0))$, $x(\delta_+^\omega(t)) = x(t)$, by Lemma 1, then $x(t)$ satisfies (3).

Let $x(t)$ be an ω -periodic solution in shifts δ_{\pm} of (3). By (3) and Lemmas 1, 2 and 5, we have

$$\begin{aligned} x^\nabla(t) &= -a(t)x(t) \\ &+ G(\rho(t), \delta_+^\omega(t)) \sum_{i=1}^m b_i(\delta_+^\omega(t)) \delta_+^{\nabla\omega}(t) \\ &\times x(\delta_-(\tau_i, \delta_+^\omega(t))) e^{-c_i(\delta_+^\omega(t))x(\delta_-(\tau_i, \delta_+^\omega(t)))} \\ &- G(\rho(t), t) \sum_{i=1}^m b_i(t)x(\delta_-(\tau_i, t)) \\ &\times e^{-c_i(t)x(\delta_-(\tau_i, t))} \\ &= -a(t)x(t) \\ &+ \sum_{i=1}^m b_i(t)x(\delta_-(\tau_i, t))e^{-c_i(t)x(\delta_-(\tau_i, t))}. \end{aligned}$$

So, $x(t)$ is an ω -periodic solution in shifts δ_{\pm} of system (1). This completes the proof. ■

It is easy to verify that the Green's function $G(t, s)$ satisfies the property

$$0 < \frac{1}{\xi - 1} \leq G(t, s) \leq \frac{\xi}{\xi - 1}, \quad \forall s \in [t, \delta_+^\omega(t)]_{\mathbb{T}}, \tag{4}$$

where $\xi = \hat{e}_{-a}(t_0, \delta_+^\omega(t_0))$. By Lemma 5, we have

$$G(\delta_+^\omega(t), \delta_+^\omega(s)) = G(t, s), \quad \forall t \in \mathbb{T}^*, s \in [t, \delta_+^\omega(t)]_{\mathbb{T}}. \tag{5}$$

Define K , a cone in X , by

$$K = \{x \in X : x(t) \geq \frac{1}{\xi} \|x\|, \forall t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}\} \tag{6}$$

and an operator $H : K \rightarrow X$ by

$$(Hx)(t) = \int_t^{\delta_+^\omega(t)} G(t, s) \sum_{i=1}^m b_i(s)x(\delta_-(\tau_i, s)) \times e^{-c_i(s)x(\delta_-(\tau_i, s))} \nabla s. \tag{7}$$

In the following, we shall give some lemmas concerning K and H defined by (6) and (7), respectively.

Lemma 8. $H : K \rightarrow K$ is well defined.

Proof: For any $x \in K$, $t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}$. In view of (7), by Lemma 3 and (5), we have

$$\begin{aligned} (Hx)(\delta_+^\omega(t)) &= \int_{\delta_+^\omega(t)}^{\delta_+^\omega(\delta_+^\omega(t))} G(\delta_+^\omega(t), s) \sum_{i=1}^m b_i(s)x(\delta_-(\tau_i, s)) \\ &\times e^{-c_i(s)x(\delta_-(\tau_i, s))} \nabla s \\ &= \int_t^{\delta_+^\omega(t)} G(\delta_+^\omega(t), \delta_+^\omega(s)) \sum_{i=1}^m b_i(\delta_+^\omega(s)) \delta_+^{\nabla\omega}(s) \\ &\times x(\delta_-(\tau_i, \delta_+^\omega(s))) e^{-c_i(\delta_+^\omega(s))x(\delta_-(\tau_i, \delta_+^\omega(s)))} \nabla s \\ &= \int_t^{\delta_+^\omega(t)} G(t, s) \sum_{i=1}^m b_i(s)x(\delta_-(\tau_i, s)) \\ &\times e^{-c_i(s)x(\delta_-(\tau_i, s))} \nabla s \\ &= (Hx)(t), \end{aligned}$$

that is, $Hx \in X$.

Furthermore, for any $x \in K$, $t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}$, we have

$$\begin{aligned} (Hx)(t) &\geq \frac{1}{\xi - 1} \int_t^{\delta_+^\omega(t)} \sum_{i=1}^m b_i(s)x(\delta_-(\tau_i, s)) \\ &\times e^{-c_i(s)x(\delta_-(\tau_i, s))} \nabla s \\ &= \frac{1}{\xi} \cdot \frac{\xi}{\xi - 1} \int_{t_0}^{\delta_+^\omega(t_0)} \sum_{i=1}^m b_i(s)x(\delta_-(\tau_i, s)) \\ &\times e^{-c_i(s)x(\delta_-(\tau_i, s))} \nabla s \\ &\geq \frac{1}{\xi} \|Hx\|, \end{aligned}$$

that is, $Hx \in K$. This completes the proof. ■

Lemma 9. $H : K \rightarrow K$ is completely continuous.

Proof: Clearly, H is continuous on $[t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}$. For any $x \in K$, $t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}$,

$$\begin{aligned} \|Hx\| &= \sup_{t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}} (Hx)(t) \\ &\leq \frac{\xi}{\xi - 1} \int_{t_0}^{\delta_+^\omega(t_0)} \sum_{i=1}^m b_i(s)x(\delta_-(\tau_i, s)) \\ &\times e^{-c_i(s)x(\delta_-(\tau_i, s))} \nabla s \\ &< \frac{\xi}{\xi - 1} \cdot \frac{B}{c_*} := M_1, \end{aligned} \tag{8}$$

where

$$c_* = \min_{1 \leq i \leq m} c_{i*}, \quad B := \int_{t_0}^{\delta_+^\omega(t_0)} \sum_{i=1}^m b_i(s) \nabla s.$$

Furthermore, for $t \in \mathbb{T}$, we have

$$\begin{aligned} (Hx)^\nabla(t) &= -a(t)(Hx)(t) \\ &+ \sum_{i=1}^m b_i(t)x(\delta_-(\tau_i, t))e^{-c_i(t)x(\delta_-(\tau_i, t))}, \end{aligned}$$

and

$$\begin{aligned} \|(Hx)^\nabla(t)\| &= \sup_{t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}} | -a(t)(Hx)(t) \\ &\quad + \sum_{i=1}^m b_i(t)x(\delta_-(\tau_i, t))e^{-c_i(t)x(\delta_-(\tau_i, t))} | \\ &\leq a^*M_1 + \frac{1}{c_*} \sum_{i=1}^m b_i^*. \end{aligned}$$

To sum up, $\{Hx : x \in K\}$ is a family of uniformly bounded and equicontinuous functionals on $[t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}$. By a theorem of Arzela-Ascoli, the functional H is completely continuous. This completes the proof. ■

III. EXISTENCE RESULT

In this section, we shall state and prove our main result about the existence of at least one positive periodic solution in shifts δ_\pm of system (1).

Lemma 10. (Guo-Krasnoselskii [17]) *Let X be a Banach space and $K \subset X$ be a cone in X . Assume that Ω_1, Ω_2 are bounded open subsets of X with $0 \in \Omega_1 \subset \bar{\Omega}_1 \subset \Omega_2$ and $H : K \cap (\bar{\Omega}_2 \setminus \Omega_1) \rightarrow K$ is a completely continuous operator such that, either*

- (1) $\|Hx\| \leq \|x\|, x \in K \cap \partial\Omega_1$, and $\|Hx\| \geq \|x\|, x \in K \cap \partial\Omega_2$; or
- (2) $\|Hx\| \geq \|x\|, x \in K \cap \partial\Omega_1$, and $\|Hx\| \leq \|x\|, x \in K \cap \partial\Omega_2$.

Then H has at least one fixed point in $K \cap (\bar{\Omega}_2 \setminus \Omega_1)$.

Lemma 11. *Let*

$$\sum_{i=1}^m b_i(t) > a(t), t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}. \tag{9}$$

Then there exist positive constants M_1 and M_2 such that for $x \in K$,

$$M_2 \leq \|Hx\| \leq M_1. \tag{10}$$

Proof: From (8), for any $x \in K, t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}$,

$$\|Hx\| \leq M_1. \tag{11}$$

From (9), there exists a $q > 1$ such that

$$\sum_{i=1}^m b_i(t) > qa(t), t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}. \tag{12}$$

For any $x \in K, t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}$,

$$\begin{aligned} (Hx)(t) &= \int_t^{\delta_+^\omega(t)} G(t, s) \sum_{i=1}^m b_i(s)x(\delta_-(\tau_i, s)) \\ &\quad \times e^{-c_i(s)x(\delta_-(\tau_i, s))} \nabla_s \\ &> q \int_{t_0}^{\delta_+^\omega(t_0)} \frac{a(s)\hat{e}_{-a}(t_0, \rho(s))}{\hat{e}_{-a}(t_0, \delta_+^\omega(t_0)) - 1} \\ &\quad \cdot \min_{1 \leq i \leq m} \inf_{s \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}} \{x(\delta_-(\tau_i, s))\} \\ &\quad \times e^{-c_i(s)x(\delta_-(\tau_i, s))} \nabla_s \\ &= q \int_{t_0}^{\delta_+^\omega(t_0)} \frac{1}{\hat{e}_{-a}(t_0, \delta_+^\omega(t_0)) - 1} \\ &\quad \cdot \min_{1 \leq i \leq m} \inf_{s \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}} \{x(\delta_-(\tau_i, s))\} \\ &\quad \times e^{-c_i(s)x(\delta_-(\tau_i, s))} \nabla [\hat{e}_{-a}(t_0, s)] \\ &\geq q \min\{x_*e^{-c^*x_*}, x^*e^{-c^*x^*}\}, \end{aligned} \tag{13}$$

where $c^* = \max_{1 \leq i \leq m} c_i^*$.

Comparing (3) with (7), we also have for $x \in K, t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}$,

$$x(t) > q \min\{x_*e^{-c^*x_*}, x^*e^{-c^*x^*}\},$$

which implies that

$$x_* > q \min\{x_*e^{-c^*x_*}, x^*e^{-c^*x^*}\}. \tag{14}$$

In the same way as (8), $x(t) \leq M_1$, which implies that

$$x^* \leq M_1. \tag{15}$$

If $\min\{x_*e^{-c^*x_*}, x^*e^{-c^*x^*}\} = x^*e^{-c^*x^*}$, then

$$(Hx)(t) > qM_1e^{-c^*M_1} := M_{21} > 0. \tag{16}$$

If $\min\{x_*e^{-c^*x_*}, x^*e^{-c^*x^*}\} = x_*e^{-c^*x_*}$, from (14), $x_* > qx_*e^{-c^*x_*}$, which implies that

$$x_* > \frac{\ln q}{c^*}.$$

From (13), we obtain

$$(Hx)(t) > q \frac{\ln q}{c^*} e^{-c^* \cdot \frac{\ln q}{c^*}} = \frac{\ln q}{c^*} := M_{22} > 0. \tag{17}$$

Let $M_2 = \min\{M_{21}, M_{22}\}$, then for $x \in K$,

$$\|Hx\| \geq M_2. \tag{18}$$

This completes the proof. ■

Theorem 1. *Assume that*

$$\sum_{i=1}^m b_i(t) > a(t), t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}.$$

Then system (1) has at least one positive ω -periodic solution in shifts δ_\pm .

Proof: Let

$$\Omega_1 = \{x \in X : \|x\| \leq M_2\},$$

and

$$\Omega_2 = \{x \in X : \|x\| \leq M_1\}.$$

Clearly, Ω_1 and Ω_2 are open bounded subsets in X , and $\theta \in \Omega_1, \bar{\Omega}_1 \subset \Omega_2$. From Lemma 8, $H : K \cap (\bar{\Omega}_2 \setminus \Omega_1) \rightarrow K$ is completely continuous.

If $x \in K \cap \partial\Omega_2$, which implies that $\|x\| = M_1$, from Lemma 11, $\|Hx\| \leq M_1$. Hence $\|Hx\| \leq \|x\|$ for $x \in K \cap \partial\Omega_2$.

If $x \in K \cap \partial\Omega_1$, which implies that $\|x\| = M_2$, from Lemma 11, $\|Hx\| \leq M_2$. Hence $\|Hx\| \geq \|x\|$ for $x \in K \cap \partial\Omega_1$.

From the cone fixed point theorem (Lemma 10), the operator H has at least one fixed point lying in $K \cap (\bar{\Omega}_2 \setminus \Omega_1)$, i.e., system (1) has at least one positive ω -periodic solution in shifts δ_\pm . This completes the proof. ■

IV. NONEXISTENCE RESULT

In this section, we shall state and prove our main result about the nonexistence of positive periodic solution in shifts δ_{\pm} of system (1).

Lemma 12. Assume that

$$\sum_{i=1}^m b_i(t) \leq \frac{1}{2}a(t), t \in [t_0, \delta_+^{\omega}(t_0)]_{\mathbb{T}}. \quad (19)$$

Then every positive solution of system (1) tends to zero as $t \rightarrow \infty$.

Proof: Let $x(t)$ be any positive solution of system (1). By using Lemma 5, integrating system (1) from t_0 to $t(> t_0)$, we have

$$\begin{aligned} x(t) &= \hat{e}_{-a}(t, t_0)x(t_0) \\ &+ \int_{t_0}^t \hat{e}_{-a}(t, \rho(s)) \sum_{i=1}^m b_i(s)x(\delta_-(\tau_i, s)) \\ &\times e^{-c_i(s)x(\delta_-(\tau_i, s))} \nabla s. \end{aligned} \quad (20)$$

From (19),

$$\begin{aligned} x(t) &\leq \hat{e}_{-a}(t, t_0)x(t_0) + \frac{1}{2c_*} \int_{t_0}^t a(s)\hat{e}_{-a}(t, \rho(s))\nabla s \\ &= \hat{e}_{-a}(t, t_0)x(t_0) + \frac{1}{2c_*} \int_{t_0}^t \nabla[\hat{e}_{-a}(t, s)] \\ &= \hat{e}_{-a}(t, t_0)x(t_0) + \frac{1}{2c_*}[1 - \hat{e}_{-a}(t, t_0)]. \end{aligned}$$

Let $\beta = \limsup_{t \rightarrow \infty} x(t)$, then $0 \leq \beta < \infty$.

Next, we shall prove $\beta = 0$. We have some possible cases to consider.

Case 1. $x^{\nabla}(t) > 0$ eventually. Choose $t_0 > 0$ such that $x^{\nabla}(t) > 0$ for $t \geq t_0$. Let $\eta > 0$ be a sufficient large number with $\delta_-(\tau_i, t) > t_0, i = 1, 2, \dots, m$ for $t > t_0 + \eta$. Then $0 < x(\delta_-(\tau_i, t)) < x(t)$ for $t \geq t_0 + \eta$ and $i = 1, 2, \dots, m$. From (1), for $t \geq t_0 + \eta$,

$$\begin{aligned} 0 &< -a(t)x(t) + \sum_{i=1}^m b_i(t)x(\delta_-(\tau_i, t))e^{-c_i(t)x(\delta_-(\tau_i, t))} \\ &< \left[\sum_{i=1}^m b_i(t) - a(t) \right] x(t) < 0. \end{aligned}$$

This contradiction shows that Case 1 is impossible.

Case 2. $x^{\nabla}(t) < 0$ eventually. Choose $t_0 > 0$ such that $x^{\nabla}(t) < 0$ for $t \geq t_0$. Then $\beta < x(\delta_-(\tau_i, t)) < x(\delta_-(\tau_i, t_0))$ for $t \geq t_0 + \eta$ and $i = 1, 2, \dots, m$. From (19) and (20), we have

$$\begin{aligned} x(t) &\leq \hat{e}_{-a}(t, t_0)x(t_0) + \frac{1}{2} \max_{1 \leq i \leq m} x(\delta_-(\tau_i, t_0))e^{-c_*\beta} \\ &\times [1 - \hat{e}_{-a}(t, t_0)]. \end{aligned} \quad (21)$$

Let $t \rightarrow \infty$ in (21), we obtain

$$\beta \leq \frac{1}{2} \max_{1 \leq i \leq m} x(\delta_-(\tau_i, t_0))e^{-c_*\beta}. \quad (22)$$

Again let $t_0 \rightarrow \infty$ in (22), we have that $\beta \leq \beta(\frac{1}{2}e^{-c_*\beta})$, which implies that $\beta = 0$.

Case 3. $x^{\nabla}(t)$ is oscillatory. By the definition of oscillatory, then

(i) there exists $\{t_n\}$ with $t_n \rightarrow \infty$ as $n \rightarrow \infty$ such that

$$x^{\nabla}(t_n) = 0 \text{ and } \lim_{n \rightarrow \infty} x(t_n) = \beta;$$

or

(ii) there exists $\{t_n\}$ with $t_n \rightarrow \infty$ as $n \rightarrow \infty$ such that

$$\begin{aligned} x^{\nabla}(t_n)x^{\nabla}(\rho(t_n)) &< 0 \text{ for } n = 1, 2, \dots, \\ \text{and } \lim_{n \rightarrow \infty} x(t_n) &= \lim_{n \rightarrow \infty} x(\rho(t_n)) = \beta. \end{aligned}$$

In case (i), from (1),

$$\begin{aligned} &a(t_n)x(t_n) \\ &= \sum_{i=1}^m b_i(t_n)x(\delta_-(\tau_i, t_n))e^{-c_i(t_n)x(\delta_-(\tau_i, t_n))} \\ &\leq x(\delta_-(\tau_l, t_n))e^{-c_*x(\delta_-(\tau_l, t_n))} \sum_{i=1}^m b_i(t_n), \end{aligned} \quad (23)$$

where $l = l(n) \in \{1, 2, \dots, m\}$ such that

$$\begin{aligned} &x(\delta_-(\tau_l, t_n))e^{-c_*x(\delta_-(\tau_l, t_n))} \\ &= \max_{1 \leq i \leq m} x(\delta_-(\tau_i, t_n))e^{-c_i(t_n)x(\delta_-(\tau_i, t_n))}. \end{aligned}$$

From (19) and (23), we have

$$2x(t_n)e^{c_*x(\delta_-(\tau_l, t_n))} \leq x(\delta_-(\tau_l, t_n)). \quad (24)$$

Set $\alpha = \limsup_{n \rightarrow \infty} x(\delta_-(\tau_l, t_n))$, then $\alpha \leq \beta$. Finding the superior limit of both sides of (24), we obtain

$$\beta(2e^{c_*\alpha}) \leq \alpha,$$

then

$$\beta(2e^{c_*\alpha}) \leq \alpha \leq \beta,$$

which implies that $\beta = \alpha = 0$.

In case (ii), from (1),

$$\begin{aligned} &a(t_n)a(\rho(t_n))x(t_n)x(\rho(t_n)) \\ &+ \sum_{i=1}^m b_i(t_n)x(\delta_-(\tau_i, t_n))e^{-c_i(t_n)x(\delta_-(\tau_i, t_n))} \\ &\times \sum_{i=1}^m b_i(\rho(t_n))x(\delta_-(\tau_i, \rho(t_n))) \\ &\times e^{-c_i(\rho(t_n))x(\delta_-(\tau_i, \rho(t_n)))} \\ &< a(t_n)x(t_n) \sum_{i=1}^m b_i(\rho(t_n))x(\delta_-(\tau_i, \rho(t_n))) \\ &\times e^{-c_i(\rho(t_n))x(\delta_-(\tau_i, \rho(t_n)))} \\ &+ a(\rho(t_n))x(\rho(t_n)) \sum_{i=1}^m b_i(t_n)x(\delta_-(\tau_i, t_n)) \\ &\times e^{-c_i(t_n)x(\delta_-(\tau_i, t_n))} \\ &\leq [a(t_n)x(t_n) \sum_{i=1}^m b_i(\rho(t_n)) \\ &+ a(\rho(t_n))x(\rho(t_n)) \sum_{i=1}^m b_i(t_n)] \\ &\times x(\delta_-(\tau_l, \hat{t}_n))e^{-c_*x(\delta_-(\tau_l, \hat{t}_n))}, \end{aligned} \quad (25)$$

where $l = l(n) \in \{1, 2, \dots, m\}$, $\hat{t}_n = \{t_n, \rho(t_n)\}$, such that

$$\begin{aligned} &x(\delta_-(\tau_l, \hat{t}_n))e^{-c_*x(\delta_-(\tau_l, \hat{t}_n))} \\ &= \max_{1 \leq i \leq m} \{x(\delta_-(\tau_i, t_n))e^{-c_i(t_n)x(\delta_-(\tau_i, t_n))}, \\ &x(\delta_-(\tau_i, \rho(t_n)))e^{-c_i(\rho(t_n))x(\delta_-(\tau_i, \rho(t_n)))}\}. \end{aligned}$$

From (19) and (25), we have

$$2x(t_n)x(\rho(t_n))e^{c_*x(\delta_-(\tau_i, \hat{t}_n))} \leq [x(t_n) + x(\rho(t_n))]x(\delta_-(\tau_i, \hat{t}_n)). \quad (26)$$

Set $\alpha = \limsup_{n \rightarrow \infty} x(\delta_-(\tau_i, t_n))$, then $\alpha \leq \beta$. Finding the superior limit of both sides of (26), we obtain

$$\beta e^{c_*\alpha} \leq \alpha,$$

then

$$\beta e^{c_*\alpha} \leq \alpha \leq \beta,$$

which implies that $\beta = \alpha = 0$. This completes the proof. ■

From Lemma 12, we can get the following Theorem.

Theorem 2. Assume that the condition (19) hold. Then system (1) has no positive ω -periodic solution in shifts δ_{\pm} .

V. NUMERICAL EXAMPLES

Consider the following Nicholson's blowflies model on time scales \mathbb{T}

$$x^\nabla(t) = -a(t)x(t) + \sum_{i=1}^2 b_i(t)x(\delta_-(\tau_i, t))e^{-c_i(t)x(\delta_-(\tau_i, t))}. \quad (27)$$

Example 1. Take

$$\begin{aligned} a(t) &= a_0 + \frac{|\sin 2t + \cos 3t|}{2}, \\ b_1(t) &= e^{e-1}(10 + 0.005|\sin t|), \\ b_2(t) &= e^{e-1}(10 + 0.005|\cos t|), \\ c_1(t) &= c_2(t) = 0.25 + 0.025|\sin 3t + \cos 2t|. \end{aligned}$$

Let $\mathbb{T} = \mathbb{R}$, $t_0 = 0$, then $\omega = \pi$ and $\delta_+^\omega(t) = t + \pi$. It is easy to verify $a(t)$, $b_i(t)$, $c_i(t)$ ($i = 1, 2$) satisfy

$$\begin{aligned} a(\delta_+^\omega(t))\delta_+^{\nabla\omega}(t) &= a(t), \quad b_i(\delta_+^\omega(t))\delta_+^{\nabla\omega}(t) = b_i(t), \\ c_i(\delta_+^\omega(t)) &= c_i(t), \quad \forall t \in \mathbb{T}^*, \quad i = 1, 2, \end{aligned}$$

and $-a \in \mathcal{R}^+$.

Case I. If $a_0 = 18$, by a direct calculation, we can get

$$\sum_{i=1}^2 b_i(t) \geq 20e^{e-1} > a(t), t \in \mathbb{R}.$$

According to Theorem 1, when $\mathbb{T} = \mathbb{R}$, system (27) exists at least one positive π -periodic solution in shifts δ_{\pm} .

Case II. If $a_0 = 240$, by a direct calculation, we can get

$$\sum_{i=1}^2 b_i(t) \leq 20.02e^{e-1} < \frac{1}{2}a(t), t \in \mathbb{R}.$$

According to Theorem 2, when $\mathbb{T} = \mathbb{R}$, system (27) has no positive periodic solution in shifts δ_{\pm} .

Example 2. Take

$$\begin{aligned} a(t) &= \frac{1}{a_0 t}, \quad b_1(t) = \frac{1}{2t}, \quad b_2(t) = \frac{1}{3t}, \\ c_1(t) &= c_2(t) = 0.25. \end{aligned}$$

Let $\mathbb{T} = 2^{\mathbb{N}_0}$, $t_0 = 1$, then $\omega = 4$ and $\delta_+^\omega(t) = 4t$. It is easy to verify $a(t)$, $b_i(t)$, $c_i(t)$ ($i = 1, 2$) satisfy

$$\begin{aligned} a(\delta_+^\omega(t))\delta_+^{\nabla\omega}(t) &= a(t), \quad b_i(\delta_+^\omega(t))\delta_+^{\nabla\omega}(t) = b_i(t), \\ c_i(\delta_+^\omega(t)) &= c_i(t), \quad \forall t \in \mathbb{T}^*, \quad i = 1, 2, \end{aligned}$$

and $-a \in \mathcal{R}^+$.

Case I. If $a_0 = 6$, by a direct calculation, we can get

$$\sum_{i=1}^2 b_i(t) = \frac{5}{6t} > a(t), t \in 2^{\mathbb{N}_0}.$$

According to Theorem 1, when $\mathbb{T} = 2^{\mathbb{N}_0}$, system (27) exists at least one positive 4-periodic solution in shifts δ_{\pm} .

Case II. If $a_0 = \frac{1}{2}$, by a direct calculation, we can get

$$\sum_{i=1}^2 b_i(t) = \frac{5}{6t} < \frac{1}{2}a(t), t \in 2^{\mathbb{N}_0}.$$

According to Theorem 2, when $\mathbb{T} = 2^{\mathbb{N}_0}$, system (27) has no positive periodic solution in shifts δ_{\pm} .

VI. CONCLUSION

Two problems for a Nicholson's blowflies model with time delays on time scales have been studied, namely, existence and nonexistence of positive periodic solutions in shifts δ_{\pm} on time scales. It is important to notice that the methods used in this paper can be extended to other types of biological models; see, for example, [18-20]. Future work will include biological dynamic systems modeling and analysis on time scales.

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