Modeling Road Accidents using Fixed Effects Model: Conditional versus Unconditional Model

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Abstract- Modeling road accidents using panel data approach recently has gained wide attention and application. As the nature of road crashes are non-negative count, the traditional linear computational approaches is inappropriate giving the nonlinear model of fixed effects (FE) the better choice. This paper examines the road accidents relationship with precipitation factors by estimating the FE Negative Binomial (NB) model. In the FE model two estimation methods were consider in this paper: conditional and unconditional estimation method. Thus, this paper compare the conditional and unconditional FE model for road accidents and discuss the findings obtain. Results showed that the unconditional FE Negative Binomial model gives approximately the same results with conditional models. The effect of monthly rainfall with shorter spell period presents greater risk of accident rate. On the other hand, a negative relationship is found between the monthly rainfalls with longer spell period and accident rate.

Index Terms— Conditional Fixed Effects, Unconditional Fixed Effects, Negative Binomial, Road accidents

I. INTRODUCTION

VER the past few years road accidents represent among the leading cause of death and injury. Statistics recorded had captured the interest of the researcher and policy maker to better understand the complexity of factors that are related to road accidents by developing statistical model. Models developed served as references for law enforcement agencies and policy maker to implement corrective action aimed to reduce the number of road accidents. Thus, there has been considerable research conducted on the development of statistical model for predicting road accident crash. A detailed review on advancement of methodological approach in crash frequency data can be found in Lord and Mannering [1]. Despite numerous advancement in estimation tools of statistical model for count data, the most common probabilities structure used for modeling road accident

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remains the traditional Poisson and Negative Binomial distribution. When dealing with panel data type of road accident count, the most familiar panel data treatments are the fixed effects (FE) and the random effects (RE) which were proposed for panel count data model by Hausman, Hall and Griliches (HHG) [2]. We employed the panel model approach of fixed effects negative binomial model method since it has several advantages over individual time series and cross sectional model [3],[4], particularly, for its ability to account for heterogeneity in the data [5]. Since, many studies had proven that precipitation generally results in more accidents compared with dry condition [6]-[8], therefore, in this study we will examines the relationship between road accidents and various precipitation factors.

Given the discrete, non-negative nature of the road accidents count, the ordinary least square is not appropriate to model this type of data [9]. Hence, the HHG negative binomial model based on conditional estimation method was employed first. Though analysis on the HHG Poisson FE is simple and has been recognized to be exceptional from incidental parameter problem [10],[11], the HHG formulation of conditional NB FE model is ambiguous [12], [13]. Thus, to account for this ambiguity in HHG FE NB, we also consider the unconditional FENB model [14]. The various models developed were applied in road accident panel data set which allows for a detailed discussion and comparison.

In section 2 we review some related works on the application of the model. Section 3 presents the models and its properties. Application to examine the relationship of road accident and precipitation factors using conditional and unconditional FE NB is presented in Section 4. Results and discussions are presented in Section 5. Finally, the last section discussed the policy lessons.

II. RELATED WORK

The literature on panel count model has grown considerably after the seminal work of Hausman, Hall and Grilliches (HHG) et al. [2]. Application of panel count model can be seen in varieties of application [15], [16]. Panel models have also become popular in road safety literature. Previous work on panel count model in road accident application has been widely applying both fixed effects and random effects model as suggested by Hausman et al. [4], [5], [7].

Eisenberg [7] examined the relationship between precipitation and traffic crashes in 48 contiguous states in US using fixed effects negative binomial model for the period of 1975 to 2000. It was found that precipitation is positively associated with fatal crashes. In terms of dry spell effects, this study found that the rainfall amount has enhanced effects on accident count after a dry spell due to the slippery surface from accumulation of oil on the roads.

Based on 6-year crash data set for urban and suburban arterial of 92 counties in Indiana, Karlaftis and Tarko [4] employed fixed effects model of Poisson and negative binomial to develop the crash model. Their findings indicated that the increase in the number of accidents is associated with higher vehicle miles travelled, population, the proportion of city mileage, and the proportion of urban roads in total vehicle miles travelled.

Kweon and Kockelman [17] investigated the safety effects of the speed limit increase on crash count measure in Washington State using the panel regression methods of both the fixed effects and random effects model assumption. They develop models for the number of fatalities, injuries, crashes, fatal crashes, injury crashes, and property-damageonly (PDO) crashes using fixed effects and random effects Poisson and negative binomial model specification. They found that the fixed-effects negative binomial model performed best in describing injury count while for fatalities, injuries, PDO crashes and total crashes, the pooled negative binomial model was a better choice.

There is also another study that applied fixed effects negative binomial model in the analysis. Kumara and Chin [18] analyzed the fatal road accident data from the period of 1980 to 1994 across 41 countries in the Asia Pacific region and found that road network per capita, gross national product, population and number of registered vehicles were positively associated with fatal accident occurrence.

In another recent study, Law et al. [5] examined the effect of motorcycle helmet law, medical care, technology improvement, and the quality of political institution on motorcycle death on the basis of Kuznets relationships. They used the HHG fixed effects negative binomial model on a panel of 25 countries from the period of 1970 to 1999. Their findings revealed that implementation of road safety regulation, improvement in the quality of political institution and medical care and technology developments showed significant effect in reducing motorcycle death.

III. METHODOLOGY

This section discusses the formulation of panel count model specification of the fixed effects Negative Binomial model for both conditional and unconditional approach.

A. Conditional estimation of Fixed Effects Negative Binomial Model

The estimation method used in this study is the panel negative binomial regression developed by Hausman et al. [2], a generalized version of Poisson regression that allows the variance of dependent variable to differ from its mean. The model can be expressed in the following way;

$$\ln(\lambda_{it}) = \alpha_i + \ln(Veh_{it}) + \gamma Time_{it} + \beta' X_{it} + \varepsilon_{it}$$
(1)
for $i = 1, 2, ...N$ and $t = 1, 2, ...T_i$

where λ_{it} is the dependent variable of road accident count for a given observation subscripted by state and time; α_i is the state specific effects; β , γ are the model parameter; *Time* is the time trend; X_{ii} includes other independent variables of interest; \mathcal{E} is the error term. To illustrate the fixed effect negative binomial model, Hausman et. al [2] add individual specific effects of α_i and the negative binomial overdispersion parameter of ϕ into the model replacing $\theta_i = \alpha_i / \phi_i$. Here, the number of accident, y_{ii} for a given time period, t is assumed to follow a negative binomial distribution with parameters $\alpha_i \lambda_i$ and ϕ_i , where $\lambda_{ii} = exp(x_{ii}'\beta)$ giving y_{ii} has a mean $\alpha_i \lambda_{ii} / \phi_i$ and variance $(\alpha_i \lambda_{it} / \phi_i) \times (1 + \alpha_i / \phi_i)$ [9]. This model allows the variance to be greater than mean. The parameter α_i is the individual-specific fixed effects and the parameter ϕ is the negative binomial overdispersion parameter which can take on any value and varies across individuals. Obviously α_i and ϕ_i can only be identified as the ratio of α_i/ϕ_i and this ratio has been dropped out for conditional maximum likelihood [10].

The conditional approach of fixed effects Negative Binomial model estimates the parameter β using the conditional joint distribution conditioning on the groups total counts by maximizing the conditional joint distribution as below;

$$P\left(y_{i1}, \dots, y_{iT} | \sum_{t=1}^{T_i} y_{it}\right)_i = \frac{\Gamma\left(\sum_{t=1}^{T} \lambda_{it}\right) \Gamma\left(\sum_{t=1}^{T} y_{it} + I\right)}{\Gamma\left(\sum_{t=1}^{T} y_{it} + \sum_{t=1}^{T} \lambda_{it}\right)}$$
(2)
$$\times \prod_{t=1}^{T_i} \frac{\Gamma\left(y_{it} + \lambda_{it}\right)}{\Gamma\left(\lambda_{it}\right) \Gamma\left(y_{it} + I\right)}$$

The fixed effects model for Poisson distribution does not allow for an overall constant [10]. However, an overall constant term is identified in the conditional distribution of HHG NB formulation [17] indicating that HHG formulation of FE NB model does not formulate the true fixed effects model in the mean of random variable and conditioned out of the distribution to produce the estimated model [13], [19]. Hence, this study also considers the unconditional estimator for both NB FE model.

B. Unconditional estimation of Fixed Effects Negative Binomial Model

The unconditional estimator of β is estimated by specifying the conventional Negative Binomial model with dummy variables for all group specific constant (less one) to capture the fixed effects [12], [13], [14]. Hence X_{it} in model (1) also includes a set of dummy variables representing fixed effects for each state and month effects. The unconditional FE Poisson model is estimated by a direct maximization of the full log likelihood function given by Proceedings of the World Congress on Engineering 2012 Vol I WCE 2012, July 4 - 6, 2012, London, U.K.

$$Log L = \sum_{i=1}^{N} \log \left[\prod_{t=1}^{T_i} \frac{\exp\left(-\exp\left(\alpha_i + \mathbf{x}_{it}'\beta\right)\right) \left[\exp\left(\alpha_i + \mathbf{x}_{it}'\beta\right)\right]^{y_{it}}}{y_{it}!} \right]$$
(3)

with respect to all K+N parameters [14], [19]. While the unconditional FE NB model was estimated using the same approach by replacing the Poisson density with the NB counterpart of

$$P(y_{i1},...,y_{iT}|\mathbf{x}_{it}) = \frac{\Gamma(\theta + y_{it})}{\Gamma(\theta)\Gamma(y_{it}+1)} u_{it}^{\theta} (1 - u_{it})^{y_{it}}$$
(4)

where

$$u_{it} = \theta / \left(\theta + \lambda_{it}\right) \tag{5}$$

in the FE Poisson log likelihood function given by

$$Log L = \sum_{i=1}^{N} \log \left[\prod_{t=1}^{T_i} \frac{\exp\left(-\exp\left(\alpha_i + \mathbf{x}_{it}'\beta\right)\right) \left[\exp\left(\alpha_i + \mathbf{x}_{it}'\beta\right)\right]^{y_{it}}}{y_{it}!} \right]$$
(6)

IV. DATA

In this paper we worked on road accident panel data comprising of a balanced panel monthly data in Peninsular Malaysia from January 1997 to December 2007. The number of observation per states was 132 with a total number of 1584 observations from 12 states. The list of states included in the study is presented in Table 1.

The monthly total road accidents or road crash data were collected from the Royal Malaysian Police Headquarters in Kuala Lumpur for the year 1997 to 2007 [20]. The data used referred to the total figure of their occurrences on public or private roads due to the negligence or omission by any party concerned (on the aspect of road users conduct, maintenance of vehicle and road condition), environmental factor (excluding natural disaster) resulting in a collision (including õout or controlö cases and collision of victims in a vehicle against object inside or outside the vehicle e.g. bus passenger) which involved at least one moving vehicle whereby damage or injury was caused to any person, property, vehicle, structure, or animal.

Data on the number of registered vehicles (VEH) were also used which were collected from the Department of Road Transport in the Malaysian Ministry of Transportation. The number referred to the total number of vehicles (private and public) that was registered with the Department of Road Transport. It included all vehicles using either petrol or diesel which were motorcycles, motorcars, buses, taxis and hired cars, goods vehicle and other vehicles. However, the figure did not include army vehicle.

Data for precipitation variables were collected from the Malaysian Meteorological Department (MMD). The precipitation factor considered was the amount of monthly rainfall (in millimeter) for a particular month. The data were captured from 12 selected weather stations in the respective 12 states. This factor had been most commonly

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 TABLE I

 THE LIST OF STATES, WEATHER STATION AND YEAR OF DATA

No	St	ate	Station	Period
1	Perlis	(PL)	Chuping	1997 ó 2007
2	Kedah	(KD)	Alor Setar ^a	1997 ó 2007
3	Pulau	(PP)	Bayan Lepas	1997 ó 2007
	Pinang			
4	Perak	(PR)	Ipoh	1997 ó 2007
5	Selangor	(SL)	Petaling Jaya	1997 ó 2007
6	Kuala	(KL)	Parlimen ^b	1997 ó 2007
	Lumpur			
7	Negeri	(NS)	Hospital	1997 ó 2007
	Sembilan		Seremban ^c	
8	Melaka	(ML)	Melaka	1997 ó 2007
9	Johor	(JH)	Senai	1997 ó 2007
10	Pahang	(PH)	Kuantan	1997 ó 2007
11	Terengganu	(TR)	Kuala	1997 ó 2007
	00		Terengganu	
			Airport	
12	Kelantan	(KN)	Kota Bharu	1997 ó 2007

Weather data (state-day and therefore state-month) are missing for period: ^a19-26 Dec 2005; ^b1-3 Aug 2004; ^c 1 Jun-15 Oct 2000, 16 May 2001-5Jun 2001, 28 Nov 2003-2 Dec 2003, 4-26 Jan 2004, 6 Sep 2004-1 Oct 2004, 22 Oct 2004-30 Apr 2005, 10-13 May 2005,18,31 Jul 2005, 1 Aug 2005-3 Dec 2005, 1-31 Jul 2006.

used in previous work in road safety modeling literature [6]-[8].

Another climate factor considered was the number of rainy days (in days) for a particular month. The number of rainy days per month had been considered in previous studies of its relationship with road accident crash [7], [8]. Variation in the number of rainy days could be associated with frequent expose of rain to road user [21]. Hence the number of rainy days was also used in this study. The data were also collected from the Malaysian Meteorological Department (MMD) submitted by the same 12 selected weather stations for rainfall amount data.

Another precipitation factor was the spell effects. The dry spell effect took place when a consecutive series of days without rainfall was broken by the first rain after that period [8]. This study used the spell period that referred to the period of first rain occured since the last rain in a month that may take few days or few weeks as determined by the rainfall recorded at 12 selected weather stations as in Table 1. The spell durations of gap between rain and norain were broken down into the following category: (i) 1-7 days; (ii) 8-14 days; (iii) 15-21 days; (iv) 22-28 days and (v) more than 28 days category. Then, the frequency of dry spell for each spell period was obtained for the particular month. If the highest frequency with the highest total number of no-rain day for the particular month fell within the specified spell interval, then the dummy assigned was equal to 1 and the other spell interval dummy would be 0. Note that the dummy for each spell period was mutually exclusive. This dummy was then interacted with the precipitation (rainfall) variable and the interaction term was included as an independent variable. These variables were created to examine what was the effect of this month precipitation with different spell period on this month crash. Thus, the accident counts were regressed with a list of interaction variables between precipitation (rainfall) and dry spell dummy.

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TABLE II DESCRIPTIVE STATISTICS								
Variable	Unit	Obs	Mean	S.D	Min	Max		
Acc	Road accidents crash	1584	1804.96	1709.65	54	8946		
Veh	Total number of registered vehicle	1584	4831.42	4765.75	136	27034		
A_rain	Monthly Rainfall (mm)	1584	206.12	150.31	0.2	1471.10		
Rainy_D	Monthly number of rainy days	1584	15.42	5.51	1	30		
Prec_ds1-7	Interaction between rainfall and dry spell period of 1 6 7 days	1584	190.47	161.48	0	1471.10		
Prec_ds8-14	Interaction between rainfall and dry spell period of 8 6 14 days	1584	13.30	47.54	0	461		
Prec_ds15-21	Interaction between rainfall and dry spell period of 15 6 21 days	1584	2.05	16.27	0	400.4		
Prec_ds22-28	Interaction between rainfall and dry spell period of 22 6 28 days	1584	0.09	1.55	0	35.9		
Prec_ds>28	Interaction between rainfall and dry spell period of > 28 days	1584	0.28	6.61	0	180.9		

TABLE III						
CODDEL ATION MATDIX						

	CORRELATION MATRIX										
	ARain	RainyD	Time	Spell_1-7	Spell_8-14	Spell_15-21	Spell_22-28	Spell>28			
ARain	1										
RainyD	0.6527	1									
Time	0.0548	0.0459	1								
Prec_ds1-7	0.9509^{a}	0.6761	0.0446	1							
Prec_ds8-14	-0.0428	-0.1667	0.0251	-0.3301	1						
Prec_ds15-21	-0.0624	-0.1748	0.0155	-0.1483	-0.0352	1					
Prec_ds22-28	-0.0655	-0.1237	0.0445	-0.0652	-0.0155	-0.0069	1				
Prec_ds>28	-0.0140	-0.0157	-0.0727	-0.0499	-0.0118	-0.0053	-0.0023	1			

^aCorrelation value greater than 0.7. Model in Table 5 was estimated without rainfall amount to cater for multicollinearity. It was found that excluding this variable significantly affect other variables coefficient.

Missing observations for rainfall amount and dry spell were calculated by linear interpolation as suggested by previous study [5]. Extrapolations were only done for short period of missing value by averaging the observations over preceding and posterior year.

In addition, the independent variables also included a vector of dummy variables for all state (less one) representing fixed effects for each state and month dummy. The log of the total number of registered vehicle was incorporated in the model as an offset variable. The õoffsetö term referred to the amount of exposure for a given observation [7]. The risk of accident is not equal for each state. For instance, state with larger vehicle population size will experience more accident than the state with less vehicle size. The different level of risk exposure can be normalized by creating a rate [22]. The rate can be included in the model by introducing the logged form of measure of risk exposure as an offset variable. Hence, the logarithm number of registered vehicle was chosen as the offset variable in this study. The coefficient of independent variables will be interpreted as effects on rates rather than count.

V. RESULTS AND DISCUSSIONS

Table 2 presents the summary statistics for all variables included in the study. Table 3 presents the pairwise correlation coefficients for the main variables used in this analysis. The highest correlation was 0.9509 for rainfall amount and interaction effect for 1 ó 7 days dry spell period

and rainfall. The model in Table 4 was estimated without rainfall variable to cater for multicollinearity. The second highest of correlation was 0.654 for rainfall amount and number of rainy days. Table 4 presents the results for negative binomial FE model specification. Both conditional and unconditional model were then estimated and compared. The specification was explored by including all explanatory variables in a linear form of the exponential function. The interpretation of the effect from exponential transformation used in panel count model (to ensure nonnegativity) is not as simple as in linear model. In $E[y_{it}|\mathbf{x}_{it}] = \exp(\mathbf{x}_{it}'\beta)$ and case, exponential each effects are as variableøs marginal follows; $\frac{\partial E[y_{it} | \mathbf{x}_{it}]}{\partial \mathbf{x}_{it}} = \exp(\mathbf{x}_{it}' \boldsymbol{\beta}) \times \boldsymbol{\beta}_{j} = E[y_{it} | \mathbf{x}_{it}] \times \boldsymbol{\beta}_{j} \quad [12] \text{ which}$ implies that a unit change in the j^{th} variable leads to a multiplicative change in $E[y_{it}|\mathbf{x}_{it}]$ of β_i . The coefficients

represent the effect of independent variables on the log of the mean of dependent variable which can be interpreted as percentage changes in the expected count or rate for 1 unit increase in the independent variable.

The increase in the number of rainy days is predicted to result in higher accident rate. The adverse effects are estimated to be 1, which is the number of increase of rainy days in a month associated with 0.3 percent increase in the monthly accident rate. This result is in accordance with the

	Dependent variable: Road accidents										
		Unconditional Fixed Effects Negative Binomial Model					Conditional Fixed Effects Negative Binomial Model (HHG)				
	Model 1		Model 2		Model 3		Model 4				
	Coef.	Z-stat	Coef.	Z-stat	Coef.	Z-stat	Coef.	Z-stat			
RainyD Time	0.0035 ^{**} 0.0020 ^{**}	4.18 25.04	0.0032 ^{**} 0.0020 ^{**}	3.99 25.12	0.0032 ^{**} 0.0021 ^{**}	4.17 29.33	0.0031 ^{**} 0.0021 ^{**}	4.04 29.42			
Precipitation (mm)x (Dry spell period 1 ó 7 days dummy)	0.0001**	3.37	0.0001**	3.27	0.0001**	3.06	0.0001**	2.99			
Precipitation (mm)x (Dry spell period 8 6 14 days dummy)	0.0002^{**}	3.24	0.0002**	3.09	0.0002**	3.76	0.0002**	3.66			
Precipitation (mm)x (Dry spell period 15 ó 21 days dummy)	0.0324	1.69	-		0.0002	1.07	-				
Precipitation (mm)x (Dry spell period 22 ó 28 days dummy)	0.0014	0.69	-		0.0017	0.91	-				
Precipitation (mm)x (Dry spell period > 28 days dummy)	-0.0013**	-2.66	-0.0013**	-2.67	-0.0015**	-2.56	-0.0015**	-2.57			
State fixed effects	**		**								
Constant	1.7886	101.74	1.8011	103.16	0.6406	16.17	0.6419	16.22			
N	15	1584		1584		1584		1584			
Group (number of states)	1			12		12		12			
Log likelihood	-10,0	-10,031.89		-10,033.56		-9,894.86		-9,895.79			

TABLE IV

Models 1 and 2 include state and month fixed effects. Models 3 and 4 include month fixed effects.

Significant at 0.05 level; ** Significant at 0.01 level.

findings on the traffic accident study done by Fridstorm [6].

The time trend factor is also estimated in the model. This variable is used as a proxy to describe the technological change that may also reflect the increase in the population volume and the development of road network over the time that captures the effects of these exogenous time variables [5], [23]. The time variable coefficient in both conditional and unconditional FE Negative Binomial model shows a positive and significant coefficient indicating an upward trend in the road accident rate in Malaysia.

For more effect on weather condition, this study used two other weather variables to examine their effect on accident count; the rainfall and dry spell effect which were described by the interaction between rainfall amount (in millimeter) and dry spell period. The results follow the expected pattern. The estimated effects from the model imply that, over the course of a month, the monthly accident rate is estimated to increase by 0.01% and 0.02% if the average monthly rainfall with shorter dry spell period of 1 to 7 days, and 8 to 14 days respectively increases by 1 millimeter. It is also interesting to see the effect is negative for interaction between monthly rainfall amounts with longer spell period. The effect is estimated to be one millimeter increase in monthly rainfall with longer spell period of more than 28 days which is associated with 0.015% decrease in the monthly accident rate. In other words, the effect of rainfall in shorter spell period presents greater risk in accident count. While the risk is lessening with the rainfall in the month of longer spell period. This concludes that precipitation in a form of rainfall; dry spell and number of rainy days are significant road safety hazards in Malaysia. Several interpretations are possible. A straightforward explanation for the positive effect would be the wet condition with shorter dry spell effect experienced in a month. The surface of road might be slippery during the rainy month with shorter spell period that might affect the safety effect thus increase the risk of accident. This is in agreement with the findings obtained in the research done by Fridstorm [6]. Other possible explanation could be due to accumulation of engine oil and gasoline on the road [7]. When the rain falls for the first time, the oil and dust that mixed with water may produce a thin liquid film on the road surface which creates slick condition known as viscous hydroplaning [7],[24]. This may cause the vehicle to lose contact with the road surface and they tend to skid. However, if the rain has fallen heavily after a certain spell period, the oil may have been washed of the road and the effect of viscous hydroplaning is lessening [7]. This may decrease the risk of accident occurrence. Another possible explanation is driven by a particular state of the country that has unique pattern of seasonal rainfall occurring regularly in particular months at different states in Malaysia. As Malaysia climate is a tropical rainforest country coupled with local topography feature, it is not surprising to see the negative effects coefficient for this variable if the same model is estimated for every subset of the sample for 12 states in Peninsular Malaysia.

VI. POLICY LESSONS

As for now, Malaysia does not have a nationwide programme to comprehensively cater for weather problems in the context of road transportation. Hence, several policy lessons and efforts that can be drawn from the results of this study should be observed in all areas in the country. The risk of road accident occurrence significantly increased among drivers during the rainy month with shorter spell Proceedings of the World Congress on Engineering 2012 Vol I WCE 2012, July 4 - 6, 2012, London, U.K.

period of gap between rain and no-rain due to wet condition. Thus appropriate policy response would be to warn drivers using electronic and non-electronic signs on the roadside. According to Malaysian Institute of Road Safety Research (MIIROS), the non electronic road signs as implemented in other countries have already been used in Malaysia for many years to warn drivers about hazards they might encounter ahead of their journey [21]. Though some of the direct and indirect road signs available are meant for weather-related warning, not hazardous all are implemented on the roadside nationwide for all 12 states in Peninsular Malaysia. An effort of Intelligent Transport System (ITS) application such as electronic sign of variable message signs (VMS) [25] has also been up and running to help alert the driver on the adverse weather condition in the selected highly populated and developed urbanized area. This effort should also be implemented covering the rural area nationwide such as east coast that experiences high amount of rainfall. The implementation of these signs might be made more effective if they emphasize on the hazard of wet condition more frequent after a dry spell period of 1 to 7 days and 8 to 14 days rather than providing the same warning for all rainy events. The most dangerous and hazardous road due to wet condition identified at particular state should be marked as targeted warning in reducing the crashes. This requires collaborations with Malaysian Meteorological Department (MMD) in providing information on the weather condition and other partnerships such as Malaysian Highway Authority (LLM) and MIROS. Educational measures through dissemination of information on real time weather updates and driving skills for adverse weather condition are also important for driversøprecautions and awareness.

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