

# Properties of a Class of Self-Maps in Metric Spaces Under Perturbations

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**Abstract-** This paper investigates self-maps  $T: X \rightarrow X$  which satisfy a distance constraint in a metric space which mixed eventually point-dependent non-expansive properties, or in particular contractive ones, and potentially expansive properties related to some distance threshold. The above mentioned distance constraint is feasible in certain real-world problems by representing, for instance, either parametrical uncertainties or perturbations.

**Index terms-** contractive maps, non-expansive maps, metric space, fixed points.

## I. INTRODUCTION

Fixed point theory and related techniques are of increasing interest for solving a wide class of mathematical problems where convergence of a trajectory or sequence to some equilibrium set is essential. Recently, the subsequent set of more sophisticated related problems are under strong research activity:

1) In the, so-called,  $p$ -cyclic non-expansive or contractive self-maps map each element of a subset  $A_i$  of an either metric or Banach space  $\mathbf{B}$  to an element of the next subset  $A_{i+1}$  in a strictly ordered chain of  $p$  subsets of  $\mathbf{B}$  such that  $A_{p+1} = A_1$ . If the subsets do not intersect then fixed points

do not exist and their potential relevance in Analysis is played by best proximity points, [1-2]. Best proximity points are also of interest in hyperconvex metric spaces, [3-4].

2) The so-called Kannan maps are also being intensively investigated in the last years as well as their relationships with contractive maps. See, for instance, [5-6], [11].

3) Although there is an increasing number of theorems about fixed points in Banach or metric spaces, new related recent results have been proven. Some of those novel results are, for instance, the generalization in [7] of Edelstein's fixed point theorem for metric spaces by proving a new theorem. Also, an iterative algorithm for searching a fixed point in a closed convex subset of a Banach space has been proposed in [8]. On the other hand, an estimation of the size of an attraction

ball to a fixed point has been provided in [9] for nonlinear differentiable maps.

4) Fixed point theory can be also used successfully to find oscillations of solutions of differential or difference equations which can be themselves characterized as fixed points. See, for instance, [9-10], [13-14].

This manuscript is devoted to investigate self-maps  $T: X \rightarrow X$  in a metric space  $(X, d)$  which satisfy the constraint  $d(Tx, Ty) - d(x, y) \leq -Kd(x, y) + M$ ; for some real constants  $K \geq 0, M \geq 0$ . It is direct to see that  $d(Tx, Ty) \leq d(x, y)$ ; i.e.  $T: X \rightarrow X$  is non-expansive, if  $d(x, y) \geq M/K$ . Also,

$$\begin{aligned} d(x, y) < M/K \\ \Rightarrow d(Tx, Ty) &\leq (1-K)d(x, y) + M < M/K \\ &\quad ; \forall x, y \in X \end{aligned} \quad (1.1)$$

Then, the self-map  $T: X \rightarrow X$  exhibits the following constraint under (1.1) provided that it is continuous:  $T: A_{xy} \rightarrow A_{\omega z}$  where  $A_{xy} \subset X$  is the open circle of center  $c_{xy} \in X$  of radius  $R := M/K$  for each given  $x, y \in A_{xy}$  and  $A_{\omega z} \subset X$  is an open circle of center at some  $c_{\omega z} \in X$  also of radius  $R$ . Note that  $A_{xy}$  can be distinct from  $A_{\omega z}$ . However, if  $T: X \rightarrow X$  is not continuous then the existence of the above circles is not ensured but only that (1.1) holds. Note that (1.1) does not guarantee that, contrarily to the case of large distances fulfilling  $d(x, y) \geq M/K$ , the self-map  $T: X \rightarrow X$  cannot be guaranteed to be non-expansive, while it can be eventually expansive, for small distances fulfilling  $d(x, y) < M/K; x, y \in X$ . The objective of this paper is the investigation of self-maps  $T: X \rightarrow X$  which such mixed properties related to some distance threshold.

## II. DISTANCE PROPERTY AND EXAMPLE

Let  $(X, d)$  be a metric space and  $T$  a self-map from  $X$  to  $X$ . Such a self-map is uncertain in the sense that the distance is subject to the following constraint:

$$\begin{aligned} d(Tx, Ty) - d(x, y) &\leq -Kd(x, y) + M \\ ; \forall x, y \in X, \text{ some real constants } K &\geq 0, M \geq 0 \end{aligned} \quad (2.1)$$

In order to discuss the feasibility of (2.1), note the following:

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1) If  $M = 0$  and  $K \in (0, 1]$  then (2.1) is the usual contractive constraint of Banach contraction principle and  $T : X \rightarrow X$  is strictly contractive. If  $K = M = 0$  then  $T : X \rightarrow X$  is non-expansive. If  $M = 0$ ,  $K = 1$  and the inequality in (2.1) is strict for  $x, y (\neq x) \in X$  then  $T : X \rightarrow X$  is weakly contractive.

2) If  $K=1$  then  $d(Tx, Ty) \leq M$ ;  $\forall x, y \in X$ . Since T is a self-map on X, the validity of the constraint (2.1) is limited to the set family:

$$\hat{A}_T := \{A_i \subset X : (\text{diam}(A_i) \leq M \wedge T(A_i) \subset A_i; \text{some } A_j \in \hat{A}_T)\}$$

of bounded subsets of X. In this case,  $d(T^j x, T^j y) \leq M$ ;  $\forall j \in \mathbf{Z}_+$  provided that  $x, y \in A_\alpha \in \hat{A}_T$  and T maps X to some member  $A_i$  of  $\hat{A}_T$  for each given  $x, y \in X$ . In other words, the image of T is restricted as  $T : X \rightarrow X | A_i$  (for some  $A_i \in \hat{A}_T$  which depends, in general, on x and y) so that  $d(Tx, Ty) \leq M$  in order to (2.1) to be feasible, i.e.  $Tx, Ty$  are in some set of the family  $\hat{A}_T$  if the pair x, y in X is such that  $d(x, y) > M$ . Note that  $T : X \rightarrow X$  is not necessarily a retraction from X to some element of  $\hat{A}_T$  since  $T(A_i) \subseteq A_j$  for  $A_i, A_j (\neq A_i) \in \hat{A}_T$ . Note that  $T : X \rightarrow X | A_i$  can possess a fixed point if  $K=1$  and ((2.1) holds.

3) If  $K > 1$  then  $d(Tx, Ty) \leq M$  if  $x = y$ ;  $x, y \in X$ , and  $d(x, y) \geq M / (K - 1) \Rightarrow 0 \leq d(Tx, Ty) \leq d(x, y) - \frac{M}{K - 1} < d(x, y)$  if  $x, y (\neq x) \in X$

Then if  $x, y \in X$  exist such that  $d(x, y) \in \left(0, \frac{M}{K - 1}\right)$  then

(2.1) is impossible for any self-map T on X since it would imply  $d(Tx, Ty) < 0$ . For  $x = y$ , (2.1) holds for self-maps T on X such that  $d(Tx, Ty) \leq M$ . Fixed points can exist only in trivial cases as, for instance,

$$X := \left\{x : d(x, y) \geq \frac{M}{K - 1}; \forall y \in X\right\}$$

is a set of isolated points with a minimum pair-wise distance threshold so that  $T : X \rightarrow X$  is such that  $T(y) = x \in X$ ;  $\forall y \in X$ .

4) The case of interest discussed through this paper for (2.1) is when  $M > 0$  and  $K \in [0, 1)$ . It is shown that the self-map  $T : X \rightarrow X$  exhibits contractive properties for sufficiently large distances which exceed a minimum real threshold while it might possibly be expansive for distances under such a threshold. A related motivating example follows.

*Example 2.1:* Note that (2.1) is equivalent to :

$$d(Tx, Ty) \leq (1 - K)d(x, y) + M; \forall x, y \in X, \text{ for some } M > 0 \quad (2.2)$$

Eq. 2.1 is relevant, for instance, in the following important problem. Let a linear time-invariant n-th order dynamic system be:

$$\dot{x}(t) = Ax(t) + \eta_x(t) \quad (2.3)$$

with  $A \in \mathbf{R}^{n \times n}$  being a stability matrix whose fundamental matrix satisfies  $\|e^{At}\| \leq K_0 e^{-\alpha_0 t}$ ;  $\forall t \geq 0$  for some positive real constants  $K_0$  (being norm-dependent) and  $\alpha_0$  and  $\eta : [0, \infty) \times X \rightarrow \mathbf{R}^n$  being an unknown uniformly bounded perturbation of essential supremum bound satisfying  $\text{ess sup}_{\infty > t \geq 0} \|\eta_x(t)\| \leq M_0 < \infty$ ;  $\forall x \in X$ . The unique solution of (2.3) for  $x(0) = x_0$  is:

$$x(t) = e^{At} x_0 + \int_0^t e^{A(t-\tau)} \eta_x(\tau) d\tau \quad (2.4)$$

Direct calculation with (2.4) for the norm-induced distance

$$\begin{aligned} d(x, y) &:= \|x - y\|; \forall x, y \in X \text{ yields:} \\ d(x(t), y(t)) &= \|x(t) - y(t)\| \leq K_0 e^{-\alpha_0 t} \|x_0 - y_0\| \\ &\quad + \frac{K_0}{\alpha_0} \sup_{0 \leq \tau < \infty} \|\eta_x(\tau) - \eta_y(\tau)\| \\ &\leq (1 - K)d(x_0, y_0) + M; \\ \forall t \geq h_0 &:= \frac{1}{\alpha_0} \ln \frac{K_0}{1 - K} \end{aligned} \quad (2.5)$$

with  $\infty > M \geq \frac{2K_0 M_0}{\alpha_0}$ ,  $K := 1 - K_0 e^{-\alpha_0 h_0} \in (0, 1)$ .

Now, let  $X \subset \mathbf{R}^n$  the state space of (2.1), generated by (2.4), subject to  $x_0 \in X$  and  $(X, d)$  is a complete metric space. Define the state transformation

$$T_h x(kh) = x \left[ (k+1)h \right] \text{ on } X \text{ which generates the sequence of states } \{x(kh)\}_{k=0}^{\infty} \text{ being in } X \text{ if } x_0 \in X \text{ with}$$

$h$  being any real constant which satisfies  $h \geq h_0$ . Then, the self-map  $T_h : X \rightarrow X$  satisfies (2.1). Note that the system (2.3) is always globally Lyapunov stable for any bounded initial conditions in view of (2.5). If the perturbation is identically zero then the origin is globally asymptotically Lyapunov stable since A is a stability matrix. This follows also from (2.5) since the self-map  $T_h$  on X is a contraction which has zero as its unique fixed and equilibrium point so that  $x(kh + \tau) = e^{A\tau} x(kh) \rightarrow 0$  as  $k \rightarrow \infty$ ;  $\forall \tau \in [0, h)$ ;  $\forall h \geq h_0$ . Thus,  $x(t) \rightarrow 0$  as  $t \rightarrow \infty$ . However, in the presence of the perturbation, the origin is not globally asymptotically stable (although the system is globally stable) and it exhibits ultimate boundedness since for sufficiently

large distances  $d(T_h x(kh), T_h y(kh)) \geq \frac{M}{K}$  (respectively,  $d(x(kh), y(kh)) > \frac{M}{K}$ ), the self-map is non-expansive (respectively, contractive). Then,  $0 \leq d(T_h x(kh), T_h y(kh)) \leq d(x(kh), y(kh))$  respectively,  $d(T_h x(kh), T_h y(kh)) < d(x(kh), y(kh))$ ). But such properties are not guaranteed if  $d(x(kh), y(kh)) < \frac{M}{K}$  which can lead to  $T_h : X \rightarrow X$  being expansive.  $\square$

Example 2.1 emphasizes the fact that some real-world problems exist where certain self-maps  $T$  from  $X$  to  $X$  are neither contractive nor expansive everywhere in  $X$  while such a map is guaranteed to be contractive for sufficiently large distances between any two points in  $X$  exceeding a known real threshold. For small distances, the self-map could be potentially expansive, or, as in the dynamic system of Example 2.1, unclassified as expansive, non-expansive or contractive. In Example 2.1, this last situation is due to the presence of unknown perturbations of known prescribed upper-bound. Note that in Example 2.1, the self-map  $X$  on  $X$  is guaranteed to be point-wise contractive or potentially expansive for each given pair in  $X$  accordingly to the distance between them.

### III. RESULTS

This section is devoted to formalize the general context of the described problem to the light of Fixed Point Theory. A first main result follows:

**Theorem 3.1.** Assume that  $K \in [0, 1)$  and consider any bounded set  $X_0 \subset X$  with  $diam(X_0) \leq R$ .

(i) Assume that  $R \geq M/K$ . Then, the restricted map  $T|_{X_0}$  of  $T$  from  $X_0$  to  $X$  is non-expansive (i.e.  $d(Tx, Ty) \leq d(x, y)$ ) for any pair  $x, y \in X_0$  such that  $d(x, y) \geq M/K$  and weakly contractive (i.e.  $d(Tx, Ty) < d(x, y)$ ) for any pair  $x, y \in X_0$  such that  $d(x, y) > M/K$ .

(ii) The distance between the iterates  $T^j x$  and  $T^j y$  is uniformly bounded;  $\forall x, y \in X_0, \forall j \in \mathbf{Z}_+$  and there exists a bounded subset  $X_1$  of  $X$  fulfilling  $X_1 \supset X_0 \neq X_1$  such that  $T^j x, T^j y \in X_1; \forall j \in \mathbf{Z}_+$ .

(iii) If Property (ii) holds then all iterate  $T^j x$  enters a compact convex subset  $X_\alpha$  of  $X$ ;  $\forall x \in X_0$ ;  $\forall j \geq j_0$  and some finite integer  $j_0$ ; i.e. the sequence  $T^j x$  is permanent;  $\forall x \in X_0$ . Also, any two pairs of iterates  $T^j x, T^j y$  enter within a compact subset of  $X_\alpha$  of

prescribed diameter  $\frac{M}{K} + \varepsilon$ ;  $\forall x, y \in X_0, \forall j \geq j_0$  and some finite integer  $j_0$ .

*Proof:* (i) It follows by direct inspection from (2.2).

(ii) Direct recursive calculation with (2.2) for  $j \in \mathbf{Z}_+$  and any bounded  $X_0 \subset X$  with  $diam(X_0) \leq R$  yields:

$$d(T^j x, T^j y) \leq (1-K)^j d(x, y) + M \sum_{i=0}^{j-1} (1-K)^{j-1-i} \leq (1-K)^j d(x, y) + \frac{M}{K} (1 - (1-K)^j) \leq d(x, y) + \frac{M}{K} \leq R + \frac{M}{K} < \infty; \forall j \in \mathbf{Z}_+ \quad (3.1)$$

:  $\forall x, y \in X$  since  $K \in [0, 1)$ .

(iii) From the first inequality of (3.2),

$$\limsup_{j \rightarrow \infty} d(T^j x, T^j y) \leq \frac{M}{K} (1 - (1-K)^j) \leq \frac{M}{K} < \infty; \forall x, y \in X \quad (3.2)$$

so that for any given real constant  $\varepsilon > 0$ , it exists a positive integer  $j_{01} = j_{01}(\varepsilon)$  such that from (3.2)

$$d(T^j x, T^j y) \leq \frac{M}{K} + (1-K)^{j_{01}} \left( R - \frac{M}{K} \right) \leq \frac{M}{K} + \varepsilon; \forall j \geq j_{01}; \forall x, y \in X \quad (3.3)$$

provided that  $\varepsilon \geq (1-K)^{j_{01}} \left( R - \frac{M}{K} \right)$ , or equivalently,

$$j_{01} \geq \ln \frac{\varepsilon}{R - M/K} - \ln |1-K| \quad \text{provided that} \quad \frac{M}{K} \leq R \leq \frac{\varepsilon}{|1-K|} + \frac{M}{K} \quad \text{Now, assume that}$$

$R > \frac{\varepsilon}{|1-K|} + \frac{M}{K}$ . Then, from (3.3) and the definition of limit superior, there exists a finite positive integer  $j_{02} = j_{02}(\delta, R)$  for any arbitrary given positive real constant  $\delta$  such that  $d(T^j x, T^j y) \leq \frac{M}{K} + \delta; \forall j \geq j_{02}$ .

Then, choose  $\delta = \frac{\varepsilon}{|1-K|}$  for the given  $\varepsilon$ . Thus, (3.4) holds

;  $\forall j \geq j_{02} := j_{01} + j_{02}$ . Finally, assume that  $0 \leq R < \frac{M}{K}$ . Then, from (3.3), it exists  $j_{03} = j_{03}(\varepsilon)$  such

that  $d(T^j x, T^j y) \leq \frac{M}{K} + \varepsilon; \forall j \geq j_{03}$ . As a result, for any bounded set  $X_0 \subset X$  with  $diam(X_0) \leq R$ , it exists a finite positive integer  $j_0 = j_0(\varepsilon, R)$  such that  $d(T^j x, T^j y) \leq \frac{M}{K} + \varepsilon; \forall x, y \in X_0, \forall j \geq j_0$ , for some finite integer  $j_0$ . Thus, for each given real  $\varepsilon > 0$ ,

there is a compact convex subset  $X_\alpha \supset X_0$  of  $X$  where all the iterates  $T^j x$  enter ;  $\forall j \geq j_0$  , for some finite integer  $j_0$  . Furthermore, any two iterates  $T^j x, T^j y$  are within a compact convex subset of  $X_\alpha$  of prescribed diameter  $\frac{M}{K} + \varepsilon$  ;  $\forall x, y \in X_0$  ,  $\forall j \geq j_0$  .  $\square$

**Remark 3.2.** Note that Theorem 3.1 (i) does not conclude that the self-map  $T : X_0 \rightarrow X_0$  is expansive for some pair  $x, y \in X_0$  (i.e.  $d(Tx, Ty) > d(x, y)$ ) if  $d(x, y) < M/K$  but only that the upper-bound  $(1-K)d(x, y) + M$  of  $d(Tx, Ty)$  is upper-bounded by  $d(x, y)$  . Thus,  $d(x, y) < M/K$  for some pair  $x, y \in X_0$  is a necessary (but not sufficient) condition for  $T : X_0 \rightarrow X_0$  to be expansive for that pair.  $\square$

**Remark 3.3.** Note that  $X_0$  in Theorem 3.1 is not required to be convex. Theorem 3.1 (ii) guarantees that  $T^j x, T^j y \in X_1 \supset X_0$  although eventually it may not belong to  $X_0$ .  $\square$

It is now of interest to characterize in some sense a subset  $X_e$  of  $X$  such that the restricted map  $T|X_e$  is a self-map from  $X_e$  to  $X_e$  and which satisfies the constraints:

$$K_1 d(x, y) \leq d(Tx, Ty) \leq \min((1-K)d(x, y) + M, K_2 d(x, y)) ; \forall x, y \in X_e \subseteq X \quad (3.5)$$

for some real constants  $K \in [0, 1)$  ,  $M > 0$  ,  $K_1 > \max(1-K, 0)$  ,  $K_2 \geq K_1$  . This will allow later on the definition of subsets of  $X$  where the self-map  $T$  is contractive , expansive or non-expansive. It would be proven later on (see Corollary 3.5) that (3.5) is impossible everywhere in  $X$  if  $K_1 > 1$  .

**Theorem 3.4.** Assume that  $K \in [0, 1)$ . Then, there is a family of nonempty bounded subsets of  $X$  for which (3.5) holds and, then trivially, a subfamily of nonempty bounded convex subsets of  $X$  with the same property.

*Proof:* The constraints (3.5) are guaranteed under two possibilities for each  $x, y \in X_e(x) \subseteq X$  where  $X_e(x) := \{y \in X : (3.5) \text{ holds}\}$  is a point-dependent subset of  $X$ , namely:

$$K_1 d(x, y) \leq d(Tx, Ty) \leq (1-K)d(x, y) + M \leq K_2 d(x, y) ; \forall x, y \in X_e(x) \subseteq X , \text{ some } M > 0 \quad (3.6)$$

which implies:

$$K_1 d(x, y) \leq d(Tx, Ty) \leq K_2 d(x, y) \leq (1-K)d(x, y) + M ; \forall x, y \in X_e(x) \subseteq X \quad (3.7)$$

The constraint (3.6) is subject to the necessary conditions:

$$d(x, y) \in \left[ \frac{M}{K+K_2-1}, \frac{M}{K+K_1-1} \right] ; \forall x, y \in X_e(x) \quad (3.8)$$

$$\frac{MK_1}{K+K_2-1} \leq K_1 d(x, y) \leq d(Tx, Ty) \leq (1-K)d(x, y) + M \leq K_2 d(x, y) \leq \frac{MK_1}{K+K_1-1} ; \forall x, y \in X_e(x)$$

$$\Rightarrow d(Tx, Ty) \in \left[ \frac{MK_1}{K+K_2-1}, \frac{MK_1}{K+K_1-1} \right] ; \forall x, y \in X_e(x) \quad (3.9)$$

Since  $T$  is a self-map on  $X$  , any pair  $x, y \in X_e(x)$  has to satisfy simultaneously (3.8)-(3.9) so that

$$d(x, y) \in \left[ \frac{M}{K+K_2-1}, \frac{M}{K+K_1-1} \right] \min(1, K_1) ; \forall x, y \in X_e(x) \quad (3.10)$$

under the constraint (3.6). Since  $K_2 \geq K_1$  , the constraint (3.7) requires

$$d(x, y) \leq \frac{M}{K+K_2-1} ; \forall x, y \in X_e$$

$$d(Tx, Ty) \leq K_2 d(x, y) \leq \frac{MK_2}{K+K_2-1} \leq \frac{MK_1}{K+K_1-1} ; \forall x, y \in X_e \quad (3.11)$$

The last inequality of (3.11) follows directly if  $K_1 > 1-K$  since  $K_2 \geq K_1 > 1-K$  implies that

$$\frac{K+K_1-1}{K_1} = 1 - \frac{1-K}{K_1} \geq 1 - \frac{1-K}{K_2} = \frac{K+K_2-1}{K_2} \quad (3.12)$$

Combining (3.11)-(3.12), one gets that (3.7) holds if

$$d(x, y) \in \left[ 0, \frac{M}{K+K_2-1} \right] \min(1, K_2) ; \forall x, y \in X_e(x) \quad (3.13)$$

Thus, it is clear the existence of a countable family of nonempty bounded subsets  $\{X_{ei}(x)\}$  of  $X_e(x)$  ;  $\forall x \in X$  defined by

$$X_{ei}(x) := \left\{ y \in X : d(x, y) \leq \frac{M}{K+K_1-1} \min(1, K_1) \right\} \subset X_e(x) \subset X ; \forall x \in X \quad (3.14)$$

since  $X_e(x) := \{y \in X : (3.5) \text{ holds}\} \supset X_{ei}(x)$  ;  $\forall x \in X$  . From the above developments, it turns out that there exists a convex subset in the family  $\{X_{ei}(x)\}$  which is convex

and then a subfamily of the set  $\{X_{ei}\}$  which possess such a property.  $\square$

Theorems 3.1 and 3.4 lead to the following important conclusion.

**Corollary 3.5.** Assume that  $K \in [0, 1)$ . Then, the following properties hold if (3.5) holds:

(i) If  $\max(1-K, 0) < K_1 \leq K_2 \leq 1$  then  $T : X \rightarrow X$  is non-expansive.

(ii) If  $\max(1-K, 0) < K_1 \leq K_2 < 1$  then  $T : X \rightarrow X$  is (strictly) contractive and then it has a fixed point. (iii) If  $K_1 \in [0, 1)$  and  $K_2 > 1$  then the restriction of T to  $\hat{X}(x)$ ,  $T|_{\hat{X}(x)} := (T : X|_{\hat{X}(x)} \rightarrow X)$ ,  $\forall x \in X$ , is non-expansive where

$$\hat{X}(x) := \left\{ y \in X : d(x, y) \geq \frac{M}{K} \right\} \subset X ; \forall x \in X \quad \text{but}$$

$T|_{\hat{X}_{ei}(x)}$  is weakly contractive for all sets  $X_{ei}(x)$  defined in (3.14) resulting to be

$$X_{ei}(x) := \left\{ y \in X : d(x, y) \leq \frac{M}{K + K_1 - 1} \right\} \quad \text{since}$$

$K_1 > 1 ; \forall x \in X$ . As a result  $T : X \rightarrow X$  is neither contractive nor expansive on X.

(iii) If  $K_2 \geq K_1 = 1$  then  $T : X \rightarrow X$  is not contractive, and

$$K_1 d(x, y) \leq d(Tx, Ty) \leq (1-K)d(x, y) + M \leq \max \left( K_2 d(x, y), \frac{K_1 M}{K + K_1 - 1} \right) ; \forall x, y \in X \quad (3.15)$$

If  $K_1 > 1$  then neither (3.6) nor (3.7) is feasible for any  $x, y \in X$  and (3.5) is not feasible either ;  $\forall x, y \in X$ .

*Proof:* Properties (i)–(ii) follow from Theorem 3.1. Property (iii) follows from Theorem 3.4 since:

$$K_1 > 1 \Rightarrow M / K \geq M / (K + K_1 - 1) \Rightarrow \hat{X}(x) \cap X_{ei}(x) = \emptyset ; \forall x \in X$$

Then, for any  $x, y \in X$ , if  $y \in \hat{X}(x)$  then  $y \notin X_{ei}(x)$  and conversely. The constraints (3.15) follow directly from

$$(3.5) \text{ and its necessary condition } d(x, y) \leq \frac{M}{K + K_1 - 1} ;$$

$\forall x, y \in X$ . It is now proven by contradiction that neither (3.6) nor (3.7) is feasible for all given pair  $x, y$  in X if  $K_1 > 1$ . A necessary condition for (3.6) to hold for each

$$x, y \in X \text{ is that } d(x, y) \in \left[ \frac{M}{K + K_2 - 1}, \frac{M}{K + K_1 - 1} \right].$$

Thus,  $T : X \rightarrow X$  is not expansive which contradicts  $d(x, y) < K_1 d(x, y) \leq d(Tx, Ty) ; \forall x, y (\neq x) \in X$  if

$K_1 > 1$ . Also, if (3.7) holds;  $\forall x, y \in X$  then

$$d(x, y) \leq \frac{M}{K + K_2 - 1} \text{ which leads to the same above}$$

contradiction if  $K_1 > 1$ . On the other hand, a necessary condition for (3.5) to hold is that

$$K_1 d(x, y) \leq (1-K)d(x, y) + M \Rightarrow$$

$$d(x, y) \leq \frac{M}{K + K_1 - 1} < \infty ; \forall x, y \in X$$

which contradicts  $K_1 > 1$ . Property (iii) has been proven.

Property (iv) follows from (3.6) and Property (iii) for  $K_2 \geq K_1 = 1$ .  $\square$

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