Image Compression Preprocessing for ANN Ensemble Motion Detection System

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Abstract – This paper presents image compression as an alternative method to preprocessing for an artificial neural network (ANN) motion detection system. Discrete wavelet transforms (DWT) and the discrete cosine transform (DCT) are used as preprocessing compression methods to improve the processing time of the ANN system used for object motion, detection, extraction and filtering. Configuring the ANN system as an ensemble was advantageous for improved noise cancellation of the end processing images. A comparison of the different image compression preprocessing methods is also presented during testing of the performance of the ANN ensemble motion detection system.

Index terms - artificial neural networks, wavelet transform, compression, ensembles, filtering, discrete cosine transform

I. INTRODUCTION

Image compression preprocessing methods are used in most image communication systems with limited bandwidth to reducing image data size [4], [5]. The DWT and the DCT are widely used for image compression applications over a variety of scientific and engineering disciplines [14], [17], [22]. When the DWT was introduced it was the favored transform for image compression over other transformation methods for both lossy and lossless compression of data [13]. Wavelets have an added advantage in that they can also be used for de-noising images, image decomposition and image reconstruction [4], [20]. Wavelets provide added flexibility in signal and image compression in that there are many wavelet functions designed for specific handling of data and compression applications [5], [17].

The DCT is derived from the Fourier Transform (FT) and is also used for image and data compression [4], [13]. The major advantages of wavelets over the FT and the DCT is that it provides vital time scaling analysis, uses filter banks for de-noising, coding gain for sub-band image coding which is attributable to memory reduction, spectral flattening of sub-band signals that enables more accurate statistical modeling and efficient entropy coding of a signal[4],[5], [6], [8].

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The ANN ensemble system that performs the object motion detection, extraction and filtering functions was proposed by Moorgas and Govender [16]. It outperforms the conventional DSP motion detection systems in terms of superior image quality save computational time. In this study the standard DCT and popular wavelet algorithms are used as image compressors for preprocessing to improve the computational speed of the ANN ensemble motion detection system (AEMDS) [16], [19].

ANN systems are used because they can generalize, are robust and inherently immune to noise [9], [11]. Furthermore changes in input data, such as illumination and varying noise levels, are handled more robustly by ANN systems [4], [9], [10]. In this study the DCT, Haar, Daubechies, and biorthogonal wavelets are applied as image compression preprocessors to the AEMDS to improve the system processing time.

This paper is arranged as follows: section 2 briefly introduces the architecture and operation of the AEMDS system; section 3 discusses the image compression preprocessing methods used; section 4 presents the performance of the AEMDS system when image compression is applied as preprocessing; section 5 concludes the study.

II. ANN ENSEMBLE MOTION DETECTION SYSTEM (AEMDS)

ANN systems display excellent PSNR ratios but are not computationally faster than conventional DSP systems. The computational speed of conventional DSP systems comes at the expense of image quality [16], [15]. In order to maintain high quality images large quantities of image data had to be processed by each neural network (NN) within the ensembles. With regard to Fig 1, the ANN ensemble consisted of two layers of NNs with each NN layer having 100 neurons and 200 neurons, respectively. In order to ensure a high resolution the input layer of each NN had to map the output layer to produce an image of 255 x 255 pixels points [12]. The large NN architectures each contributed to the slower processing speeds. During testing of the AEMDS there was no preprocessing of the images presented to the system except for grayscaling.

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The AEMDS shown in Fig. 1 uses multilayer feedforward (MLFF) backpropagation networks and a log-sigmoid nonlinear activation function to detect motion and remove any stationary background. The MLFF architecture was designed with two hidden layers and an output layer, having 100, 200 and 255 neurons respectively [12]. The output layer maped corresponding pixel elements from an input image matrix to the output image matrix. The AEMDS had two layers of NN ensembles to perform the motion detection function, extraction and filtering. This configuration produced high quality end processing images [13], [16].



A. Testing

Initial testing was conducted with no image compression or noise as shown in Fig. 2. Gray scaled image sequences were captured, each image frame within the sequence was split into single frames and presented to the input of the ANN system. The AEMDS system detected any motion and displayed the new position of the object.



Fig 2: Motion Detection of the AEMDS system without preprocessing and noise

III. IMAGE COMPRESSION

The main focus of this study was to consider the application of image compression preprocessing in object motion detection, extraction and filtering, with a view to improving the processing speed of the AEMDS system and still retain high quality images. (1) represents a captured frame sequence presented to the input of the AEMDS after image compression and the introduction of noise, Fig. 3(c), Fig. 4(c), Fig. 5 (c) and Fig. 6 (c).

$$S_{\beta} = [\mathbf{H}_1, \mathbf{H}_2, \dots \mathbf{H}_n^{\text{th}}]$$
(1)

Where S_{β} is an image frame sequence, β the sequence number with \mathbf{H}_1 , \mathbf{H}_2 , ... \mathbf{H}_n^{th} representing the image frame matrices of the captured image sequence.

A. DCT Compression

In transform coding the compression technique applied divides an image into small non-overlapping blocks of equal size $M \ge N$ dimensions. The blocks are then processed independently using the 2D-DCT transform in the frequency domain [6], [18]. With regard to (2), the 2D-DCT of an image is a sum of sinusoids of magnitudes and frequencies. varving After computation of the 2D-DCT, the significant information of the image is represented by coefficients. (3) is the 2D-IDCT which then converts this information back to the time domain [6], [8], [22].

For this study the 2D-DCT and the 2D-IDCT was modified and applied to the $M \ge N$ image matrix of each image frame within each captured sequence with $f_{\beta}[x, y]$ representing each image frame, β denoting the frame number within each image sequence, x and yrepresenting the rows and columns of the image frame matrices and p and q denotes the frequency variables.

$$F(p,q) = \alpha_p \alpha_q \sum_{x=0}^{M-1} \int_{y=0}^{N-1} f_{\beta}[x,y] \cos \frac{\pi (2x+1)p}{2M} \cos \frac{\pi (2y+1)q}{2N}$$
$$0 \le p \le M-1, \quad 0 \le q \le N-1$$
(2)

$$f_{\beta}[x,y] = \sum_{p=0}^{M-1} \sum_{q=0}^{N-1} \alpha_{p} \alpha_{q} F(p,q) \cos \frac{\pi (2x+1)p}{2M} \cos \frac{\pi (2y+1)q}{2N}$$
$$0 \le x \le M-1, \quad 0 \le y \le N-1$$
(3)

In Fig.3: an image sequence is captured in Fig 3(a), DCT image compression is applied to image frames in Fig. 3(b), noise is induced in each frame in Fig. 3(c), ANN motion detection, extraction and filtering is shown in Fig. 3(d) and the image frames are enhanced in Fig. 3(e).



(d) ANN Motion Detection



(e) Enhanced Images

Fig 3: Motion Detection of the AEMDS using DCT Image Compression as Pre-processing

B: DWT Compression

The disadvantage of the DCT like the FT is that it only caters for frequency resolution and not time resolution [18], [6]. This means that only the frequencies within a signal can be determined but not the time at which these frequencies were introduced to the signal. The DWT is used to overcome the shortcomings of the DCT and the DFT [8], [18]. The WT and DWT are used extensively in image processing applications (for segmentation, morphological operations and image compression) and exhibits superior performance over most other image compression methods [8].

For this study the Haar, Daubechies Wavelets (db4) and biorthogonal wavelets (bior 1.3) wavelets were used as image compression preprocessing algorithms to test the AEMDS system with the objective of reducing the detection, time of the ANN motion detection system.

The scaling function of the two dimensional wavelet is $\varphi(x, y)$, and the three two dimensional directional wavelets are, $\psi^{H}(x, y)$, $\psi^{v}(x, y)$ and $\psi^{D}(x, y)$ which are defined by (4), (5) and (6): *H*(*horizontal*), *V*(*vertical*) and *D*(*diagonal*) are the directional wavelet indicators.

They measure intensity variations along columns, rows and diagonals of an image matrix [3], [6], [8]. $\psi^{H}(x, y) = \psi(x)\phi(y)$ (4)

$$\psi^{V}(x,y) = \varphi(x)\varphi(y) \tag{5}$$

$$\psi^{D}(x,y) = \psi(x)\psi(y) \tag{6}$$

The scaled and translated basis functions are defined as follows:

$$\varphi_{j,m,n}(x,y) = 2^{j/2} \varphi(2^j x - m, 2^j y - n)$$
(7)

$$\psi^{i}{}_{j,m,n}(x,y) = 2^{j/2} \psi^{i}(2^{j}x - m, 2^{j}y - n)$$
(8)

With regards to (7) and (8) *i* assumes the value *H*, *V*, and *D* to identify the directional wavelets, *j* denotes the resolution level of the image frame $f_{\beta}[x, y]$ having *x*-rows and *y*-columns. The 2D-DWT is defined by (9) and (10) for the image frames within the image frame sequences $f_{\beta}[x, y]$ of size *M x N*. $W_{\varphi}(j,m,n)$ are coefficients defined as approximations of $f_{\beta}[x, y]$ with j_{θ} the starting scale. The $W_{\psi}^{i}(j,m,n)$ coefficients add horizontal, vertical and diagonal details for scales *j*. $N=M=2^{j}$ so that j = 0, 1, 2, ..., j-1 and $m = n = 0, 1, 2, ..., 2^{j} - 1$.

$$W_{\varphi}(j_0, m, n) = \frac{1}{\sqrt{MN}} \sum_{x=0}^{M-1} \sum_{y=0}^{M-1} f_{\beta}[x, y] \varphi_j, m, n(x, y)$$
(9)

$$W_{\psi}^{i}(j,m,n) = \frac{1}{\sqrt{MN}} \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f_{\beta}[x,y] \psi_{j}^{i}, m, n(x,y) \quad (10)$$

A captured image frame $f_{\beta}[x, y]$ contains a vector space V^{j} which has 2^{j} pixels in V^{j} with j = 0, 1, 2....n-1.

B.1 Haar Wavelet Compression

The Haar wavelet is used for most image processing applications because of its simple algorithm, high compression processing time and compactness [5], [21]. (8) is the conventional 2D Haar wavelet scaled and translated box functions.

$$\phi_{i}^{j}(x) := \phi(2^{j} x - i) \quad \text{where } i = 0, 1, 2 \dots 2^{j} - 1 \quad (8)$$
$$\phi(x) = \begin{cases} 1 & \text{for } 0 \le x < 1 \\ 0 & \text{otherwise} \end{cases}$$

The Haar wavelets corresponding to the box basis are given by (9):

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 $\psi_{i}^{j}(x) := \psi(2^{j}x - i) \quad \text{where } i = 0, 1, 2, \dots, 2^{j} - 1 \quad (9)$ $\psi_{i}(x) := \begin{cases} 1 \quad \text{for} \quad 0 \le x < 1 / 2 \\ -1 \quad \text{for} \quad 1 / 2 \le x < 1 \\ 0 \quad \text{otherwise} \end{cases}$

The 2D DWT of $f_{\beta}[x, y]$ was obtained from the 1D

DWT by multiplying two 1D scaling functions that scan *horizontal*, *vertical* and *diagonal* details of the image frame [23]. Results of the Haar compression preprocessing is shown in Fig.4. Fig. 4(a) is the captured image sequence, Fig.4(b) is Haar compressed image frames of the image sequence, Fig.4(c) is the introduction of noise, Fig.4(d) is the ANN motion detection, extraction and filtering and Fig.4(e) is the enhanced images image frames.





(b) Haar Wavelet Compressed Images



(c) Noise Induced at 0.09 Salt & Pepper



(d) ANN Motion Detection



(e) Enhanced Images

Fig.4: Motion Detection of the AEMDS using Haar Wavelet Compression

B.2 Daubechies Wavelet Compression

Daubechies' wavelets are used in image analysis and synthesis because they are orthonormal, have continuous derivatives (images are smooth except occasional edges) and compact algorithms [24], [25]. The Daubechies' wavelets have quadratic mirror filters of the Haar wavelet [7]. Like the Haar wavelet the Daubechies' wavelet was translated for any image frame $f_a[x, y]$ within the captured sequence. Results of

the motion detection are shown in Fig.5 using the Daubechies' compression algorithm. Fig.5(a) is the captured image sequence, Fig. 5(b) using Daubechies (db4) for image frame compression, Fig.5(c) is induced noise, Fig. 5(d) ANN motion detection, object extraction and filtering and Fig.5(e) is image enhancement of each frame.

B.3 Biorthogonal Wavelet Compression

Biorthogonal Wavelets exhibit properties of linear phase which is needed for signal and image reconstruction and analysis [17]. They are excellent for image coding and de-noising [1]. Many elegant quantization and entropy coding techniques have been developed that exploit the multi-resolution nature of this wavelet family to enhance the low bit rate coding of images [26]. The properties of the biorthogonal wavelets have duality in any subspace because of its symmetry and separate decomposition and reconstruction functions in each member of its family of wavelets [20]. The scaling functions are obtained by multiplication for a vector space V^{j} which can be translated to an image matrix frame $f_{\beta}[x, y]$. During testing the biorthogonal (bior1.3) wavelet algorithm was applied.



(a) Captured Image Sequences





(c) Noise Induced at 0.09 Salt & Pepper



(d) ANN Motion Detection



Fig.5: Motion Detection of the AEMDS using Daubechies (db4) Wavelets

The results of the AEMDS system using the biorthogonal image compression as preprocessing are shown in Fig.6. Fig.6(a) is the captured image sequence, Fig.6(b) is the biorthogonal image compression (bior1.3), Fig. 6(c) is induced noise, Fig. 6(d) is the ANN motion detection, object extraction and filtering and Fig 6 (e) is image enhancement.



(b) Biorthogonal (bior 1.3) Wavelet Compressed Images



(c) Noise Induced at 0.09 Salt & Pepper



(e) Enhanced Images

Fig. 6: Motion Detection of the AEMDS using Biorthogonal (bior 1.3) Wavelet Compression

IV. PERFORMANCE OF THE AEMDS WITH IMAGE COMPRESSION

A. Noise

The Peak Signal-to-Noise Ratio (PSNR) (10) is used to measure image quality of the image sequences produced by the AEMDS system.

$$PSNR = 10 \log_{10} \frac{[g_{\text{max}} - g_{\text{min}}]^2}{MSE}$$
(10)

With regards to (10), g_{max} and g_{min} indicate the maximum and minimum pixel values for an image frame; *MSE* is the mean squared error for two dimensional $M \times N$ gray scaled images. Fig 7 shows

PSNR response of the different preprocessing image compression methods applied to the AEMDS system.

With regard to Fig. 7:

Sequence limage sequence is captured: Under identical conditions for each motion detection test (Fig. 3(a), Fig. 4(a), Fig. 5(a) and Fig. 6(a)).

Sequence 2, image frames are compressed: For each image frame within the captured sequences different image compression methods are applied (Fig. 3(b), Fig. 4(b), Fig. 5(b) and Fig. 6(b)).

Sequence 3, noise is induced: The same level of noise is induced to each frame of each image sequence (Fig. 3(c), Fig. 4(c), Fig. 5(c) and Fig. 6(c)).

Sequence 4, motion is detected: The AEMDS detects motion and improves the PSNR of each frame within the sequence (Fig. 3(d), Fig. 4(d), Fig. 5(d), and Fig. 6(d)).

Sequence 5, image enhancement: Each frame of the image sequence is enhanced to show the new position of the non – stationary object (Fig. 3(e), Fig. 4(e), Fig. 5(e), and Fig. 6(e)).



Fig 7: PSNR of Motion Detection with Image Compression Preprocessing

B. Average Processing Time

Fig. 8 shows the average processing time of the AEMDS system. The AEMDS system shows a far more superior processing time with image compression than without. When considering the image compression preprocessing applied to the image frame sequences presented to the AEMDS, the Haar exhibits the fastest average processing time, followed by Daubechies, then biorthogonal with the DCT the slowest of all.

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Fig. 8: Average Processing Time of the AEMDS

V. CONCLUSION

This paper showed that the ANN ensemble motion detection system (AEMDS) used for object detection, extraction and filtering had improved processing time and still retained high image quality with the applied image compression preprocessing methods. The method of object motion detection, extraction and filtering presented proved superior to some conventional DSP motion detection systems.

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